Supplementary Material

The Effect of Human Autonomy and Robot Work Pace on Perceived Workload in Human-Robot Collaborative Assembly Work

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Statistical tests

Table 1 - Table 6 show the outcomes of the Wilcoxon Signed Ranks Tests. The comparison Fast Robot Lead (FRL) with Human Lead (HL) tests the effect of human autonomy. The comparison FRL with Slow Robot Lead (SRL) tests the effect of robot work pace.

Table 1: Test Statistics Cognitive

	SRL-HL	FRL-HL	FRL-SRL
Z	-2,054[a]	-3,519[a]	-2,230[a]
Asymp. Sig. (2-tailed)	,040	<,001	,026
a. Based on negative ranks.			

Table 2: Test Statistics Physical

	SRL-HL	FRL-HL	FRL-SRL
Z	-1,610[a]	-2,546[a]	-,526[a]
Asymp. Sig. (2-tailed)	,107	,011	,599
a. Based on negative ranks.			

Table 3: Test Statistics Temporal

	SRL-HL	FRL-HL	FRL-SRL
Z	-,026[a]	-2,676[b]	-2,667[b]
Asymp. Sig. (2-tailed)	,979	,007	,008
a. Based on positive ranks.			
b. Based on negative ranks.			

Table 4: Test Statistics Effort

	SRL-HL	FRL-HL	FRL-SRL
Z	-,189[a]	-2,170[a]	-1,261[a]
Asymp. Sig. (2-tailed)	,850	,030	,207
a. Based on negative ranks.			

Table 5: Test Statistics Frustration

	SRL-HL	FRL-HL	FRL-SRL
Z	-,281[a]	-2,149[a]	-1,015[a]
Asymp. Sig. (2-tailed)	,778	,032	,310
a. Based on negative ranks.			

Table 6: Test Statistics Performance

	SRL-HL	FRL-HL	FRL-SRL
Z	-1,107[a]	-1,114[a]	-,120[a]
Asymp. Sig. (2-tailed)	,268	,265	,905
a. Based on positive ranks.			