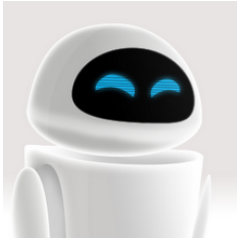
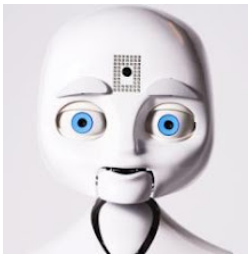
Appendix 2. Description of SAR (focus group booklet)

Name Producer, (country)	Picture	Type of robot	Description
RobuLAB 10 Robosoft (France)		Machine-like	- Mobile platform - Embarks a group of sensors and cameras for autonomous navigation, - Input devices include speech control and touch-screen - System programmed to provide cognitive and social support through different applications (e.g., task reminder, cognitive training, navigation support, communication tools)
Kompaï Robosoft (France)		Mechanical human-like	- Same configuration as Robulab but with a different appearance (human-like head)
Pearl Carnegie Mellon University (USA)		Mechanical human-like	- Mobile platform - Designed to help older adults to navigate through a nursing facility - Provides advice, cognitive support, functional assistance
Mamoru University of Tokyo Toyota and Fujitsu (Japan)		Mechanical human-like	- Desktop elder-care robot - Designed to provide prompts and reminders (e.g., Item location, medication intake) - Uses a wide-angle camera to detect objects regardless of rotation, scale, or lighting conditions
EVE PIXAR, DISNEY studios (USA)		Mechanical human-like	- Animated female robot from the film Wall-E - Mix between human and machine features - Emotions represented through facial expressions and voice

Name Producer, (country)	Picture	Type of robot	Description
Telenoïd Osaka University, ATR (Japan)		Human-like	- Humanoid robot with minimal human appearance - High quality silicon human mimicking skin - Designed to be a communication device, with applications in remote work, education, and elderly care - Allows distant transmission of "human presence" (e.g., voice, face and head movements)
Nexi MIT Media Lab (USA)		Human-like	- Mobile manipulator robot capable of social expression - Applications for personal robots and human-robot teamwork - Hands for manipulating objects, eyes (video cameras), ears (an array of microphones), 3-D infrared camera and laser rangefinder to support real-time tracking of objects, people, voices, and indoor navigation
Geminoid F Osaka University, ATR (Japan)		Android	- Android that works as a substitute for clerks, when typical responses are required - Consists in three elements: a robot, a central controlling server, and a teleoperation interface
iCat Philips Electronics (The Netherlands)		Mechanical animal-like	- Cat-like appearance - Face expressing emotions - Aimed at functional assistance -Strongly relates to social interaction
Paro Intelligent Systems Research Institute (ISRI) (Japan)		Animal-like	- Soft seal robot developed for robot therapy in older adults with cognitive impairment, and other populations with disabilities - Programmable behavior as well as a set of sensors (touch sensor, infrared sensor, stereoscopic vision and hearing). - Actuators include eyelids, upper body motors, front paw and hind limb motors.