

Analysing head-thorax choreography during free-flights of bumblebees, *bombus terrestris*.

1 SUPPLEMENTARY TABLES AND FIGURES

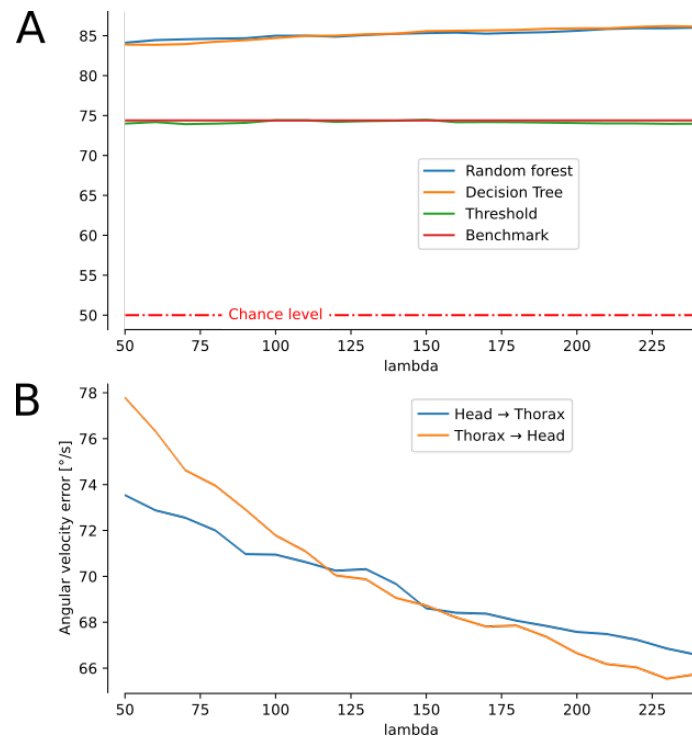


Figure S1. Effect of the smoothing parameter λ on the accuracy of the saccade-intersaccade classifier and angular error of the neural network, respectively. The timecourse of the head and thorax orientation was filtered with a cubic spline with parameter λ before developing the two methods. A) To test for the robustness of the saccade-intersaccade classifier against the smoothing parameters λ , we evaluated the accuracy of the classifier (Thresholding, Decision tree, and Random forest) for λ varying between 50 and 250. We observe a slight increase with decreasing λ , and less variance for the Random forest classifier B) We tested the robustness of the neural network in predicting head's velocity from thorax's velocity (and vice versa) for different λ . We observe a decrease in angular error between network prediction and head angular velocity with increasing λ .

Table S1. Overview of the parameters used for the two methods, classifier and fore-backcasting.

	Parameter	Value/Range
Filtering	λ (smoothing parameter)	150
Classifier	Δt (window size)	$\in \{1, 3, 5, \dots, 53\}$
	D (depth)	$\in [1, 20]$
Fore-backcasting	Δt (window size)	$\in \{1, 3, 5, \dots, 53\}$
	N (number of neurons)	$\in \{1, 2, 4, 8, 16, 32, 64, 128\}$
	λ (regularization term)	0.5
	ϵ (avoid division by zero)	0.1
	τ (temporal-shift)	$\in \{-25, -23, \dots, 23, 25\} \cup \{0\}$

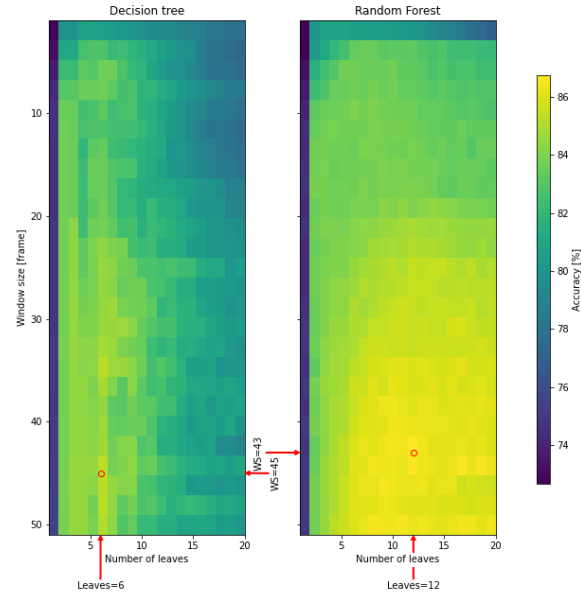


Figure S2. Accuracy of the Decision tree and Random forest on the validation datasets for different parameters. The windows size Δt was varied in 1, 3, 5, ..., 53 (x-axis), and the depth of the trees D was varied from 1 to 20 (y-axis). Color represent the accuracy on the validation datasets. The red dot indicate the chosen parameter Δt and D for evaluating the model on the test set.