



# Individual Variation in Temporal Dynamics of Post-release Habitat Selection

Simona Picardi<sup>1,2\*</sup>, Nathan Ranc<sup>3</sup>, Brian J. Smith<sup>1,4</sup>, Peter S. Coates<sup>5</sup>, Steven R. Mathews<sup>5</sup> and David K. Dahlgren<sup>1</sup>

<sup>1</sup> Department of Wildland Resources, Utah State University, Logan, UT, United States, <sup>2</sup> Jack H. Berryman Institute, Utah State University, Logan, UT, United States, <sup>3</sup> Center for Integrated Spatial Research, Environmental Studies Department, University of California, Santa Cruz, Santa Cruz, CA, United States, <sup>4</sup> Ecology Center, Utah State University, Logan, UT, United States, <sup>5</sup> U.S. Geological Survey, Western Ecological Research Center, Dixon Field Station, Dixon, CA, United States

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> \*Correspondence: Simona Picardi simona.picardi@usu.edu

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Translocated animals undergo a phase of behavioral adjustment after being released in a novel environment, initially prioritizing exploration and gradually shifting toward resource exploitation. This transition has been termed post-release behavioral modification. Post-release behavioral modification may also manifest as changes in habitat selection through time, and these temporal dynamics may differ between individuals. We aimed to evaluate how post-release behavioral modification is reflected in temporal dynamics of habitat selection and its variability across individuals using a population of translocated female greater sage-grouse as a case study. Sage-grouse were translocated from Wyoming to North Dakota (USA) during the summers of 2018-2020. We analyzed individual habitat selection as a function of sagebrush cover, herbaceous cover, slope, and distance to roads. Herbaceous cover is a key foraging resource for sage-grouse during summer; thus, we expected a shift from exploration to exploitation to manifest as temporally-varying selection for herbaceous cover. For each individual sage-grouse (N = 26), we tested two competing models: a null model with no time-dependence and a model with time-dependent selection for herbaceous cover. We performed model selection at the individual level using an information-theoretic approach. Time-dependence was supported for five individuals, unsupported for seven, and the two models were indistinguishable based on AIC<sub>c</sub> for the remaining fourteen. We found no association between the top-ranked model and individual reproductive status (brood-rearing or not). We showed that temporal dynamics of post-release habitat selection may emerge in some individuals but not in others, and that failing to account for time-dependence may hinder the detection of steady-state habitat selection patterns. These findings demonstrate the need to consider both temporal dynamics and individual variability in habitat selection when conducting post-release monitoring to inform translocation protocols.

Keywords: resource selection, post-release behavioral modification, individual behavior, individual heterogeneity, translocation, greater sage-grouse

# INTRODUCTION

Most animals select for areas that have been previously visited - their familiar space (Wolf et al., 2009; Avgar et al., 2015; Ranc et al., 2020b). This behavioral process has been shown to provide benefits in terms of resource acquisition (Merkle et al., 2014; Ranc et al., 2021) and reduction of predation risk (Gehr et al., 2020). Translocated animals experience an unfamiliar landscape and therefore often undergo a phase of behavioral adjustment after being released in a novel environment (Berger-Tal and Saltz, 2014; Berger-Tal et al., 2020). During this initial phase, translocated individuals learn information about their new environment and may undertake exploratory movements to build a cognitive map of their surroundings (Berger-Tal and Saltz, 2014). Exploration and resource exploitation are at opposite ends of a behavioral gradient that translocated animals exhibit after release (Berger-Tal et al., 2014). Initially, the trade-off leans toward exploration; then, individuals gradually shift their behavior toward exploitation as they become more familiar with their new environmental context - a process that underlies the emergence of stable home ranges (Ranc et al., 2020a). The transition from exploration to exploitation has been termed post-release behavioral modification (PRBM; Berger-Tal and Saltz, 2014).

Post-release monitoring is important for understanding the success of translocation efforts (Bubac et al., 2019). Typically, the goal of monitoring is to assess individual behavior (such as habitat selection) and vital rates (such as survival or reproductive success) post-translocation (Armstrong and Seddon, 2008; Parker et al., 2013). This information helps to fine-tune translocation protocols within the context of an adaptive management framework, for example, by adjusting the choice of release sites or individuals to translocate (Letty et al., 2007; Osborne and Seddon, 2012).

When monitoring post-release behavior – for example, using telemetry devices fitted on translocated individuals – not accounting for PRBM may bias or confound estimates of habitat selection. An animal's habitat selection changes depending on current motivation and internal state (Nathan et al., 2008; Roever et al., 2014), and motivation is fundamentally different when animals are focused on exploration vs. exploitation. This issue is frequently ignored, or sometimes dealt with by discarding data for the first few days or weeks after release (e.g., Mondal et al., 2013; Werdel et al., 2021), during which behavior is assumed not to be representative of a steady state. In the latter case, the choice of the temporal cut-off to use is arbitrary and relies on the assumption that every individual in the population behaves similarly.

Evidence is increasing that individual behavioral responses to stimuli are idiosyncratic in wild populations (Cote et al., 2010; Bonnot et al., 2015; Merrick and Koprowski, 2017). Individuals with different temperaments may react differently when exposed to novel environments (Germano et al., 2017; de Azevedo and Young, 2021). Individual differences may manifest, for example, in the degree of risk-aversion exhibited during exploration (Montagne, 2016), stress-tolerance (May et al., 2016), or dispersal distances (Richardson et al., 2017); but individuals may also differ in the time it takes for them to move along the exploration/exploitation continuum, or in how their habitat selection changes as their internal state shifts.

Explicitly modeling temporal dynamics and accounting for individual heterogeneity should improve the quality of our inference on habitat selection in translocated populations. Incorporating these elements into the analysis of postrelease behavior may improve translocation protocols aimed at maximizing the probability of successful population restoration. In this study, we evaluated individual variation in temporal dynamics of habitat selection after release in a novel environment using a population of greater sage-grouse (*Centrocercus urophasianus*; hereafter, sage-grouse) translocated from Wyoming, USA, to North Dakota, USA, as a case study.

Translocation has been used as a management tool to augment declining sage-grouse populations across their range (Reese and Connelly, 1997; Baxter et al., 2008, 2013; Duvuvuei et al., 2017). Sage-grouse populations have undergone severe declines since the 1960s (Garton et al., 2011; Coates et al., 2021). In North Dakota, the extant sage-grouse population experienced a sharp decline due to habitat loss and a West Nile Virus (Flavivirus spp.) disease outbreak in the mid-2000s (Garton et al., 2011). Augmentation of this declining population was initiated in 2017 with translocation of individuals from a large, stable population in central Wyoming (Coates et al., 2021). Using data from this translocation, our objectives were to evaluate: (1) whether sage-grouse exhibited individual variation in habitat selection during PRBM, and (2) whether including time-dependent terms improved inference on individual habitat selection.

# MATERIALS AND METHODS

We captured female sage-grouse during summers 2018-2020 from the source population near Stewart Creek, WY at night using spotlights and dip-nets cast from all-terrain vehicles (Wakkinen et al., 1992). The captured individuals included brood-rearing females (captured in June with their young chicks, 7-40 days old; Meyerpeter et al., 2021) and non-brood-rearing females (captured in June without a brood). All individuals were translocated within 24 h post-capture (Lazenby et al., 2021). We measured and weighed individuals and equipped them with rump-mounted Global Positioning System (GPS) Platform Transmitter Terminal (PTT) ARGOS-enabled tracking devices (23 g, GeoTrak©, Inc.) scheduled to acquire six locations a day at irregular intervals. In the case of brood-rearing females, we also captured their chicks, weighed them, and equipped them with Very High Frequency (VHF) suture-style tracking devices (1.1 g, Holohil Systems©, Ltd.). During transport, females and their chicks were kept separated to prevent injury but within audio-visual contact in specialized transport boxes (Meyerpeter et al., 2021). We translocated captured sage-grouse to Bowman County, ND and released them using a soft-release method, i.e., allowing for an acclimation period ( $\sim$ 30–45 min) in a release pen. The source habitat in WY is part of the Wyoming Basin Sage-Grouse Management Zone, characterized by large, uninterrupted

sagebrush (*Artemisia spp.*) steppe (Lazenby et al., 2021). The sage-grouse population in this area is one of the largest remaining across the species range (Coates et al., 2021). The release area in ND is part of the Great Plains Sage-Grouse Management Zone which is a grass-dominated landscape interspersed with small sagebrush patches (Lazenby et al., 2021). The sage-grouse population in this area constitutes a small remnant fragment at the northeastern periphery of the species range (Coates et al., 2021).

To quantify temporal dynamics in post-release habitat selection, we analyzed GPS-tracking data for female sage-grouse in the 60 d following their translocation to ND. Model predictors included percent sagebrush cover, percent herbaceous cover, slope, and distance to roads; based on previous literature, these variables are known to be important predictors of sage-grouse habitat selection across their range (Connelly et al., 2011; Dinkins et al., 2014) as well as specifically in the translocated ND population (Lazenby et al., 2021). We obtained percent sagebrush and herbaceous cover data at a 30-m resolution from the National Land Cover Database (NLCD 2016; https://www.mrlc.gov/national-land-cover-database-nlcd-2016). We obtained data on slope at a 30-m resolution from Landfire (https://landfire.gov/). We obtained data on roads from the USGS National Transportation Dataset (USGS 2014), including paved roads, highways, and interstates as well as gravel or dirt roads. We rasterized the roads vector layer to a 30-m resolution and calculated distance of each pixel to the nearest road. We log-transformed distance values to allow for a spatial decay in the behavioral response to roads. We scaled and centered all predictors before including them in the model.

We used integrated step selection analysis (iSSA; Avgar et al., 2016) to quantify habitat selection. Because iSSA requires data at regular time intervals, we scanned our dataset to find the most frequent regular interval between locations (i.e., 11 h) and only retained 11-h steps. An iSSA simultaneously models the habitat selection process [denoted as w(x)] and the movement process [denoted as  $\phi(x)$ ] underlying an animal's space use (Avgar et al., 2016). For all models, we modeled step lengths as realizations of a gamma distribution, which accounts for the heavy-tailed distribution of movement distances typically observed in empirical data; and turning angles as realizations of a von Mises distribution, which accounts for directional persistence. Both distributions were initially parameterized with population-level data (gamma with shape = 0.72 and scale = 725.04; von Mises with mean = 0.00 and concentration = 0.10). Accordingly, our movement process model was  $\phi(x) =$  $\exp[\alpha_1 l + \alpha_2 \log(l) + \alpha_3 \cos(\theta)]$ , where l is the step length and  $\theta$  is the turning angle. We sampled 100 available steps for each observed step using these population-level gamma and von Mises distributions.

We tested our hypothesis of temporal modification of habitat selection by fitting competing models for the habitat selection process. We used model selection to evaluate whether individuals exhibited temporal modification of habitat selection by fitting an interaction between a focal predictor and the natural logarithm of time, measured as days since translocation. Herbaceous cover is the primary driver of habitat selection for translocated sage-grouse during summer (our period of investigation) in our study area. In summer, sage-grouse - and especially females with broods - rely on grasses, forbs, and the associated insect community as the main food sources for themselves and their young (Connelly et al., 2000, 2011). In the grassdominated ecosystem of North Dakota, where sagebrush cover is sparser than in most other areas of the species range, the availability of herbaceous cover plays a more important role than sagebrush cover at fine scales (Kaczor et al., 2011). As such, if time-dependent habitat selection were to emerge in our study system, we would expect it to manifest primarily in the response to herbaceous cover. We expected individual responses to potentially vary through time for resources but not for conditions, thus we chose not to test for time-dependent responses to slope. Sagebrush is not a limiting resource for sage-grouse during summer as much as during winter, when alternative food sources are not available (Connelly et al., 2000; Swanson et al., 2013); although it remains an important broadscale predictor of sage-grouse habitat selection, we did not expect it to be the main driver of habitat selection at fine scales during summer. Selection for roads may potentially vary through time after release, but we did not expect individual responses to switch from selection to avoidance or vice-versa; thus, we did not test for time-dependent responses to roads.

Our two competing models of the habitat selection process for each individual were:

• Model T0 did not include any time-dependence in the habitat selection process (null model);

$$w(x) = \exp\left(\beta_1 S_x + \beta_2 H_x + \beta_3 L_x + \beta_4 R_x\right)$$

• Model T1 included time-dependent selection for herbaceous cover and no time-dependence for selection for the other predictors;

$$w(x) = \exp[\beta_1 S_x + \beta_2 H_x + \beta_3 L_x + \beta_4 R_x + \beta_5 H_x \log(T_x)]$$

In the equations above, w(x) denotes the habitat selection function,  $S_x$ ,  $H_x$ ,  $L_x$ , and  $R_x$  denote percent sagebrush cover, percent herbaceous cover, slope, and distance to roads at location x, respectively, and  $T_x$  denotes days since translocation when the GPS location x was taken. Because the total number of parameters in the more complex model (T1) was 8, we only fit the models to individuals with at least 80 observed steps (using a minimum of 10 steps per estimated parameter as a rule of thumb to ensure adequate power). We ranked models for each individual based on Akaike's Information Criterion corrected for small sample sizes (AIC<sub>c</sub>). We grouped individuals based on their top-ranked model: group T0 had model T0 as top-ranked  $(\Delta AIC_c > 2 \text{ for model T1})$  and group T1 had model T1 as topranked ( $\Delta AIC_c > 2$  for model T0). Individuals for which the second-ranked model had  $\Delta AIC_c \leq 2$  were not attributed to either group. For individuals in groups T0 and T1, we evaluated mean parameter estimates at the individual level under both

<b>TABLE 1</b>   Summary of model ranking based on AIC <sub>c</sub> for translocated female
sage-grouse in North Dakota in 2018–2020.

	T0 top-ranked	T1 top-ranked	Indistinguishable
Brood-rearing females	6	5	8
Non-brood-rearing females	1	0	6

Model T0 is a null model including sagebrush cover, herbaceous cover, slope, and distance to roads as predictors and no time-dependence terms. Model T1 includes the four predictor and also a time-dependent term for selection for herbaceous cover. Both models were fit to a set of 26 translocated sage-grouse, of which 19 were broodrearing females and seven were non-brood-rearing females. A model was considered top-ranked when  $\Delta AlC_c > 2$  for the second-ranked model. If  $\Delta AlC_c \leq 2$ , the models were indistinguishable.

models. We used standard errors to calculate 95% confidence intervals around mean parameter estimates using a large-sample approximation. Then, for all individuals, we calculated mean predictions of log Relative Selection Strength (log-RSS; Avgar et al., 2017) for herbaceous cover under model T1 as a function of days since translocation. Log-RSS is the natural logarithm of the ratio of the exponential habitat selection function for two sets of predictor values (Avgar et al., 2017); we chose to evaluate selection for the 3rd quartile of herbaceous cover (52%) vs. the mean value across the dataset (46%), but because our model is linear on the log-scale, these patterns would hold for any values of herbaceous cover separated by 6%.

# RESULTS

The final dataset included 26 translocated sage-grouse. Of these, 19 were brood-rearing females and seven were nonbrood-rearing females. Time-dependence in habitat selection was supported for five individuals, while the absence of time-dependence (i.e., null model T0) was best supported for seven individuals; the two models were indistinguishable based on AIC<sub>c</sub> for the remaining 14 individuals (Table 1; see Supplementary Material for individual model selection tables). We found no evidence of association between the occurrence of time-dependence in habitat selection and individual status (brood-rearing or non-brood-rearing; Fisher's exact test; p > p0.05). Out of seven individuals in group T0, model T0 indicated selection for herbaceous cover in four, avoidance in one, and no significant response for two; we detected no significant responses to the other three predictors (Figure 1). Out of five individuals in group T1, model T1 indicated initial selection for herbaceous cover with a shift toward avoidance for two and initial avoidance with a shift toward selection for three (Figures 1, 2); we also detected selection and avoidance of steeper slopes for one individual, respectively (Figure 1). When fitting model T0 to group T1, the sign of the response to herbaceous cover was reversed with respect to model T1 for four out of five individuals (Figure 1). When fitting model T1 to group T0, the mean parameter estimate was estimated accurately albeit with greater uncertainty (Figure 1). For individuals that exhibited time-dependent habitat selection for herbaceous cover, the switch

from selection to avoidance (or vice-versa) occurred within 1–3 days after release (**Figure 2**).

# DISCUSSION

Using data for translocated greater sage-grouse, we showed that temporal dynamics of post-release habitat selection may manifest in some individuals but not in others, and that not accounting for time-dependence may hinder correct interpretation of habitat selection patterns. These findings showcase the need to consider both temporal dynamics and individual variability in habitat selection when conducting post-release monitoring of translocated animals.

Five translocated sage-grouse (all brood-rearing females) exhibited a temporally varying response to herbaceous cover within the first 60 days post-release. For two of these individuals, selection for higher herbaceous cover was strongest immediately after release and gradually decreased through time, switching to avoidance (Figure 2). The remaining three individuals initially exhibited avoidance of higher herbaceous cover and then switched to selection (Figure 2). A switch from avoidance to selection for herbaceous cover during post-release behavioral modification is what we expected based on theory: translocated animals should initially prioritize exploration of their new surroundings and move through the landscape regardless of the distribution of key resources, and they should gradually shift to resource exploitation once acclimated (Berger-Tal and Saltz, 2014). The trend we observed is also compatible with natal habitat preference induction, where translocated individuals select for habitat that is most similar to their natal habitat before they gradually adjust to the new conditions (Davis and Stamps, 2004). Indeed, sage-grouse habitat at the source population consisted of contiguous sagebrush steppe, where sagebrush was the dominant vegetation type and herbaceous cover was sparse; sage-grouse were then released in a grass-dominated system. Some translocated individuals may have responded to this change by initially avoiding unfamiliar features and then gradually selecting for higher herbaceous cover as they became familiar with the release area. Individuals who initially selected and then started avoiding higher herbaceous cover may have done so because their brood fledged or died within the 60 days after release, which relaxed their dependence on herbaceous cover for foraging.

Seven sage-grouse (six brood-rearing and one non-broodrearing female) did not exhibit time-dependent habitat selection for herbaceous cover; most of them selected for herbaceous cover, one avoided it, but their behavior did not change through time (**Figures 1**, **2**). Although our sample size did not give us statistical power to make definitive claims, we did not find a link between temporal dynamics of habitat selection exhibited by translocated individuals and their status (brood-rearing or non-brood-rearing). Rather, the individual variation we observed in temporal dynamics of post-release habitat selection may be a result of intrinsic characteristics of each individual (e.g., personality; Carere and Eens, 2005).



**FIGURE 1** Mean parameter estimates and 95% confidence intervals for nabitat selection of translocated sage-grouse in North Dakota, 2018–2020, in the 60 days after release. Model T0 includes no time-dependent terms, while model T1 includes time-dependent selection for herbaceous cover, a key foraging resource during summer. Both models were fitted to each individual separately and ranked based on AICc, then individuals were grouped based on their top-ranked model. Individuals in group T0 had model T0 as top-ranked ( $\Delta AIC_c > 2$  for model T1), while individuals in group T1 had model T1 as top-ranked ( $\Delta AIC_c > 2$  for model T0). Parameter values express log-Relative Selection Strength (sensu Avgar et al., 2017), i.e., the selection coefficient for a 1-unit increase in the covariate value.



**FIGURE 2** | Predictions of log-Relative Selection Strength from model T1 in response to herbaceous cover as a log-function of time (days since translocation) in translocated female sage-grouse in North Dakota, 2018–2020, in the 60 days after release. Predictions were evaluated using individual-level parameter estimates. Group T1 included individuals for which the model with time-dependent selection for herbaceous cover was top-ranked ( $\Delta AIC_c > 2$  for model T0), group T0 included individuals for which the model without time-dependence was top-ranked ( $\Delta AIC_c > 2$  for model T1), and the "no group" label denotes individuals for which the two models were indistinguishable ( $\Delta AIC_c \le 2$  for the second-ranked model).

Our results demonstrate that model formulation affects inference, reinforcing that failure to consider temporal dynamics and individual variation may substantially change the conclusions drawn about habitat selection in translocated populations. When using a model without time-dependence terms to predict habitat selection for individuals that exhibit time-dependence, our estimates of steady-state habitat selection were altered. In some cases, opposite trends canceled out - e.g., initial avoidance neutralized steady-state selection, resulting in a non-significant pattern (Figure 1). In others, the initial response outweighed the steady-state behavior resulting in a reversed pattern (Figure 1). These findings demonstrate that failing to account for time-dependent habitat selection in individuals that exhibit it is likely to lead us to inaccurate conclusions. By contrast, including time-dependence terms still resulted in accurate estimates for steady-state selection for herbaceous cover in individuals that did not exhibit temporal dynamics, albeit with greater uncertainty (Figure 1). All in all, these results show that the inclusion of time-dependence terms, at least during data exploration, allows for detection of temporal dynamics where they occur without compromising accuracy in estimating steady-state habitat selection.

The time-dependent model was indistinguishable from the null for the remaining 14 individuals based on  $AIC_c$ . This is likely because the response to herbaceous cover in these individuals was too weak to outweigh the penalty from an additional model parameter. Nonetheless, our results show that fitting a model that includes time-dependent terms to individuals that do not exhibit time-dependent habitat selection increases uncertainty but does not affect the accuracy of steady-state estimates. Thus, one possible approach is to begin data exploration by fitting time-dependence models to all individuals and then further refine individual parameter estimates by removing unnecessary time-dependence terms on an individual basis.

Responses to other predictors in our models were weak, with a few exceptions: one individual selected to be near roads, four individuals selected for high sagebrush cover, one avoided steeper slopes and three selected for them (Figure 1). One possible explanation for selection for roads is that linear features may provide conspicuous landmarks for some individuals and help with orientation in an unknown landscape. Landmarks play an important role in spatial orientation and learning in vertebrates (Bingman and Cheng, 2005; Lewis et al., 2020), and previous studies have shown that, in some bird species, translocated individuals are able to use anthropogenic landmarks (including roads, e.g., Bélisle and St. Clair, 2002) to navigate across the landscape. Selection for high sagebrush cover and avoidance of steep slopes are typical habitat selection responses observed in sage-grouse across their range (Connelly et al., 2000, 2011). Selection for steeper slopes in some individuals was surprising, although less so when contextualized within the study area, where even the steepest slopes are only moderately steep. The fact that, overall, responses of translocated sage-grouse to key predictors were weak could be attributed to several reasons. One possible explanation is that some translocated sage-grouse were unable to behave adaptively in an environment so different from their natal habitat, at least during the first 2 months after release, and thus behaved similarly to random walkers using resources in close proportion to their availability. Another possible reason for the lack of strong responses, which is not necessarily in contradiction with the first one, is that habitat selection in translocated sage-grouse may be stronger at coarser orders of selection, but at finer scales, once settled within a general area, sage-grouse behavior becomes closer to a random walk. Finally, the release environment was rather homogeneous, and the lack of landscape heterogeneity may have resulted in weak responses.

In our study system, sage-grouse exhibited weak to moderate habitat selection responses, but accounting for temporal dynamics may be even more important in highly heterogeneous landscapes. When evaluating time-dependent habitat selection, it is beneficial to decide a priori on ecologically meaningful model formulations based on existing knowledge of the study species and system, especially when data availability constraints limit the complexity of the models. In this study, the size of our individual datasets did not allow us to fit time-dependent terms for multiple predictors at a time. Higher-frequency, temporally regular location data should allow researchers to include several time-dependent terms within one model and test alternative hypotheses regarding time-dependent habitat selection for multiple resources. Potentially, individuals might display time-dependent selection for different predictors and reveal new, intriguing patterns of individual heterogeneity.

Temporal dynamics in habitat selection provide insight into how long it takes for translocated individuals to reach steadystate behavior in the release area. Results from this study illustrate that (1) the time-to-steady-state may differ between individuals, (2) the acclimation phase may be shorter (or longer) than expected *a priori*, and (3) some individuals may not display any time-dependent responses. In principle, the time it takes for individuals to reach steady-state habitat selection may also differ between predictors. Often, researchers deal with postrelease behavioral modification by discarding data from the first few days or weeks after release. Explicitly modeling temporal dynamics of individual behavior may inform the choice of cutoff to use when discarding data or entirely remove the need for it, because the model structure already accommodates the potential for behavioral adjustments.

Time-dependence in habitat selection could be implemented using different formulations. A shortcoming of the formulation we used is that the natural logarithm of time since release constrains the shape of the temporal-dependence curve, making it range from 0 on the first day post-release to 1 at the maximum number of days post-release (in our case, 60). At the same time, a benefit of this formulation is that our temporal dependence curve is still a linear curve that can be fit using standard software. More complex, non-linear formulation of time-dependence curves would allow for explicit estimation of individual time-dependence parameters over time-series of varying lengths. However, this implementation would require custom non-linear models, which are sometimes beyond the reach of non-statisticians; to overcome this barrier, some quantitative biologists may prefer a Bayesian solution. Custom form models would also be data-hungry due to their nonlinear nature.

Temporal dynamics and individual variation in habitat selection are often viewed as a nuisance to remove; instead, we

argue that they should be treated as processes on which to make inference. Our results showed that including time-dependent responses and evaluating habitat selection at the individual level may provide a detailed picture of how translocated populations respond to their new environment. Our study indicates benefits of approaches that explicitly incorporate temporal dynamics and accommodate individual variation when examining postrelease habitat selection of translocated animals. Accounting for individual differences in habitat selection and post-release behavioral modification should ultimately improve populationlevel inference as well, by ensuring, first, that population-level analyses focus on steady-state behavior only, and second, that opposite patterns of selection between groups of individuals do not cancel each other out when analyzed collectively. Formal tests of a priori hypotheses on post-release behavior via appropriately designed experimental translocation have the potential to provide valuable information for adaptive management (Armstrong and Seddon, 2008). These benefits warrant high interest in future research aimed to test hypotheses on drivers of individual heterogeneity in post-release behavior.

# DATA AVAILABILITY STATEMENT

The data are available on Dryad, https://doi.org/10. 5061/dryad.44j0zpcf5. The code is available on GitHub, https://github.com/picardis/picardi-et-al\_2021\_sage-grouse\_ frontiers-in-conservation.

# **ETHICS STATEMENT**

The animal study was reviewed and approved by Utah State University Institutional Animal Care and Use Committee.

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# **AUTHOR CONTRIBUTIONS**

SP and NR conceived the idea. SP, NR, and BS conducted the analysis. DD and PC supervised the project and provided the data. SM curated the field data. SP wrote the initial manuscript draft. All authors contributed to manuscript editing and revision.

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# SUPPLEMENTARY MATERIAL

The Supplementary Material for this article can be found online at: https://www.frontiersin.org/articles/10.3389/fcosc. 2021.703906/full#supplementary-material

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