



Recent Developments in Fast Kurtosis Imaging

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Hansen B and Jespersen SN (2017) Recent Developments in Fast Kurtosis Imaging. Front. Phys. 5:40. doi: 10.3389/fphy.2017.00040 Diffusion kurtosis imaging (DKI) is an extension of the popular diffusion tensor imaging (DTI) technique. DKI takes into account leading deviations from Gaussian diffusion stemming from a number of effects related to the microarchitecture and compartmentalization in biological tissues. DKI therefore offers increased sensitivity to subtle microstructural alterations over conventional diffusion imaging such as DTI, as has been demonstrated in numerous reports. For this reason, interest in routine clinical application of DKI is growing rapidly. In an effort to facilitate more widespread use of DKI, recent work by our group has focused on developing experimentally fast and robust estimates of DKI metrics. A significant increase in speed is made possible by a reduction in data demand achieved through rigorous analysis of the relation between the DKI signal and the kurtosis tensor based metrics. The fast DKI methods therefore need only 13 or 19 images for DKI parameter estimation compared to more than 60 for the most modest DKI protocols applied today. Closed form solutions also ensure rapid calculation of most DKI metrics. Some parameters can even be reconstructed in real time, which may be valuable in the clinic. The fast techniques are based on conventional diffusion sequences and are therefore easily implemented on almost any clinical system, in contrast to a range of other recently proposed advanced diffusion techniques. In addition to its general applicability, this also ensures that any acceleration achieved in conventional DKI through sequence or hardware optimization will also translate directly to fast DKI acquisitions. In this review, we recapitulate the theoretical basis for the fast kurtosis techniques and their relation to conventional DKI. We then discuss the currently available variants of the fast kurtosis techniques, their strengths and weaknesses, as well as their respective realms of application. These range from whole body applications to methods mostly suited for spinal cord or peripheral nerve, and analysis specific to brain white matter. Having covered these technical aspects, we proceed to review the fast kurtosis literature including validation studies, organ specific optimization studies and results from clinical applications.

Keywords: MRI, diffusion, kurtosis, higher-order tensors, orientational sampling, WMTI

INTRODUCTION

Microstructural sensitivity in MRI is most often obtained by sensitizing the signal to the diffusion of water. In combination with modeling, such data can vield specific microstructural markers, but the data required to support such modeling is often prohibitive in particular in a clinical context. A less data intense strategy to obtain microstructural sensitivity in diffusion MRI (dMRI) is the diffusion kurtosis imaging (DKI) framework [1] which quantifies the leading deviation from Gaussian diffusion in each image point. This deviation arises from the influence of tissue microstructure on the water diffusion profile and is easily visualized by plotting the log signal as function of *b*-value. This is done in Figure 1 using data acquired along one direction in a white matter region in normal human brain (circles). Here the familiar log-linear signal decay is seen up to $b \approx 1 \text{ ms/}\mu\text{m}^2$, below which a diffusion tensor fit (solid red line) approximates the signal very well. Extrapolation of this fit beyond $b \approx 1$ $ms/\mu m^2$ (dashed red line), however, clearly does not match the observed signal. Conversely, the DKI fit (solid green line) is seen to approximate the measured signal over the entire bvalue range shown, although it will diverge at sufficiently high b-values. DKI thus allows quantification of the deviation from log-linear signal decay caused by tissue microarchitecture and compartmentalization. This deviation thereby indirectly provides information about these tissue properties.

Compared to most other advanced dMRI techniques, DKI is easily implemented. For this reason, and because of its increased sensitivity to tissue microstructure compared to diffusion tensor imaging (DTI), DKI has grown to be a popular dMRI method. Nevertheless, DKI is not experimentally inexpensive, as typical protocols consist of a few unweighted images for normalization and two 30-direction shells at two non-zero b-values (typically 1.0 $ms/\mu m^2$ and 2.0–2.5 $ms/\mu m^2$) thus totaling 60–70 images [2]. This is current standard, although more data intense protocols are not uncommon [3]. While most DKI protocols are too lengthy for everyday clinical use, high quality data can be acquired in a time frame considered reasonable for many clinical and preclinical studies. Even so, the time required for postprocessing of DKI is significant, and both acquisition time and data processing time limit its clinical application, especially in patients with time sensitive ailments (e.g., stroke or trauma), or patients with difficulties lying still, e.g., children.

The DKI method yields a wealth of parameters that can be mapped on a voxel by voxel basis. Several of these DKI metrics have been shown to detect subtle changes in brain tissue structure. To briefly summarize, studies have shown DKI to have potential in diagnostics of a number of diseases such as stroke [4, 5], Alzheimer's disease [6], multiple sclerosis [7], gliomas [8, 9], and head trauma [10–12] (see also the review of this area in Ostergaard et al. [13]). DKI is not only of clinical interest but is also a valuable tool in basic neuroscience, and the method has for example been employed in studies of natural alteration of brain microstructure e.g., in the context of development and aging [14, 15].

DKI is sensitive to microstructure generally, and therefore in brain it can be used to study both gray matter (GM) and white



FIGURE 1 Diffusion MRI data (circles) from a white matter region in human brain acquired along one direction over the *b*-value range from 0 to 3 ms/ μ m². Fits obtained with DTI (solid red line, $b = 0-1 \text{ ms}/\mu m^2$) and DKI (green line, all *b*-values) are shown. The signal deviation from the DTI signal prediction is illustrated by extrapolating the DTI fit (the dashed red line) into the DKI regime ($b > 1 \text{ ms}/\mu m^2$). Conversely, the DKI fit is seen to approximate the signal very well.

matter (WM). However, in WM, DKI can be combined with modeling to obtain some of the biophysical specificity of more advanced dMRI modeling frameworks. One important example of this is the white matter tract integrity (WMTI) technique [2] which on the basis of a DKI data set provides detailed information about microstructure of highly aligned fiber bundles, such as intra- and extra-axonal diffusivities, axonal water fraction (AWF), and the tortuosity, α , of the extra-axonal space.

Like DKI, WMTI has also been used to study the brain in a wide range of contexts: normal brain development and aging [16, 17], Alzheimer's disease [18, 19], mild head trauma [20], multiple sclerosis [21], autism [22], and stroke [4]. Validation studies comparing WMTI indices to histology and electron microscopy [23–26] have largely confirmed the ability of WMTI to detect microstructural changes in WM. While other frameworks for DKI-based estimation of tissue model parameters have been proposed [27, 28], a recent comparative study showed WMTI to be the most widely applicable [27].

While WMTI was developed specifically for analysis of WM, the DKI framework itself is almost without assumptions and its applications are therefore not limited to brain imaging. Consequently, interest in DKI for body imaging is growing [29] with demonstrated applications in imaging of liver [30, 31], kidney [32, 33], and prostate [34–36].

This short survey of the DKI literature documents the high potential of DKI as a method to obtain sensitive markers suitable for basic research (e.g., for the study of brain plasticity), diagnostics and treatment monitoring. However, widespread clinical application of DKI and WMTI has yet to emerge. Two major limitations that are most likely responsible for DKI not being routinely used in the clinic have already been identified: acquisition time and post-processing time. Lowering both of these barriers has therefore been an important goal as methods for fast DKI and WMTI would not only increase the clinical applicability of DKI and WMTI, but also make possible more widespread, routine exploration of DKI metrics by allowing inclusion of DKI, at little additional cost, as a component of any protocol for imaging of the brain or other organs. Furthermore, such methods would facilitate high resolution preclinical studies for characterization of animal models of disease or for validation studies.

Here we review recent developments enabling fast kurtosis imaging based on small data sets (13 or 19 images) and with near-instant post-processing [37-42]. The review is structured such that first the theoretical foundation of DKI and WMTI is recapitulated briefly. For a more in-depth review of conventional DKI we refer to Jensen and Helpern [43], Wu and Cheung [44]. On this basis we then introduce the rapidly obtainable DKI metrics used in fast kurtosis and discuss their relation to conventional DKI definitions. Since a few variants of fast kurtosis have been introduced we cover all of them and their various area of application. Having covered the methodological background we review the literature of fast DKI application studies and discuss current efforts for method refinement and potential future applications. All data shown was reused from the cited papers from our group. The presented non-human data was acquired at 9.4T (except from Figure 8, acquired at 16.4T) while human brain data was acquired in normal volunteers at 3T. We refer to the original publications for details on data acquisition and analysis.

DIFFUSION KURTOSIS IMAGING VARIANTS

Conventional DKI

The standard expression for the DKI signal is [1]:

$$\log S(b, \hat{n})/S_0 = -bn_i n_j D_{ij} + \frac{1}{6} b^2 \overline{D}^2 n_i n_j n_k n_l W_{ijkl} + O(b^3)$$

= $-bD(\hat{n}) + \frac{1}{6} b^2 \overline{D}^2 W(\hat{n}) + O(b^3)$ (2.1.1)
= $-bD(\hat{n}) + \frac{1}{6} b^2 D(\hat{n})^2 K(\hat{n}) + O(b^3)$

Here $S_0 = S(b = 0)$ is the unweighted signal used for normalization and *b* is the diffusion weighting applied along a direction $\hat{n} = (n_x, n_y, n_z)$. The normalized signal is denoted *S* from here on. Throughout, subscripts label Cartesian components (e.g., i = x,y,z) and summation over repeated indices is assumed. D is the diffusion tensor [45], and the kurtosis tensor W and the apparent excess kurtosis $K(\hat{n})$ are defined as in Jensen et al. [1]. Overbar denotes mean value over diffusion directions, i.e., $\overline{D} = \text{Tr}(D)/3$ is the mean diffusivity (Tr is the trace).

In the DKI analysis, the tensors D and W are estimated by fitting Equation (2.1.1) to data acquired as described above

(with *b*-values sufficiently low so that the $O(b^3)$ terms can be neglected and satisfying $b \leq 3/D(\hat{n})K(\hat{n})$ [46] so that the DKI signal model Equation (2.1.1) does not diverge). From these tensors, a wealth of metrics is available. For the diffusion tensor, the most important metrics are \overline{D} , fractional anisotropy (FA) and radial and axial diffusivities. To obtain these, the diffusion tensor is diagonalized to yield three pairs of eigenvectors \hat{v}_i and eigenvalues λ_i (i = 1, 2, 3). The eigenvalues (diffusivities) are sorted by size so that the primary eigenvector (\hat{v}_1) indicates the direction of highest diffusivity (λ_1), etc. The axial diffusivity is then $D_{||} = \lambda_1$ and radial diffusivity is $D_{\perp} = (\lambda_2 + \lambda_3)/2$. The anisotropy of D is summarized by the FA due to Basser and Pierpaoli [47]:

$$FA = \sqrt{\frac{3}{2}} \frac{\sqrt{\left(\lambda_1 - \overline{D}\right)^2 + \left(\lambda_2 - \overline{D}\right)^2 + \left(\lambda_3 - \overline{D}\right)^2}}{\sqrt{\lambda_1^2 + \lambda_2^2 + \lambda_3^2}}$$
$$= \sqrt{\frac{3}{2}} \frac{\|D - \overline{D}I\|}{\|D\|}, \qquad (2.1.2)$$

where the double vertical bars $\|\cdot\|$ denote the Frobenius norm and \mathbb{I} is the rank-2 identity matrix. From the kurtosis tensor, summary metrics can also be derived, the most important parameter being the mean kurtosis (MK, \overline{K}) [1]:

$$\overline{K} = \frac{1}{4\pi} \int_{S_2} K(\hat{n}) d\hat{n} = \frac{1}{4\pi} \int_{S_2} W(\hat{n}) \frac{\overline{D}^2}{D(\hat{n})^2} d\hat{n} \qquad (2.1.3)$$

Other meaningful parameters can be extracted from the kurtosis tensor. Similar to the directional diffusivities, the kurtoses observed along (||) and orthogonal (\perp) to the primary eigenvector direction have been introduced [3, 43, 48, 49]:

$$K_{||} = K(\hat{v}_1)$$

$$K_{\perp} \equiv \frac{1}{2\pi} \int_{S_2} d\hat{n} \,\delta(\hat{n} \cdot \hat{v}_1) K(\hat{n})$$

$$= \frac{1}{2\pi} \int_0^{2\pi} d\varphi K(\hat{v}_2 \cos \varphi + \hat{v}_3 \sin \varphi)$$
(2.1.4)

where S₂ is the sphere. These are known respectively as (conventional) radial and axial kurtosis. Note that in contrast to their diffusion tensor counterparts, they are not strictly rotationally invariant. The reason for this behavior is that in orthogonal fiber bundle crossings the diffusion eigenvalues may be degenerate (i.e., for such a 3D fiber arrangement there is no primary fiber direction and the diffusion tensor is isotropic) while the apparent kurtosis can differ among the fiber directions due to microstructural differences in the bundles [42]. Consequently, in this thought-experiment noise will determine which eigenvector will be deemed the primary direction thus causing the estimated directional kurtosis values to vary between measurements. While such fiber configurations are most likely rare this property should nevertheless be kept in mind when employing directional kurtosis metrics. Other definitions have been proposed and the fast DKI counterparts rely on other definitions than those presented in Equations (2.1.3) and (2.1.4). These will be discussed in Sections "Fast estimation of mean diffusivity and mean kurtosis", "Fast kurtosis estimation with increased experimental robustness" and, "Axisymmetric DKI".

In addition to the raw tensor metrics, D and W can also provide metrics of white matter tract integrity (WMTI) based on modeling described in Fieremans et al. [2]. The assumptions and modeling choices that make estimation of these WM metrics possible are covered in the following section.

White Matter Tract Integrity from DKI

WMTI uses the estimated tensors D and W to estimate the (MR detectable) axonal water fraction, and several compartmental diffusivities. This analysis exploits the relation between the tensors D and W and the WMTI parameters found by the cumulant expansion of the expression for the dMRI signal from a two-compartment system consisting of the extra-axonal space (EAS) and an intra-axonal space (IAS) described as sticks with an effective radius of zero, which is valid for the gradients employed in acquiring typical clinical diffusion data. Diffusion in both the EAS and the IAS is approximated with anisotropic Gaussian diffusion, and because of the latter, the analysis is restricted to areas of highly aligned WM. Water exchange is assumed to be negligible over the experimental time window, and myelin water is assumed not to contribute because of its large value of TE/T2. A limited amount of dispersion of axons within the WM bundle does not violate the Gaussian intra-axonal assumption, but implies that the intra-axonal diffusion tensor has three nonvanishing eigenvalues [2]. With these assumptions, the signal expression for this two-compartment system becomes:

$$S(b, \hat{n}) = f \exp(-b\hat{n}^T D_a \hat{n}) + (1 - f) \exp(-b\hat{n}^T D_e \hat{n})$$
(2.2.1)

where f is the axonal water fraction (AWF from here on), D_a and D_e are the diffusion tensors belonging to the IAS and EAS respectively. The form of these tensors is:

$$D_{a} = \begin{bmatrix} D_{a3} & 0 & 0 \\ 0 & D_{a2} & 0 \\ 0 & 0 & D_{a1} \end{bmatrix}, \qquad D_{e} = \begin{bmatrix} D_{e3} & 0 & 0 \\ 0 & D_{e2} & 0 \\ 0 & 0 & D_{e1} \end{bmatrix} (2.2.2)$$

where subscript numbers label the eigenvalues by magnitude in descending order, implying that here the primary direction is \hat{z} . From the cumulant expansion of this model, the measured diffusion and kurtosis tensors D and W can be expressed in terms of the model parameters. In this manner, the otherwise unspecific DKI parameters yield approximations for specific biophysical parameters: the AWF, IAS diffusivity ($D_a = Tr(D_a)$), parallel and radial EAS diffusivities ($D_{e,\parallel} = D_{e,1}$ and $D_{e,\perp} = (D_{e2} + D_{e3})/2$), and the EAS tortuosity ($\alpha = D_{e,\parallel}/D_{e,\perp}$). Notably, the estimates are only approximate, as the diffusion and kurtosis tensors in principle do not supply sufficient information to estimate all diffusivities and the axonal volume fraction because of the confounding factors of axonal dispersion [50]. Additionally, kurtosis based estimation of compartmental diffusivities yields two solutions. This arises because the kurtosis is related to the variance ("mean of square minus square of mean") over diffusivities [43] causing the square root to enter the analysis.



For this reason, WMTI furthermore relies on the assumption that intra-axonal diffusivity D_{a1} is smaller than extra-axonal diffusivity D_{e1} as argued in Fieremans et al. [2]. Figure 2 shows a schematic of this representation of a WM bundle and the biophysical properties that may be estimated from WMTI analysis. For further details on derivations and modeling assumptions, the reader is referred to the original WMTI papers [2, 51].

Fast Estimation of Mean Diffusivity and Mean Kurtosis

The ability to rapidly estimate mean diffusivity and mean kurtosis from only 13 images was presented in Hansen et al. [39, 40]. In order to achieve this, a mean kurtosis definition was introduced (\overline{W}) which differs from the definition in Equation (2.1.3), namely:

$$\overline{W} = \frac{1}{4\pi} \int_{S_2} d\hat{n} W(\hat{n})$$

$$= \frac{1}{5} \text{Tr}(W) \qquad (2.3.1)$$

$$= \frac{1}{5} (W_{xxxx} + W_{yyyy} + W_{zzzz} + 2W_{xxyy} + 2W_{xxzz} + 2W_{yyzz})$$

This definition differs from the conventional MK definition in Equation (2.1.3) in that it is based on the spherical average of the apparent tensor kurtosis $W(\hat{n})$:

$$W(\hat{n}) = K(\hat{n}) \frac{D(\hat{n})^2}{\overline{D}^2},$$
 (2.3.2)

instead of $K(\hat{n})$. For this reason we also refer to \overline{W} as the mean of the kurtosis tensor (MKT). This definition is compactly written



as one fifth of the trace (Tr) of the kurtosis tensor W. The factor of one fifth stems from the spherical average [52]:

$$\frac{1}{4\pi} \int_{S_2} d\hat{n} \, n_i n_j n_k n_l = \frac{1}{15} (\delta_{ij} \delta_{kl} + \delta_{ik} \delta_{jl} + \delta_{il} \delta_{jk}) \equiv \frac{1}{5} \mathbb{I}_{ijkl}$$
(2.3.3)

where \mathbb{I} is the fully symmetric isotropic rank 4 tensor [53]. Hence, \overline{W} represents the isotropic part of the kurtosis tensor [39]. The advantage of this mean kurtosis definition is apparent from the last line in Equation (2.3.1) which states that \overline{W} is proportional to a linear combination of six tensor elements, and this linear combination can be obtained from measurements without fitting to the data. For the measurements, the "pure" tensor elements (W_{iiii}) can be probed directly, whereas the mixed elements $(W_{iiij}, i \neq j)$ requires the combination of two directions for each to cancel cross terms, see Hansen et al. [39] for details. Therefore, a total of nine directions is needed to calculate \overline{W} . These directions are illustrated in Figure 3, where it is readily seen that this encoding scheme does not sample the sphere very efficiently; the high estimation quality obtained with this scheme rests entirely on the relations introduced shortly. The directions are also listed in Table 1 which also defines the notation used in the following equations.

For data acquired along these directions (i = 1,2,3) the following holds [39]:

$$\begin{aligned} &\frac{1}{15} \left(\sum_{i=1}^{3} \log S(b, \hat{n}^{(i)}) + 2 \sum_{i=1}^{3} \log S(b, \hat{n}^{(i+)}) + 2 \sum_{i=1}^{3} \log S(b, \hat{n}^{(i-)}) \right) \\ &= -b\overline{D} + \frac{1}{6} b^2 \overline{D}^2 \overline{W} \end{aligned} \tag{2.3.4}$$

With an independent estimate of \overline{D} , Equation (2.3.4) allows estimation of \overline{W} without data fitting, thus eliminating both

TABLE 1 The nine directions in the compact notation (leftmost column) used in the manuscript and stated as normalized vectors.

Direction	x-component	y-component	z-component
n ⁽¹⁾	1	0	0
$\hat{n}^{(1+)}$	0	$1/\sqrt{2}$	$1/\sqrt{2}$
$\hat{n}^{(1-)}$	0	$1/\sqrt{2}$	$-1/\sqrt{2}$
n ⁽²⁾	0	1	0
n ⁽²⁺⁾	$1/\sqrt{2}$	0	$1/\sqrt{2}$
<i>î</i> (2–)	$1/\sqrt{2}$	0	$-1/\sqrt{2}$
n ⁽³⁾	0	0	1
n ⁽³⁺⁾	$1/\sqrt{2}$	$1/\sqrt{2}$	0
<i>î</i> (3–)	$1/\sqrt{2}$	$-1/\sqrt{2}$	0

the time consuming post-processing and the pitfalls associated with it [54–56]. The mean diffusivity \overline{D} can be estimated from data acquired along three orthogonal directions at a single bvalue (and b = 0), but is improved by taking into account the kurtosis term in the analysis [57], which can be done if the 3 directions are acquired also at a second higher b-value shell. In this manner a closed form solution for \overline{D} [58] is obtained taking into account the directional kurtosis for high fidelity estimation [57]. The strategy proposed in Hansen et al. [39] thus implements the estimation of \overline{D} based on data acquired at an intermediate *b*-value along the three main directions, $\hat{n}^{(1)}$, $\hat{n}^{(2)}$ and $\hat{n}^{(3)}$, which are already contained in the nine directions in Table 1. Thus, the "1-3-9 approach" for fast estimation of \overline{D} and \overline{W} is to acquire one b=0 image, 3 images at $b_1 = 1.0$ ms/ μ m² along the x,y,z directions ($\hat{n}^{(i)}$, i = 1,2,3), and nine images acquired at $b_2 = 2.5 \text{ ms}/\mu\text{m}^2$ along the directions listed in Table 1.

The scaling factor of $D(\hat{n})^2/\overline{D}^2$ in Equation (2.3.2) generally depends on direction and as such will affect the spherical average so that $\overline{K} = \overline{W}$ only for isotropic systems. From the definitions therefore, \overline{K} and \overline{W} are expected to deviate the most in highly anisotropic tissue. It is natural therefore to evaluate whether the rapidly obtainable tensor based mean kurtosis (\overline{W}) offers similar contrast to the conventional MK. This is illustrated in Figure 4 which shows typical DTI and DKI parameters mapped in fixed rat brain at an in-plane resolution of 100 µm x 100 µm to allow contrast comparison in specific brain regions such as the subfields of the hippocampus. Overall, the parameters can be seen to provide vastly different contrast, except for \overline{K} and \overline{W} which are seen to be almost indistinguishable although a few blank pixels are seen in the \overline{W} map due to noise (see also comments on preprocessing below). The level of agreement between \overline{K} and \overline{W} presented in **Figure 4** has been quantified (linear correlations) exceed 0.9 in most cases but will depend on the data foundation) and demonstrated in both fixed and live brain in a number of studies [59-61] and also in fixed kidney [62]. In the diseased brain, the 1-3-9 method has been validated in an animal model of stroke [63, 64] and was found to yield diffusion and kurtosis lesions in good agreement with conventional DKI. Similarly, strong correlations between the diffusion-kurtosis stroke lesion mismatch obtained from 1-3-9 and conventional DKI was shown



FIGURE 4 | Example maps of typical DTI and DKI parameters in fixed rat brain. The two mean kurtosis definitions are shown and seen to provide similar contrast. Figure adapted from Hansen and Jespersen [37] with permission.



[63]. Additionally, \overline{W} was found to be the most sensitive parameter for revealing acute ischemic injury in an analysis also including axial and radial kurtosis [64]. This is important because \overline{W} can be reconstructed almost instantly once acquisition is complete, making this most sensitive parameter immediately available e.g., for clinical decision making. In the same study [64], the contrast to noise ratio (CNR) of \overline{W} estimated from fast DKI was found to be significantly higher than for conventional DKI. Importantly, the fast DKI CNR efficiency (CNR per unit scan time) was shown to be twice that of conventional DKI. The authors conclude that the fast kurtosis method captures heterogeneous diffusion and kurtosis lesions in acute ischemic

stroke, and thus is suitable for translational applications. The rapidly obtainable \overline{W} is therefore by now established as a biomarker offering the same information as the conventional \overline{K} in normal tissue and stroked brain. Strictly speaking, the methods await similar validation in other pathologies but \overline{W} is now recognized as an independent marker and not merely a rapidly obtainable surrogate for \overline{K} . Recent clinical studies have employed the 1-3-9 method for glioma grading [65], for studying the effect of crack cocaine addiction [66], and in mild traumatic brain injury patients [12]. Preliminary results in stroke patients was presented in Li et al. [67] obtained using a combination of the 1-3-9 technique and the simultaneous multislice imaging (SMS) technique [68].

Fast Kurtosis Estimation with Increased Experimental Robustness

The 1-3-9 method relies heavily on the nine direction scheme being precisely met. Encoding may, however, be imperfect causing deviations from the encoding scheme required for Equation (2.3.4) to hold. Such encoding errors may have a number of causes such as gradient non-linearities, eddy currents, contributions from gradient cross-terms and coregistration due to subject movement. While not explored initially, subsequent analysis of these effects showed the 1-3-9 scheme to be quite sensitive to severe encoding deviations. A simple remedy was demonstrated in Hansen et al. [41] where the 1-3-9 scheme was extended so that all of the nine directions in **Table 1** are acquired at the two non-zero *b*-values, b_1 and b_2 . This so-called 1-9-9 version of fast DKI achieves increased experimental robustness by forming Equation (2.3.4) at two distinct *b*-values, b_1 and b_2 :

$$A_{1} \equiv \frac{1}{15} \left(\sum_{i=1}^{3} \log S(b_{1}, \hat{n}^{(i)}) + 2 \sum_{i=1}^{3} \log S(b_{1}, \hat{n}^{(i+)}) + 2 \sum_{i=1}^{3} \log S(b_{1}, \hat{n}^{(i-)}) \right) = -b_{1}\overline{D} + \frac{1}{6} b_{1}^{2}\overline{D}^{2}\overline{W}$$

$$A_{2} \equiv \frac{1}{15} \left(\sum_{i=1}^{3} \log S(b_{2}, \hat{n}^{(i)}) + 2 \sum_{i=1}^{3} \log S(b_{2}, \hat{n}^{(i+)}) + 2 \sum_{i=1}^{3} \log S(b_{2}, \hat{n}^{(i-)}) \right) = -b_{2}\overline{D} + \frac{1}{6} b_{2}^{2}\overline{D}^{2}\overline{W} \quad (2.3.5)$$

producing a set of two equations with two unknowns, \overline{D} and \overline{W} , for which closed for solutions are readily obtained so that the 1-9-9 estimate for \overline{D} is:

$$\overline{D}_{199} = \left(b_1^2 A_2 - b_2^2 A_1\right) / \left(b_1 b_2^2 - b_1^2 b_2\right)$$
(2.3.6)

and for \overline{W} :

$$\overline{W}_{199} = 6b_1b_2\left(A_1b_2 - A_2b_1\right)\left(b_1 - b_2\right) / \left(A_1b_2^2 - A_2b_1^2\right)^2$$
(2.3.7)

For precise encoding, i.e., when effective *b*-values are constant among directions on each encoding shell and encoding directions follow the prescribed directions, the 1-3-9 and 1-9-9 schemes

produce very similar appearing maps as shown in Figure 5, where estimates of \overline{D} and \overline{W} from a full DKI data set can be compared to estimates obtained with 1-3-9 and 1-9-9 in the same normal human brain. The effect of the 1-9-9 method's increased data foundation is apparent when comparing the schemes' robustness to experimental imperfections: numerical analysis reveals that the 1-9-9 scheme has precision similar to nonlinear least squares (NLS) fitting to large data sets, vastly outperforming the 1-3-9 scheme [41]. The effects of imperfect encoding was also addressed in a series of simulations showing that the 1-9-9 estimation quality (evaluated as the %-error compared to the ground truth value) remains below 10% even when b-values vary by as much as 10% among directions and the withinshell encoding directions deviate up to 10° from the prescribed directions. For the 1-3-9 scheme, these conditions cause estimates to deviate on the order of 15%. These results indicate that the 1-9-9 method is robust to most real-world encoding imperfections and even to effects from subject movement, where coregistration will cause b-matrices to require rotation. Nevertheless, a post-hoc correction scheme was also proposed and demonstrated to repair effects of even severe encoding faults [41].

Recommended *b*-values for both the 1-3-9 and 1-9-9 schemes are $b_1 \approx 1 \text{ ms}/\mu\text{m}^2$ and $b_2 \approx 2.5 \text{ ms}/\mu\text{m}^2$, but the experimental and numerical *b*-value optimization in Hansen et al. [41] showed that precise matching to these two *b*-values was not critical. These values are achievable on most if not all gradient systems while also keeping the echo time sufficiently short to retain good SNR even at b_2 . The analysis in Hansen et al. [41] showed that the recommended *b*-values are (perhaps surprisingly) suitable for both *in vivo* (37°C) and *ex vivo* (21°C) work. These *b*-values were used with the 1-9-9 method in an animal model of stroke, where a relaxation-based normalization method was introduced to enable automatic segmentation of kurtosis lesions [69]. Nevertheless, optimal *b*-values may vary between brain regions, and example data sets for region specific *b*-value optimization are freely available as described in Hansen et al. [70].

Increasing the number of data points from 13 (1-3-9) to 19 (1-9-9) also makes possible estimation of the full diffusion tensor (with fitting) from which all DTI metrics can then be calculated. As a rapid alternative, FA estimation from 1-9-9 data was also proposed based on the variance (var) of $D(\hat{n})$ over the 9 sampling directions (the expression is exactly FA for complete sampling of the sphere):

$$FA_{199} = \sqrt{\frac{3}{2} \frac{\operatorname{var}(D(\hat{n}))}{\operatorname{var}(D(\hat{n})) + 6/15\overline{D}^2}}$$
(2.3.8)

Here the $D(\hat{n})$ values over the nine directions are calculated using both non-zero *b*-values as in Jensen et al. [58] so that the directional kurtosis is included to improve estimation [57]. FA maps obtained in this manner were found to correlate strongly (average correlation was 0.77 ± 0.04 across three subjects) with ground truth FA from a large data set. Code enabling automatic parameter map calculation from 1-3-9 and 1-9-9 data during image reconstruction on Siemens systems is available as described in Hansen et al. [41]. The data examples shown in **Figures 4**, **5** were produced from non-preprocessed data and so the maps in **Figure 5** illustrate the map quality one might expect to achieve with online parameter calculation. For offline dMRI data preprocessing and analysis (including DKI and WMTI) a number of toolboxes are available e.g., Diffusion Kurtosis Estimator (DKE: http://academicdepartments.musc.edu/cbi/dki/ dke.html), the Dipy library in python [71] (http://nipy.org/ dipy/), MRTrix (http://www.mrtrix.org), some of which also include estimation of \overline{W} and kurtosis fractional anisotropy (KFA, see Equation (2.5.5) and the related text).

Recent work on efficient experimental designs for estimating the isotropic part of higher-order tensors [72], suggests that the 9 directions of the 1-3-9 and 1-9-9 designs can be reduced to 7 for an even more economical version of fast mean kurtosis imaging.

Axisymmetric DKI

As mentioned in the introduction, DKI parameters other than mean kurtosis are available, e.g., the kurtosis along the primary eigenvector (axial kurtosis) and perpendicular to it (radial kurtosis). Furthermore, modeling based WM characterization such as WMTI provides other valuable markers, but requires knowledge of the full diffusion and kurtosis tensors. It is therefore desirable to be able to estimate these valuable markers from fast protocols. Since the number of free parameters in the conventional DKI signal equation amounts to 22 (Equation 2.1.1), the 1-9-9 protocol does not provide enough data points to support estimation of D and W from fitting. For estimation of D and W from reduced data sets (say a 1-9-9 acquisition, but in principle it could be other low angular resolution DKI acquisitions), a substantial reduction of parameters in the DKI signal expression would be needed. An effective strategy to achieve such a reduction was proposed in Hansen et al. [42], and builds on the observation that if the system is assumed to possess axial symmetry, the apparent kurtosis $W(\hat{n})$ can be expressed by only three independent parameters: letting \hat{z} be parallel to the symmetry axis, $W(\hat{n})$ is characterized by \overline{W} , $W_{||} = W(\hat{z})$ (axial kurtosis), and W_{\perp} (radial kurtosis). Stated in terms of the diffusion tensor eigenvectors ($\hat{\nu}_1$, $\hat{\nu}_2$, $\hat{\nu}_3$ in decreasing order of the eigenvalues as above), the tensor-based directional kurtosis parameters are defined to be:

$$W_{\perp} \equiv \frac{1}{2\pi} \int_{S_2} d\hat{n} \,\delta(\hat{n} \cdot \hat{v}_1) W(\hat{n}) = \frac{1}{4} \left(W(\hat{v}_2) + W(\hat{v}_3) + W\left((\hat{v}_2 + \hat{v}_3)/\sqrt{2} \right) + W\left((\hat{v}_2 - \hat{v}_3)/\sqrt{2} \right) \right)$$

$$W_{||} = W(\hat{v}_1)$$
(2.5.1)

Comparing these definitions to the conventional directional kurtosis parameter definitions in Equation (2.1.4) shows $K_{||} = (\overline{D}^2/\lambda_1^2) W_{||}$ so that only for isotropic media $K_{||} = W_{||}$. Rescaling of the axial and radial tensor kurtosis is convenient and causes the axial kurtosis definitions to become identical but radial kurtosis as defined in Equation (2.5.1) is in general different from the convention in Equation (2.1.4), unless there is axial symmetry [42].

The assumption of axial symmetry requires the axis of symmetry to be specified with respect to the lab frame, which adds two angles, resulting in a total of only 5 parameters needed to fully describe an axisymmetric kurtosis tensor. Under axisymmetry, D and W share their symmetry axis so that D only adds two parameters. Finally, signal normalization adds one parameter, producing a total of eight free parameters for axisymmetric DKI [42]. Even in regions where axial symmetry is unlikely to hold in reality, the simplified DKI signal expression thus obtained yields reliable estimates of mean and directional kurtosis and diffusion metrics [42]. Not only does this open the possibility of estimation of all DTI and DKI metrics from small DKI data sets such as those acquired with the 1-9-9 scheme, the axisymmetric DKI framework also allows direct (no fitting) estimation of tensor-based directional kurtosis parameters in regions with a well-defined axis of symmetry (i.e., known pricipal axis) such as large peripheral nerves and spinal cord. This is readily seen in Equation (2.5.1) for $W_{\parallel} =$ $W(\hat{z})$ and from the rightmost expression for W_{\perp} . Software for axisymmetric DKI analysis is freely available on our group homepage: http://cfin.au.dk/cfinmindlab-labs-research-groups/ neurophysics/software.

Fast Estimation of White Matter Biomarkers Using Axisymmetic DKI

Axisymmetric DKI makes it possible to estimate D and W from small data sets. A natural next step is to use this framework to provide a fast variant of the technique for assessment of WM tract integrity metrics (WMTI) proposed in Fieremans et al. [2, 51]. In its original form, WMTI adds an analysis step so that in addition to the data acquisition and data processing related to conventional DKI, WMTI also requires a rather time-consuming pixel-by-pixel estimation procedure including numerical optimization. With the assumption of axial symmetry and fully aligned axons, both the data requirement and computational load can be reduced significantly. This is achieved by establishing closed form solutions for all WMTI parameters based on the axisymmetric DKI parameters directly. In this manner, only one optimization procedure is needed for the WMTI analysis, the initial fitting to Equation (2.1.1) or its axisymmetric counterpart. The expressions for the biophysical parameters that describe the axonal system are obtained from this relationship for 2-compartment Gaussian systems [43]:

$$D(\hat{n}) = f D_a(\hat{n}) + (1 - f) D_e(\hat{n})$$

$$W(\hat{n})\overline{D}^2 = 3f(1 - f) (D_a(\hat{n}) - D_e(\hat{n}))^2 \qquad (2.5.2)$$

When evaluated along the radial and axial directions and with averaging over all directions, these general expressions yield directional diffusivities and kurtoses from which expressions for $AWF = f, D_a, D_{e,\perp}$, and $D_{e,\parallel}$ can be derived [38]:

$$D_{\perp} = (1 - f)D_{e,\perp} \tag{a}$$

$$D_{||} = fD_a + (1 - f)D_{e,||}$$
(b)

$$W_{\perp}\overline{D}^2 = 3f(1-f)D_{e,\perp}^2$$
 (c)

$$W_{||}\overline{D}^2 = 3f(1-f)(D_a - D_{e,||})^2$$
 (d)

$$\overline{WD}^{2} = 3f(1-f) \left[D_{e,\perp}^{2} + \frac{1}{15} (D_{e,\parallel} - D_{a} - D_{e,\perp}) \left(7D_{e,\perp} + 3(D_{e,\parallel} - D_{a}) \right) \right]$$
(e) (2.5.3)

where it was used that $D_{a\perp} = 0$ for parallel sticks. It is readily seen that the left-hand sides of Equation (2.5.3) can be determined using parameters obtained directly from an axially symmetric DKI fit as well as from a general DKI fit.

Of the five equations in Equation (2.5.3), only 4 of the equations are actually independent (i.e., they have only four unknowns due to the assumption of parallel axons with radius zero), so that one equation can be omitted. In Hansen et al. [42] \overline{W} was found to be more robustly estimated from 1-9-9 than $W_{||}$. We therefore advice to omit Equation (2.5.3d) which contains the slightly noisier $W_{||}$. In this way, closed form expressions for the WMTI parameters can be established based on Equations (2.5.3a,b,c,e):

$$f = AWF = \left(1 + 3D_{\perp}^{2} / W_{\perp} \bar{D}^{2}\right)^{-1}$$
(a)

$$D_{e,\perp} = D_{\perp} / (1 - f) \tag{b}$$

$$D_{e,||} = D_{||} - \frac{2}{3} \frac{f}{1-f} \left(D_{\perp} \pm \sqrt{\frac{15(1-f)}{4f}} \bar{D}^2 \bar{W} - 5D_{\perp}^2 \right) \quad (c)$$

$$D_a = D_{||} - \frac{2}{3} \left(D_{\perp} \mp \sqrt{\frac{15(1-f)}{4f} \bar{D}^2 \bar{W} - 5D_{\perp}^2} \right) \qquad (d)$$

$$\alpha = D_{e,||}/D_{e,\perp}$$
 (e) (2.5.4)

These expressions clearly show the existence of a sign ambiguity which affects the estimates of $D_{e,||}$ (and consequently α) and D_a [2]. Determining which of these two "branches" yields physically correct parameter estimates has been subject of some debate [38, 73, 74] and is not yet fully resolved. In Hansen et al. [38] affected parameters are reported for both branches. The solutions for the two branches are much more obvious than in conventional WMTI, where the sign choice is only known to be stable over diffusion encoding directions for the branch defined by $D_a \leq$ $D_{e,||}$ [2]. WMTI analysis based on modest data makes it feasible to experimentally investigate the unresolved branch duality-e.g., using data acquisitions employing varying diffusion times as in Jespersen et al. [73] which would have been prohibitively time consuming with conventional WMTI. Similarly, the increase in acquisition speed facilitates high resolution data acquisitions for validation purposes or for in vivo applications. High resolution in vivo WMTI based on the 1-9-9 fast DKI protocol is demonstrated in Figure 6 using one of four rats analyzed in Hansen et al. [38]. The advantage of the fast WMTI techniques is evident as the low data requirement allows whole brain coverage at an isotropic resolution of 300 µm to be acquired in 1 h. For ex vivo studies, e.g., for validation studies with subsequent histological analysis, the fast axisymmetric WMTI method enables studies at even higher resolution with high SNR with substantially shorter acquisition times than required for conventional WMTI.

When abandoning the assumption of fully parallel axons, the relationships between the measured diffusion and kurtosis metrics and the microstructural parameters will also involve parameters characterizing the orientation distribution of the axons (fODF) [75]. For axially symmetric systems specifically, these are p_2 and p_4 , the two lowest nontrivial Legendre expansion

coefficients of the fODF [73]. Hence in general, there are more unknowns than equations. However, if a one parameter fODF, such as the Watson distribution, can be assumed, p_2 and p_4 become interdependent and the number of unknowns equals the number of equations, facilitating fast axisymmetric WMTI in the presence of dispersion [73]. Figure 7A (upper row) shows estimates of the time-dependent dispersion [Watson concentration parameter κ (kappa)] of both branches (labeled + and -, shown on the left and right, respectively) measured using such an approach with data acquired from a stimulated echo diffusion-weighted sequence in four regions of interest (ROIs) in in pig spinal cord white matter. The data is from Jespersen et al. [73] with ROI labels matching that work. Figure 7B (lower row) plots time dependence of intra-axonal diffusivity of both branches (again + branch on the left and - branch on the right). As argued in Jespersen et al. [73], these results indicate the most likely choice to be the plus branch $D_a > D_{e,||}$ for this data set. In this manner, the framework allows analysis of time dependence of microstructural parameters in both branches in white matter providing further insight into the branch choice.

Other metrics suitable for WM characterization are available from DKI, e.g., the kurtosis fractional anisotropy (KFA) introduced in Hansen et al. [39] and Jespersen [76] in complete analogy to FA (Equation 2.1.2):

$$KFA = \frac{\left\| \mathbf{W} - \overline{\mathbf{W}} \mathbb{I} \right\|}{\left\| \mathbf{W} \right\|} \tag{2.5.5}$$

where double bars $\|\cdot\|$ signify the Frobenius norm of the tensor and I is the fully symmetric isotropic tensor. This metric describes the ratio of the size of the anisotropic part of W to the Frobenius norm of the full W and thus assumes values in the range 0-1 without the need for rescaling to this range as done for FA (Equation 2.1.2). KFA can be estimated in any region but is likely to be of most interest in anisotropic tissues and in regions where more than one dominant fiber orientation exists. KFA was investigated using simulations and human brain data in Hansen and Jespersen [37] and Glenn et al. [61] and found to provide contrast in regions where complex WM fiber composition causes the FA to vanish, manifesting as dark bands in the FA maps in Figure 8. This is because D cannot resolve more than one primary direction and is related to the well-known crossing fiber problem in DTI. Since KFA does not vanish when 2 or 3 fiber bundles cross, KFA may aid in identifying regions where low FA is due to fiber complexity. The maps from normal human brain shown in Figure 8 allow comparison of FA and KFA contrast in three consecutive slices. Evidently, KFA provides a different contrast than FA. Such additional information from W may be used to increase the robustness of diffusion tensor tractography in complex fiber arrangements. In Hansen and Jespersen [37] KFA was explored further using data from various model systems and KFA estimation by proxy was tested. With sufficient SNR, the proxy was found to agree very well with true KFA even for estimates based on a 1-9-9 data set. However, the SNR required (>100) for this strategy is unrealistic for practical purposes. A strategy for KFA estimation from small data sets based on an



axisymmetric W was evaluated in Hansen et al. [38], but here KFA contrast deteriorates due to the symmetry imposed on W. At present, therefore, KFA can only be reliably estimated based on conventional DKI acquisitions and post-processing yielding the full W tensor with no symmetry constraints.

Summary of Parameter Definitions

In addition to allowing fast estimation, the tensor-based kurtosis metrics covered above also bring DKI metrics onto a form more analogous to their DTI counterparts. This feature is evident in Table 2 which summarizes the definitions for each of the corresponding parameters derived from D and W. Note that the different ranks of D and W cause some definitions to differ by a scaling factor, nevertheless the analogy is obvious in most cases with the notable exception being radial kurtosis in the principal diffusion tensor frame, which cannot be formed from the two non-primary axis directions alone but also contains a crossterm (W_{xxyy}) . For completeness, we also note that other mean kurtosis definitions than those shown in Table 2 have been proposed such as the generalized kurtosis (GK) and the generalized kurtosis of the norm (GKN) [77] which reflect the kurtosis of the diffusion propagator obtained from q-space data based on concepts from multivariate statistics [78].

FUTURE DIRECTIONS FOR THE FAST KURTOSIS TECHNIQUES

Imaging of tissue microstructure has been a strong motivation for diffusion MRI research since the technique was introduced. Since then, studies aimed at improving our ability to image tissue microstructure have focused on understanding cellular-level

diffusion properties by MR microscopy in an effort to inform modeling [79-85], and modeling aimed at extracting specific cytoarchitectural measures [86, 87]. A common limitation of these methods is the requirement for strong gradients. In contrast, DKI yields valuable reporters of tissue microstructure (although most frequently unspecific) while remaining feasible on clinical systems, even those with modest gradient capability. However, acquisition and post-processing time are often limiting factors for clinical imaging and therefore may impede routine clinical application of DKI. Therefore, rapid DKI acquisitions with fast post-processing are important for further clinical adaptation of DKI. Preclinically, the mentioned time constraints are perhaps not as severe. However, the low data requirement of the 1-3-9/1-9-9 protocols enables higher spatial resolution or higher SNR in the same (or less) scan time as conventional DKI acquisitions, which is certainly a significant benefit for all areas of DKI related research. Furthermore, fast DKI may become increasingly valuable in preclinical studies as imaging of awake animals becomes more widely used to avoid physiological perturbations caused by either inhaled or injected anesthesia [88, 89]. Here, methods with modest data demand are preferable to reduce animal stress and to afford data acquisition with gating or even reacquisition if data is affected by movement.

Despite its sensitivity, DKI is microstructurally unspecific, causing studies with comparison of DKI metrics to histology to be needed to understand how disease related microstructural alterations are reflected in DKI (regardless of metric definitions and acquisition methods). Such studies have been carried out for experimental stroke [5, 90], stress and depression [60, 91], and kidney fibrosis [62] to name a few. Furthermore, studies have been performed to elucidate the relation between DKI metrics



FIGURE 7 | Plots of diffusion time dependence for dispersion (A) and intra-axonal diffusivity (D_a , **B**) in both of the two WMTI solution branches (labeled + and -). Data points are color coded to four ROIs in the pig spinal cord used for this experiment. The ROIs are labeled A, C, E, G in keeping with Jespersen et al. [73] where the data was first presented. Figure adapted from Jespersen et al. [73] with permission.



and tissue magnetic susceptibility [92, 93] with results suggesting a susceptibility contribution in DKI metrics warranting further investigation. Similarly, studies have been performed to optimize diffusion sampling schemes for DKI [3] and to assess the DKI metric reproducibility across field strengths [94]. Field strength dependence was found to be most pronounced for KFA which

	Diffusion tensor	Kurtosis tensor
Mean	$\overline{D} = \frac{\operatorname{Tr}(D)}{3}$	$\overline{W} = \frac{\mathrm{Tr}(W)}{5}$
Anisotropy	$FA = \sqrt{\frac{3}{2}} \frac{\ D - \overline{D}\ }{\ D\ }$	$KFA = \frac{\ \mathbf{W} - \overline{W}\mathbf{I}\ }{\ \mathbf{W}\ }$
Axial/longitudinal	$D_{ } = D(\hat{v}_1) = \lambda_1$	$W_{ } = W(\hat{v}_1) = W_{ZZZZ} (*)$
Radial/orthogonal	$D_{\perp} = \frac{1}{2\pi} \int_{S_2} d\hat{n} D(\hat{n}) \delta(\hat{n} \cdot \hat{v}_1) = (\lambda_2 + \lambda_3)/2$ = $\frac{1}{2} (D_{XX} + D_{YY}) (*)$	$ \begin{aligned} W_{\perp} &\equiv \frac{1}{2\pi} \int_{S_2} d\hat{n} \delta(\hat{n} \cdot \hat{v}_1) W(\hat{n}) \\ &= \frac{3}{8} (W_{XXXX} + W_{YYYY} + 2W_{XXYY}) (^*) \end{aligned} $
	$=\frac{1}{2}(D_{XX}+D_{YY})$ (*)	$=\frac{3}{8}(W_{XXXX} + W_{yyyy} + 2W_{XXyy})$ (*)

TABLE 2 | Summary of the fast kurtosis metrics definitions and their DTI counterparts.

Note the convenient similarity in these DTI and DKI metric definitions. (*), The latter identity holds in the frame with $\hat{z} = \hat{v}_1$.

is known to be more SNR dependent than the remaining DKI metrics [37, 61]. In validation studies, high resolution is often desirable in order to identify specific regions or sub-regions, since varying response is sometimes seen in sub-regions as for example in the hippocampus in relation to stress [60, 95]. In such cases, the fast DKI methods are convenient to ensure reasonable scan time for high resolution data acquisitions.

The fast kurtosis methods are already used for imaging of experimental stroke [63, 64] and with the developments in Hansen et al. [38, 42], axial and radial kurtosis can also be investigated from fast DKI data along with WMTI parameters, e.g., for detection of axonal beading [96]. Fast kurtosis imaging is also convenient for studies of the diffusion time dependence of DKI and WMTI parameters. Such experiments are expected to provide a deeper understanding of the WMTI branch ambiguity explored in Hansen et al. [38] by making use of the theoretically expected diffusion time dependence [73].

An intriguing prospect of the fast DKI methods is the combination with SNR-efficient, rapid imaging techniques such as simultaneous multislice imaging (SMS) [68]. Combined with slice dithered enhanced resolution (gSlider), SMS can in principle be used to acquire diffusion MRI with sub-millimeter resolution on clinical systems, although so far demonstrations have used non-standard, high-performance gradient sets [97]. The combination of these fast imaging techniques and fast kurtosis methods would make it feasible to acquire high resolution DKI and WMTI data sets in clinically feasible acquisition times and might even be used for acquisition of time series data so that 1-9-9 data sets can be acquired with high (sub-minute) sliding window temporal resolution. Such data sets may then form the basis for analysis with the presented techniques, yielding time series data of DKI metrics (e.g., mean, radial and axial kurtosis for use in the study of GM plasticity [98]) and WM biomarkers for high sensitivity studies of WM plasticity [99, 100]. Other future applications might include combination of the 1-9-9 framework with diffusion weighted spectroscopy. With such data sets from

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In conclusion, DKI is a non-invasive imaging technique with high sensitivity to microstructural alterations in biological tissue and has demonstrated value in a number of neuroscientific and clinical contexts. Methods now exist which enable rapid estimation of the full range of DKI parameters facilitating routine clinical use of DKI and WMTI.

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BH and SNJ developed fast kurtosis methods, BH wrote the paper, BH and SNJ edited the paper.

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