

Supplementary Material

1 THREE PCA METHODS IMPLEMENTED WITH NUMPY IN PYTHON

We can obtain the PCA components (U), the eigenvectors (V), and the eigenvalues ($\Lambda = S^2$) of a $m \times n$ matrix X via the following three methods with the NumPy linear algebra. Let consider X defined as:

```
import numpy as np
np.random.seed(50)
n = 3; m = 10
X = np.random.random((m, n))
```

Singular Value Decomposition (SVD). The SVD of $X = USV^T$ can be conducted as follows:

```
U, S, VT = np.linalg.svd(X, full_matrices=False)
V = VT.T
eigenVectors = V
eigenValues = S**2
```

Eigendecomposition. The eigenvalue decomposition (EVD) of the covariance matrix $C = X^T X = V \Lambda V^T$ and the least-squares solution (U) to $XV = US$ can be computed as follows:

```
C = np.dot(X.T, X)
eigenValues, eigenVectors = np.linalg.eigh(C)
idx_sort = eigenValues.argsort()[::-1]
eigenValues = eigenValues[idx_sort]
eigenVectors = eigenVectors[:, idx_sort]
S = eigenValues**0.5
V = eigenVectors
XV = np.dot(X, V)
UT, resid, rank, sv = np.linalg.lstsq(np.diag(S), XV.T, rcond=None)
U = UT.T
```

QR Decomposition. The QR decomposition of $X = QR$ and the SVD of $R^T = \bar{U} \bar{S} \bar{V}^T$ can also be implemented using the NumPy functions, leading to $S = \bar{S}$, $V = \bar{U}$, and $U = Q\bar{V}$:

```
Q, R = np.linalg.qr(X)
U_bar, S_bar, VT_bar = np.linalg.svd(R.T)
V_bar = VT_bar.T
U = np.dot(Q, V_bar)
V = U_bar
S = S_bar
eigenVectors = V
eigenValues = S**2
```

These different methods can sometimes result in a sign difference in one PCA component and its eigenvector compared to each other.