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Physics schemes in the first version of NCEP operational hurricane analysis and forecast system (HAFS)

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This document summarizes the physics schemes used in two configurations of the first version of the operational Hurricane Analysis and Forecast System (HAFSv1) at NOAA NCEP. The physics package in HAFSv1 is the same as that used in NCEP global forecast system (GFS) version 16 except for an additional microphysics scheme and modifications to sea surface roughness lengths, boundary layer scheme, and the entrainment rate in the deep convection scheme. Those modifications are specifically designed for improving the simulation of tropical cyclones (TCs). The two configurations of HAFSv1 mainly differ in the adopted microphysics schemes and TC-specific modifications in addition to model initialization. Experiments are made to highlight the impacts of TC-specific modifications and different microphysics schemes on HAFSv1 performance. Challenges and developmental plans of physics schemes for future versions of operational HAFS are discussed.

KEYWORDS

HAFS, operational forecast, physics parameterization, tropical cyclones, verification

1 Introduction

Based on NOAA's unified forecast system (UFS) framework, Hurricane Analysis and Forecast System (HAFS) is a UFS application specialized in tropical cyclone (TC) research and forecasting, which has been under active development with collaborative efforts among multiple agencies as well as the broader research communities. The first operational implementation of HAFS (HAFSv1) at NCEP occurred in June 2023 as a planned replacement for operational Hurricane Weather Research and Forecasting (HWRF) model (Tallapragada, 2016) and the Hurricane Multi-scale Ocean-coupled Non-hydrostatic (HMON) model (Mehra et al., 2018; Wang et al., 2019). The newly-developed HAFS was highlighted in the 10th WMO international workshop for TCs held in December 2022 as one of the most important developments of TC dynamic modeling during the last 4

years because it has shown the capability to further improve dynamic model guidance for TC track and intensity (Zhang et al., 2023). Multiple configurations of HAFS have been used in real-time experiments since 2019 to improve model performance. Before 2021, all experiments, including a HAFS-based ensemble system (Zhang et al., 2021), were based on a fixed basin-scale domain with high resolution (3 km) and without a vortex initialization process (Dong et al., 2020; Hazelton et al., 2021; Chen et al., 2023). The moving nest capability and a combined vortex modification and data assimilation system was developed and added to HAFS in late 2021; these additions were tested in the 2022 real-time experiment (Hazelton et al., 2023a).

The operational HAFSv1 is configured as a convection-allowing high resolution atmosphere-ocean-wave coupled TC forecasting system with one storm-following moving nest, advanced vortex initialization, data assimilation, and physics suite that is specially calibrated for hurricane predictions taking into account multiscale interactions (Zhang et al., 2023). The atmospheric model dynamics is based on the fully compressible Finite-Volume Cubed-Sphere (FV3) dynamical core (Lin and Rood, 1996; Lin, 1997; Lin and Rood, 1997; Lin, 2004; Harris et al., 2020) with a Lagrangian vertical coordinate (Chen et al., 2013). The ocean model implemented in HAFS is HYbrid Coordinate Ocean Model (HYCOM) (Bleck, 2002; Bleck et al., 2002). HAFSv1 has two configurations (HFSA and HFSB) to maintain the current operational capability of dynamical model diversity, with the former replacing HWRF and the latter replacing HMON. Like the HWRF and HMON models, both HFSA and HFSB are configured with one movable and two-way interactive nested horizontal grid that follows the projected path of a storm. Both HFSA and HFSB use an Extended Schmidt Gnomonic (ESG) horizontal grid system (Purser et al., 2020), with spatial resolutions of 6 km in the parent domain and 2 km in the nested domain. In addition, both configurations use 81 vertical levels on a sigma-pressure hybrid system with a model top of 10 hPa and the lowest level approximately at 20 m above the surface. There are 23 levels below 1.5 km, with vertical grid spacing varying approximately from 20 m near the surface to 130 m near 1.5 km, to reasonably resolve physical processes in the planetary boundary layer (PBL). A major difference between HFSA and HFSB is in microphysics schemes they used. The single-moment GFDL (Geophysical Fluid Dynamics Laboratory) microphysics scheme (Lin et al., 1983; Lord et al., 1984; Krueger et al., 1995; Chen and Lin, 2013) is used in HFSA, while the double-moment Thompson microphysics scheme (Thompson and Eidhammer, 2014) is used in HFSB. Because the double-moment Thompson scheme is more computationally costly than the single-moment GFDL scheme, HFSB uses a slightly smaller parent domain and lower calling frequency of the radiation scheme than HFSA to guarantee the running time of HFSB forecast jobs fit within the operational time window. Other differences include adjustments in the PBL and convection schemes and the thresholds used in the vortex initialization process. Zhang et al. (2023) gives the details of HFSA and HFSB as well as the development history of HAFS.

In this paper, we will describe the physics schemes used in both HFSA and HFSB, with a focus on TC-specific modifications and microphysics schemes. Section 2 summarizes individual

physics schemes. Section 3 describes HAFS experiments used to highlight the impacts of different microphysics schemes and TC-specific modifications on the performance of HAFSv1. Challenges and future developmental plans of HAFS physics schemes are discussed in Section 4. A summary is provided in Section 5.

2 Descriptions of physics schemes

In general, HAFSv1 uses the same physics schemes as in the NCEP Global Forecast System version 16 (GFSv16), except for a few TC-specific modifications for better TC intensity forecasts and different microphysics schemes for diversity of the configurations. Table 1 summarizes the physics schemes used in both configurations of operational HAFSv1. The main differences in physics schemes between HAFSv1 and the legacy HWRF and HMON are in the selection of surface layer, PBL, and microphysics schemes. HWRF and HMON use the GFDL surface layer scheme (Bender et al., 2007), GFS hybrid K-based Eddy-Diffusivity Mass-Flux (EDMF) PBL scheme with TC-specific modifications (Han et al., 2016; Wang et al., 2018), and the Ferrier-Aligo microphysics scheme (Ferrier et al., 2002; Aligo et al., 2018). In this section, the physics schemes and modifications in HAFSv1 are briefly described.

2.1 Land and ocean surface models

2.1.1 Land surface model

The Noah land surface model (LSM) is used in HAFSv1 to characterize hydrological processes over land. The model is derived originally from the Oregon State University land surface model and has a long history of development. It provides surface sensible and latent heat fluxes, skin temperature, albedo, and other quantities to the atmospheric model. The Noah LSM includes a four-layer soil model, with the thickness of 0.1, 0.3, 0.6, and 1 m, respectively, from top to bottom. It solves the prognostic equations for soil temperature and moisture with the parameterized physical processes of surface energy and water budgets, including precipitation, surface runoff and infiltration, canopy evaporation and transpiration, soil evaporation, sublimation from snowpack, and more. The model uses a few look-up tables to prescribe soil, vegetation, and other general parameters in addition to key input datasets including land-use/vegetation type, soil texture, and slope. The NASA Visible Infrared Imaging Radiometer Suite (VIIRS) vegetation type is used in HAFSv1. Ek et al. (2003) gives a detailed description of the Noah model, its evolution, refinements, as well as key references of the schemes for various physical processes.

2.1.2 Ocean model

HYCOM solves three-dimensional hydrostatic primitive equations without tides at 1/12-degree resolution on the Arakawa C grid and 41 hybrid-z vertical coordinates (Bleck, 2002; Chassignet et al., 2003; Wallcraft et al., 2009). HYCOM in HAFSv1 uses the same solver and model grids as in the NCEP global Real-Time Ocean Forecast System (RTOFS), except it is a regional

TABLE 1 Physics schemes used in HFSA and HFSB. (TC-specific modifications are marked in bold and differences between HFSA and HFSB are marked in *italics*).

Schemes	HFSA	HFSB	References
Land/ocean Surface	NOAH LSM with VIIRS veg type, HYCOM	NOAH LSM with VIIRS veg type, HYCOM	Ek et al. (2003), Bleck (2002)
Surface Layer	GFS, TC-specific sea surface roughness	GFS, TC-specific sea surface roughness	Long (1984), Long (1986), Zheng et al. (2012), Zheng et al. (2017)
Boundary Layer	Scale aware TKE-EDMF, <i>near-surface mixing length adjustment</i>	Scale aware TKE-EDMF, <i>model coefficients and mass flux adjustment</i>	Han and Bretherton (2019), Wang et al. (2022), Wang et al. (2023a), Chen et al. (2022)
Microphysics	<i>GFDL single-moment</i>	<i>Thompson double-moment</i>	Lin et al. (1983), Chen and Lin (2013), Thompson and Eidhammer (2014)
Radiation	RRTMG Called every 720 s	RRTMG Called every 1800 s	Iacono et al. (2008), Mlawer et al. (1997), Mlawer et al. (2016), Liu and Yang (2023)
Cumulus convection (deep and shallow)	Scale-aware-SAS calibrated deep convection entrainment rate	Scale-aware-SAS	Han et al. (2017), Shin et al. (2024)
Gravity wave drag	Unified GWD v0 (orographic on/convective off)	Unified GWD v0 (orographic on/convective off)	Alpert et al. (1988), Kim and Arakawa (1995), Kim and Doyle (2005)

application (Kim et al., 2014; Kim et al., 2022). The regional domain covers the Atlantic, eastern Pacific, and central Pacific basins from 23.03°S to 47.0°N in latitude and from 182°E to 15.0°E in longitude. The lateral boundaries are closed with a buffer zone with 10 horizontal grid spacings, to relax the interior solutions to the climatology. The initial conditions (ICs) for each cycle are provided by subsets of daily nowcast and forecast products of the global RTOFS. The global nowcasts are analyses produced from a flow-dependent three-dimensional variational data assimilation system with 6 hourly incremental analysis updates. The K-Profile Parameterization (KPP) scheme is used to represent sub-grid turbulent momentum and scalar fluxes via diffusivity and viscosity profiles from the sea surface to the bottom of the boundary layer.

Time integration uses the time-split method to apply a longer time step to solve the slow internal mode and a shorter time step to resolve the fast external barotropic mode. The momentum and scalar advection schemes are for second-order and second-order flux-corrected transport (Zalesak, 1979), respectively. HYCOM dynamically remaps the vertical layers in response to density changes at a given time step, using a weighted Arbitrary L-positive definiteness for falling hydrometeors.agrangian-Eulerian (ALE) approach (Boscheri and Dumbser, 2014). Coupling variables between HYCOM and FV3 are atmospheric surface momentum flux, heat flux, precipitation rates and mean sea level pressures to force HYCOM (Kim et al., 2014). HYCOM provides sea surface temperature to the atmospheric model. More details are found in Kim et al. (2024)¹.

2.2 Surface layer scheme

As the lowest part of the atmospheric boundary layer, the surface layer is the region at the bottom 10% of the boundary layer depth and links the atmosphere and the surface (Stull, 1988). The atmosphere and the surface interact through the exchange of surface fluxes of heat, moisture and momentum (Olson et al., 2021).

The surface layer parameterization scheme used in the NCEP GFSv16 was originally developed by Long (1984) and Long (1986). This scheme utilizes the Monin–Obukhov (MO) similarity theory to describe the vertical behavior of nondimensionalized mean flow and turbulence properties within the surface layer (Monin and Obukhov, 1954), with an alternative flux-profile formulation which has no limitation of a finite critical bulk Richardson number throughout a continuous range of the stable regime. Moreover, under stable conditions, a stability parameter constraint proposed by Zheng et al. (2017) is used to prevent the land-atmosphere system from fully decoupling. This constraint yields a more proper downward heat transport between the land and the atmosphere in very stable surface layer conditions, and thus largely mitigates the systematic deficiencies and substantial errors in NCEP GFS near-surface 2-m air temperature forecasts. Momentum and thermal roughness lengths (z_{0m} and z_{0t}) are prescribed to estimate the surface fluxes from the surface-layer MO similarity theory. Moisture roughness length z_{0q} is equal to z_{0t} . Over the land, the vegetation-dependent formulations of momentum and thermal roughness lengths were proposed by Zheng et al. (2012) in the GFSv16 model to reduce the substantial cold bias in land surface skin temperature over arid and semiarid regions during daytime in warm seasons. Over the water, the GFSv16 surface layer scheme's default z_{0m} and z_{0t} (with the namelist option $z0_type = 0$) were derived by Zeng et al. (1998), which is valid for the wind speed range from 0 to 18 m·s⁻¹ and limited by the values at 18 m·s⁻¹. Over open ocean, the momentum

¹ Kim, H.-S., Liu, B., Thomas, B., Rosen, D., Wang, W., Hazelton, A., et al. (2024). Ocean component of the first operational version of hurricane analysis and forecast system: HYbrid coordinate Ocean model (HYCOM). *Front. Earth Sci.* in review.

roughness length is based on a Charnock relation (Charnock, 1955), capped by a constant (0.0317 m). In 2021, surface-layer physics parameterization has been updated, including the calculations of the maximum z/L (L is the obukhov length), thermal and momentum roughness lengths, canopy storage, and sea spray effects (Han et al., 2021).

HAFSv1 uses the same surface layer scheme as GFSv16, except for the parameterizations of the roughness lengths over ocean. The sea surface roughness lengths (z_{0m} and z_{0t}) used in HWRP and HMON (Biswas et al., 2018) were implemented in UFS and adopted in both HFSA and HFSB configurations (with the namelist option $z0_type = 6$). With this option, the relationships between air-sea surface exchange coefficients and 10-m winds are consistent with those supported by observations, despite large uncertainty for high-wind conditions. The sea surface momentum exchange coefficient (C_d) under low-to-moderate winds is consistent with the COARE algorithm V3.5 (Edson et al., 2013), which is supported by numerous observations. Under high-wind conditions, the momentum roughness length is obtained by fitting C_d to available field measurements from various observations (Powell et al., 2003; French et al., 2007; Jarosz et al., 2007; Bell et al., 2012; Holthuijsen et al., 2012; Bi et al., 2015; Potter et al., 2015; Zhao et al., 2015; Richter et al., 2016). The sea-surface scalar roughness length from the COARE algorithm V3.0 (Fairall et al., 2003), which was obtained from various field measurements under low-to-moderate winds, is used to calculate sea-surface heat fluxes. Under high wind conditions, z_{0t} -wind relation is fitted so that the sea-surface enthalpy exchange coefficient (C_k) is capped around 0.00135 with little variation with wind speed, despite large uncertainty based on field measurements (e.g., Bell et al., 2012; Jeong et al., 2012) and laboratory studies (e.g., Komori et al., 2018; Troitskaya et al., 2018). More discussions about the variations of C_d and C_k with 10-m wind used in HAFS are given in Section 3.2.1.

2.3 PBL scheme

For vertical turbulent mixing in the PBL, the scale-aware TKE (turbulent kinetic energy)-based moist EDMF scheme (Han and Bretherton, 2019) from NCEP GFS is used. In the scheme, the sub-grid scale turbulent flux is represented by contributions from large eddies and local small eddies parameterized using a mass-flux (MF) scheme and an eddy-diffusivity (ED) scheme, respectively. The nonlocal flux includes the contribution of the stratocumulus-top-driven downdraft as well as for the thermal in the unstable boundary layer during the daytime. In addition, the scheme also considers the effect of enhanced buoyancy during the moist adiabatic process. The contribution of sub-grid scale cumulus convection to TKE is estimated by parameterized cumulus mass flux. Entrainment rates in cumulus convection schemes are proportional to sub-cloud mean TKE. The scale-aware parameterization is based on the scale-aware cumulus convection parameterization (Han et al., 2017), where the mass flux for the updraft decreases with increasing the updraft area fraction for the horizontal grid spacing where the large turbulent eddies are partially resolved. The scheme also includes a TKE dissipative heating proportional to the TKE dissipation rate.

In a recent update (Han et al., 2022), the mass-flux scheme was modified to eliminate negative values for tracers such as water vapor, cloud condensate, TKE, and all other scalar variables. To reduce the excessive vertical turbulence mixing in strongly sheared environments such as in hurricanes, the turbulent mixing length was modified to decrease in larger environmental wind shear. To better predict surface inversion as well as capping inversion near the PBL top, the background turbulent eddy diffusivity was also modified to be reduced in the inversion layers.

There are two modifications in the PBL scheme used in HFSA and HFSB, respectively, for improving TC intensity forecasts.

2.3.1 Modification in HFSA—adjustment of the near-surface mixing length

The $sfc_rlm = 1$ option is used in HFSA, which forces the mixing length near the surface follows the MO similarity theory so that the near-surface mixing length scale used in the PBL scheme is consistent with that in the surface-layer scheme. This modification improves the intensity bias and wind profiles at low levels near the eyewall (Wang et al., 2022; Wang et al., 2023a). The maximum allowable mixing length (L_{max}) is set to 300 m and 250 m, respectively in parent and nest domains. The default L_{max} value in NCEP GFSv16 is 300 m.

2.3.2 Modification in HFSB—TCPBL adjustment

The $tc_pbl = 1$ option is used in HFSB. The tc_pbl option uses a recently developed modeling framework tailored to hurricane boundary layers (Chen et al., 2021). It refers to four major changes to the TKE-EDMF scheme based on boundary layer theories and large-eddy simulations (Chen et al., 2022). These changes include 1) determining values of two coefficients in the eddy viscosity and TKE dissipation term to match the surface layer and PBL parameterizations (discussions in Chen et al., 2022), 2) reducing L_{max} from 300 to 75 m over the nest domain (which agrees with the upper end of the observational values, see Figure 3 in Chen et al., 2022), while L_{max} is still 300 m in the parent domain, 3) implementing a different bulk-Richardson-number-based PBL height (Vogelezang and Holtslag, 1996) that performs better in high-wind conditions, and 4) reducing mass fluxes from the nonlocal portion of the PBL scheme in high-wind conditions (Chen and Marks, 2024). These changes effectively reduce the excessive vertical mixing in hurricane conditions as seen from the original TKE-EDMF scheme, and have been shown to lead to improved forecasts of TC structure and rapid intensification in HFSB (Gopalakrishnan et al., 2021; Hazelton et al., 2021).

2.4 Scale-aware deep and shallow convection schemes

The deep cumulus convection scheme in both configurations of HAFSv1 is the same as that used in NCEP GFSv16 (Han and Pan, 2011; Han et al., 2017). It uses a bulk mass-flux scheme for well-organized updraft and complementary environments such as cumulus convection. The parcel property is calculated by a single entraining and detraining plume model. The lateral entrainment and detrainment are formulated in proportion to

environmental relative humidity to suppress convection in a drier environment. The cloud base mass flux is determined with a quasi-equilibrium assumption for horizontal grid spacing larger than 8 km, while it is determined by a mean updraft velocity for horizontal grid spacing smaller than 8 km. Convection triggering conditions include the distance between the convection starting level and the level of free convection, sub-cloud convective inhibition, and sub-cloud mean relative humidity. The distance threshold is proportion to the grid-scale vertical velocity, ranging from 120 to 180 hPa. The scheme also includes the effects of the convection-induced pressure gradient force on convective momentum transport. The cloud condensate in the upper cloud layers is detrained into the grid-scale condensate. The scale- and aerosol-aware parameterizations are based on Han et al. (2017). In the current version, the scale-aware parameterization considered the ratio of advection time scale to convective turnover time scale. The convective turnover time scale is used as the convective adjustment time scale. The rain conversion rate is a function of air temperature above the freezing level, decreasing with decreasing air temperature. The scheme also considers the mutual interaction between convection and TKE (Han and Bretherton, 2019; Han et al., 2021). TKE is transported and contributed by parameterized convection. As a simple parameterization, the TKE contribution due to convection is calculated by cloud mass fluxes. The entrainment rates in convection updrafts are proportional to sub-cloud mean TKE.

The shallow cumulus convection scheme in HAFSv1 is also based on that in NCEP GFSv16 (Han and Pan, 2011; Han et al., 2017). There are three major differences from the deep convection scheme. Firstly, the shallow cloud base mass flux is calculated as the updraft velocity averaged in a cloud layer, rather than with a quasi-equilibrium assumption. Secondly, only convection updrafts are considered in the shallow scheme. Thirdly, the entrainment rate is larger than that in deep convection. In a horizontal grid, only either deep or shallow convection is allowed. Separation of deep and shallow convection is determined by cloud depth (currently set to 200 hPa).

There is one modification to the deep convection scheme in HFSA, where the entrainment rate is increased. Experiments indicate that this adjustment can improve intensity forecasts (see Section 3.2.3).

2.5 Microphysics schemes

The GFDL and Thompson microphysics schemes are used, respectively, in HFSA and HFSB to increase model diversity. The former is used in NCEP GFSv16.

2.5.1 GFDL microphysics scheme

GFDL microphysics scheme is a single-moment scheme. It predicts five hydrometeors (cloud water, cloud ice, rain, snow and graupel). The scheme was developed based on the Lin-Lord-Krueger cloud microphysics scheme (Lin et al., 1983; Lord et al., 1984; Krueger et al., 1995) and was substantially revised and redesigned at GFDL for the GFDL global high-resolution model HiRAM (High-Resolution Atmospheric Model) in the early 2000s (Zhao et al., 2009; Chen and Lin, 2011; 2013; Harris et al., 2016). The scheme

was updated by Zhou et al. (2019), and was named GFDL MP v1. The GFDL MP v1 was implemented into the NCEP GFS in 2019. The GFDL microphysics scheme is formulated with a strict moist energy conservation during phase changes, and maintains heat and momentum budgets for all condensates. A part of the scheme is in-core fast saturation adjustment which is called after the “Lagrangian-to-Eulerian” remapping in the code. The scheme uses time-splitting between warm-rain and ice-phase processes. Scale awareness is achieved by an assumed horizontal sub-grid variability and a second-order finite-volume-type vertical reconstruction for autoconversion processes.

2.5.2 Thompson microphysics scheme

The Thompson microphysics scheme predicts the mixing ratios of cloud water (qc), rain (qr), cloud ice (qi), snow (qs), and graupel (qg), plus the number concentration of ice (Ni) (Thompson et al., 2004; Thompson et al., 2008). In a later version, the number concentration of rain is added as a prognostic variable, and, therefore, the scheme becomes a double moment for both ice and rain. In 2014, the scheme was updated with an option to explicitly incorporate aerosols in a simple and cost-effective manner (Thompson and Eidhammer, 2014). The scheme nucleates water and ice from their dominant nuclei and tracks and predicts the number of available aerosols. In the 2014's update, three new prognostic variables were added: the number concentration of cloud water, as well as the number concentrations of the two new aerosol variables. This scheme adopts a generalized gamma particle size distribution assumption for all hydrometer species except for snow. The snow distribution is based on Field et al. (2005). The method by Srivastava and Coen (1992) is used in the calculations of the evaporation of cloud rain and the sublimations of cloud ice, snow, and graupel. An explicit bin method in the Stochastic Collection Equation (SCE) is used to represent the effects of collisions between hydrometeors. The conversion of cloud ice to snow is represented by an explicit and non *ad hoc* method. To reduce the numerical instability when using this scheme with large time steps in weather forecast application, a smaller time step than the FV3 physics time step can be used though an option of inner loop through FV3 namelist or setting a sub-cycle loop in the physics suite definition file controlled by the common community physics package (CCPP, https://dtcenter.ucar.edu/gmtb/users/ccpp/docs/sci_doc_v2/) framework. Another namelist option to reduce the instability is to use the Semi-Lagrangian sedimentation of rain and graupel proposed by Juang and Hong (2010), in which a sub-time step is only applied to sedimentation computation (Sun et al., 2023).

2.6 Radiation scheme

The radiation scheme used in HAFS is the Rapid Radiative Transfer Model for GCMs (RRTMG). The RRTMG calculates shortwave (SW) flux, longwave (LW) flux and the radiative heating/cooling rates of all model levels at any given location. Details for the implantation of RRTMG in NCEP GFSv16 can be found in Liu and Yang (2023). For computational efficiency, the correlated K-method is used in RRTMG. The accuracy of this method is consistent with the computationally more expensive line-by-line radiative transfer models. The SW algorithm includes

112 g-points in 14 bands, while 140 unevenly distributed g-points (quadrature points) in 16 broad spectral bands are included in the LW algorithm. Key atmospheric absorbing gases include ozone, water vapor, and carbon dioxide. RRTMG also considers the effects of minor absorbing species including methane, nitrous oxide, oxygen, and halocarbons (CFCs). Aerosol optical properties, cloud liquid water and ice paths and effective radius are used to represent the radiative effects of aerosols and clouds in the calculation. The effects of sub-grid scale clouds are treated by a Monte-Carlo Independent Column Approximation (McICA) method, with a decorrelation length overlap assumption for multi-layered clouds.

2.7 Gravity wave drag scheme

The CCPP Suite shared by GFS and HAFSv1 is the Unified Gravity Wave Physics (UGWP), developed within the framework of NOAA's UFS. HAFSv1 uses an orographic drag suite and a non-stationary gravity wave drag parameterization.

Some of the topographic effects can be resolved explicitly in atmospheric model's dynamic core, however, its sub-grid scale impact needs to be parameterized, which is done in the UGWP orographic drag suite, including four orographic physical parameterizations: (1) Mesoscale Orographic gravity wave drag (MSOGWD), developed by [Kim and Arakawa \(1995\)](#), and later modified by [Kim and Doyle \(2005\)](#) and [Choi and Hong \(2015\)](#). (2) Low-level flow blocking by subgrid-scale orography in the UGWP suite follows the scheme of [Kim and Arakawa \(1995\)](#). (3) The small-scale GWD (SSGWD) scheme of [Steenveld et al. \(2008\)](#) and [Tsiringakis et al. \(2017\)](#), captures the effects of gravity waves produced by horizontal terrain variations on scales down to about 1 km in length. Just as MSOGWD, such small-scale waves can propagate vertically under highly stable conditions. The scheme is active for all horizontal grid spacings. (4) The turbulent orographic form drag (TOFD) parameterization is based on [Beljaars et al. \(2004\)](#), and accounts for drag due to horizontal topographic variations on scales of 5 km and smaller. Note that TOFD is not a gravity wave phenomenon, as it does not involve the vertical transport of momentum and energy. The effects of the horizontal grid resolution on the strength of the parameterized GWD is accounted for. These parameterizations are essential to accurately forecasting the near-surface winds, the zonal circulation in global models and alleviating the high westerly wind speed biases and associated "cold pole" problems that develop without parameterized GWD.

The non-topographic, sub-grid-scale gravity wave sources, including deep convection, frontal instability, and stratified shear instability associated with the tropospheric jet, must be parameterized in order to provide realistic forecasts of winds in the middle atmosphere ([Scinocca and Ford, 2000](#); [Scinocca, 2003](#)).

A scheme to move from a single-wavenumber representation of sub-grid topography to a Fourier series of two-dimensional ridges approach has been proposed. Particular consideration for HAFS, which has a very high horizontal resolution, is clearly necessary in the future.

3 Experiments, results, and discussions

Experiments were designed to highlight the impact of TC-specific modifications and different physics options on HAFS performance. The HAFS system using the NCEP GFSv16 physics package ([Table 2](#)) without any modifications was first run to illustrate the necessity of modifications, referred to as HGFS. Then, two sets of experiments were run based on the HFSA and HFSB configurations, respectively, as summarized in [Tables 2, 3](#), to analyze the impact of each modification on HAFS performance. Note that TC intensity in the following analyses refers to the maximum 10-m wind speed (V_{max}) unless otherwise specified.

Since there are three TC-specific modifications used in the HFSA configuration, three HFSA-based experiments, referred to as HAZ0, HAL0, and HAET, were run, where the respective modifications were not adopted. The HAZ0 experiment uses the default roughness length formulations over open ocean as used in NCEP GFSv16 (default $z0_type = 0$ in the model namelist) to assess the impact of the TC-specific roughness length formulations on HAFS performance. The HAL0 experiment uses the default settings of the TKE-EDMF PBL scheme as used in NCEP GFSv16 (i.e., $sf_rlm = 0$ and $tc_pbl = 0$) to assess the impact of the adjustment of near-surface mixing length in the PBL scheme ($sf_rlm = 1$) on HAFS performance. The HAET experiment uses the default value of the entrainment rate coefficient ($clam_deep = 0.1$), which is smaller than that used in the operational HFSA, to assess the impact of the increased entrainment rate. The fourth experiment (HAMP) runs HFSA with the Thompson microphysics scheme instead of the GFDL microphysics scheme to assess the impact of different microphysics schemes on HAFS, although different microphysics schemes were originally intended to add model diversity to HAFS forecasts.

Two TC-specific modifications are used in the HFSB configuration. One is the TC-specific roughness length ($z0_type=6$) like in HFSA. The other is the TCPBL adjustment in the PBL scheme ($tc_pbl = 1$). To assess the impact of the TCPBL adjustment in the PBL scheme on HFSB performance, a HFSB-based experiment was run, referred to as NOTB, where the default PBL settings are used, to highlight the impact of the TCPBL adjustment.

For all experiments, the HAFS system is initialized every 6 h with a combined vortex initialization and data assimilation system using data from the NCEP GFSv16 analysis and global data assimilation system. HAFS's 6-h forecasts from the previous cycle are also used in the initialization for warm cycling (a first-guess of vortex) when the initial V_{max} is greater than a threshold (50 kt in HFSA and 40 kt in HFSB). HGFS and each HFSA-based experiment simulated most of the TCs with life cycles longer than 2 days in 2021 and 2022 over the North Atlantic (NATL) basin as listed in [Table 4](#), producing 618 forecast cycles. The HFSB-based experiment simulated the same storms, but also included five NATL storms in 2020 ([Table 4](#)), adding 147 cycles to the sample.

The evaluation below focuses on the performance of track, V_{max} , and vortex size forecasts by the HAFS experimental runs. NHC's verification package is used to assess the statistical performance of each experiment against the best-track analysis data.

TABLE 2 Summary of HFSA-based experiments.

Experiment	Description and TC-related physics namelist options
HFSA	Operational HFSA v1, default NCEP GFSv16 settings ^a except for <code>z0_type = 6</code> , <code>sf_rlm = 1</code> , <code>clam_deep = 0.15</code>
HAZO	Same as HFSA, except <code>z0_type = 0</code> (default)
HAL0	Same as HFSA, except <code>sf_rlm = 0</code> and <code>tc_pbl = 0</code> (i.e., default PBL settings)
HAET	Same as HFSA, except <code>clam_deep = 0.1</code> (default)
HAMP	Same as HFSA, except Thompson microphysics scheme is used

^aDefault settings in the namelist use `z0_type = 0`, `sf_rlm = 0`, `tc_pbl = 0`, `clam_deep = 0.1`, GFDL, microphysics scheme, and other schemes HAFSv1 adopts from NCEP GFSv16 without modifications.

TABLE 3 Summary of HFSA-based experiments.

Experiment	Description and TC-related physics namelist options
HFSA	Operational HFSA v1, default NCEP GFSv16 settings except for the Thompson microphysics scheme, <code>z0_type=6</code> , and <code>tc_pbl=1</code>
NOTB	Same as HFSA, except <code>tc_pbl=0</code> and <code>sf_rlm=0</code> (i.e., default PBL settings)

Figure 1 compares the performance of the HAFS experiments using the NCEP GFSv16 physics package (HGFS, blue lines) and the legacy HWRF (red lines), along with operational configurations (HFSA in purple lines and HFSA in green lines). There are 543 verifiable cycles for this set of 4-run comparison. Compared with HWRF, HGFS has noticeably improved the forecasts of track (Figure 1A) and the radius of 64-kt wind (R64) (Figure 1F) as well as comparable performance in the forecasts of the radii of 34-kt wind (R34) (Figure 1D) and 50-kt wind (R50) (Figure 1E). However, HGFS generates larger root-mean-squared (RMS) errors and biases in Vmax than the legacy HWRF does, with the mean Vmax of HGFS approximately 10 kt weaker than HWRF and the best-track analysis (Figure 1B). In addition, HGFS has degraded the performance in the forecasts of the radius of the surface maximum wind (RMW) (Figure 1C), with larger RMS errors and positive biases than HWRF. This comparison indicates that modifications are needed so that the performance of HAFS is comparable to or better than the then-operational HWRF model at NCEP. As a result, TC-specific modifications are introduced to the two configurations (i.e., HFSA and HFSA) of the operational HAFSv1. Figure 1 shows that the performance of HFSA and HFSA is close to or better than that of HWRF, except for RMW forecasts. Next, we will analyze the impact of each modification on HAFS performance.

3.1 Case study—Hurricane IAN (09 L)

This section compares the simulated track and Vmax of Hurricane Ian (09 L) from different HAFS experiments to illustrate the impact of the TC-specific modifications or different microphysics schemes on HAFS forecasts.

Hurricane Ian (09 L) was a major Category five hurricane over the NATL basin in 2022. The maximum sustained 10-m wind speed of this hurricane reaches 160 mph, with the central pressure of 937 hPa, just before making landfall in Southwest Florida, United

States around 12 UTC on 28 September 2022. Ian originated from a tropical wave. It becomes a numbered storm (09 L) at 12 UTC on 23 September 2022. After that, Ian nearly kept intensifying till 12 UTC on 28 September 2022, with the maximum 10-m wind speed increase reaching 30 kt during 12 h before it reaches peak wind. Ian made three major landfalls during its life cycle. It made its first landfall on the western Cuba as a category three hurricane on 27 September 2022, and its final landfall in South Carolina on 30 September 2022. It was completely dissipated by 12 UTC on 1 October 2022.

The HAFS cycling system in each experiment simulating Hurricane Ian starts from cycle 2022092306 through 2023100106 UTC, initialized every 6 h. Each experiment produced 31 5-day forecasts of track, Vmax, and other atmospheric and oceanic fields.

Figures 2A–E compare the spaghetti plots of the simulated tracks of Hurricane Ian (09 L) from all forecast cycles by different HFSA-based runs, along with the best-track analysis (black solid line). In general, the track forecasts of all runs at lead times beyond 72 h exhibit westward biases, except that some track forecasts initialized on September 23 and 24, 2022 are biased to the east (red lines). Comparing HAZO, HAL0, and HAET with HFSA shows that the TC-specific modifications do not have major impacts on track forecasts, despite improved track biases in some cycles. Using the Thompson microphysics scheme improves the track forecasts at lead times less than 72 h or 96 h of the cycles initialized on September 23 and 24, 2022 (i.e., less eastward biases) but it degrades the track forecasts at lead times beyond 72 h of the cycles initialized on September 25–28, 2022 (i.e., more westward biases, see red, green, and blue lines). Figures 2F–J compare the spaghetti plots of Vmax forecasts for all cycles. It shows that the modified roughness lengths and mixing length as well as the entrainment rate adjustment do improve the rapid intensification (RI) forecasts initialized on September 23–26, 2022 (red and green lines). HFSA with the Thompson microphysics scheme (HAMP) produces not

TABLE 4 List of NATL storms simulated in retrospective HAFS experiments.

Year	Storm ID (L)	Storm names	No of forecast cycles
2022	02	Bonnie	19
	05	Danielle	29
	06	Earl	32
	07	Fiona	42
	08	Gaston	22
	09	IAN	33
	13	Julia	13
	14	Karl	15
	15	Lisa	23
	16	Martin	10
2021	17	Nicole	16
	03	Claudette	12
	05	Elas	36
	06	Fred	30
	07	Grace	33
	08	Henri	29
	09	Ida	17
	12	Larry	43
	14	Nicholas	10
	15	Odette	17
	16	Peter	24
	17	Rose	14
	18	Sam	49
2020	20	Victor	20
	21	Wanda	30
	09	Isaias	32
	13	Laura	33
	19	Sally	22
20	Teddy	44	
28	Zeta	16	

only stronger Vmax forecasts but also better RI forecasts than that with the GFDL scheme. Figure 3 quantitatively compares the RMS errors and mean biases of track, Vmax, and vortex sizes

at different forecast lead times. HAZ0 and HAL0 do not have major changes in the track RMS errors, compared with HFSA, while increasing the entrainment rate (HAET vs. HFSA) does

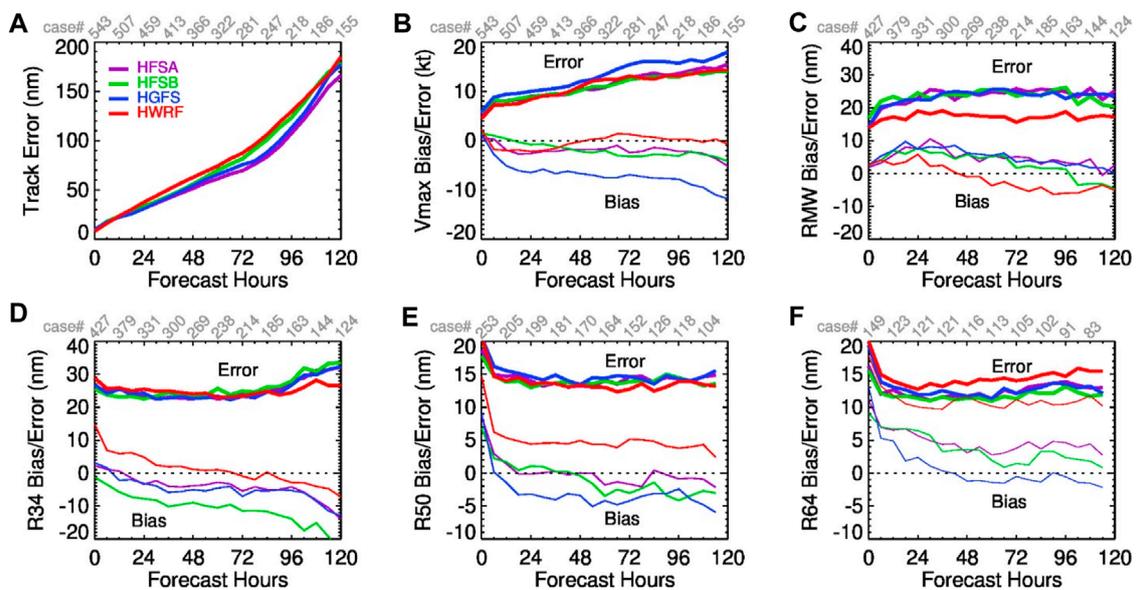


FIGURE 1 (A) RMS errors of track simulated by HFSA, HFSB, HGFS, and legacy HWRf. RMS errors and biases of (B) Vmax, (C) RMW, (D) R34, (E) R50, and (F) R64.

reduce the track RMS errors for lead times beyond 96 h. The run with the Thompson microphysics scheme (HAMP) degrades the track forecast for Hurricane Ian, due to large westward bias as shown in Figure 2. HFSA has smaller RMS errors and biases in Vmax than HAZ0, HAL0, and HAET, indicating improvements by those TC-specific modifications. Noticeably, HAMP has the smallest Vmax biases, although RMS errors are close to those of HFSA. For TC structure verifications, all RMS errors in vortex sizes are very close among the experiments, but differences in the mean sizes from the different experiments are noticeable. For lead times beyond 48 h, using the modified roughness length in HAFS reduces the mean RMW, while adjusting the mixing length and entrainment rate increases the mean RMW, leading to positive RMW bias. The mean R34 decreases with lead time for all experiments, resulting in large negative R34 bias for lead times beyond 96 h. Overall, using the modified roughness length and increasing the entrainment decreases the mean sizes of R34, R50, and R64, respectively. Both adjusting the mixing length and using the Thompson microphysics scheme increase the vortex size.

Similarly, Figure 4 shows the spaghetti plots of track and Vmax from all cycles of Hurricane Ian (09 L) in the HFSB and NOTB experiments. Overall, the track forecasts of HFSB and NOTB have westward biases at lead times beyond 72 h, with the former slightly more westward than the latter (Figures 4A, B). Applying the tc_pbl option improves RI in the cycles initialized on September 23–26 (red and green lines in Figures 4C, D). From the analyses of errors and biases, a notable difference is the improvement of Vmax bias with the tc_pbl option (Figure 5B), although track is slightly degraded on day 5 (Figure 5A). There are no major differences in the RMS errors in RMW, R34, R50, and R64. The TCPBL adjustment in HFSB reduces mean R34, but increases mean R50 and R64 sizes; this degrades the R34 and R64 biases, compared with NOTB. This issue could be due

to the impact of the reduced value of Lmax in the nest domain as well as zeroing surface-driven mass fluxes for nearly neutral conditions (Chen and Marks, 2024) in HFSB on vortex size.

3.2 Statistical performance

Based on the criteria of the NHC's verification package, there are 548 verifiable cycles from all 618 forecast cycles of each HFSA-based experiment. To assess the HAFS performance of weak and strong cycles, a stratified verification analysis is conducted by grouping all verifiable cycles into 367 strong (≥ 64 kt) and 181 weak (< 64 kt) cycles of each HFSA-based experiment based on the maximum Vmax of the best-track analysis during the same 5 days of each cycle. For HFSB-based experiments, there are 684 verifiable cycles from all 765 cycles for each experiment. The verifiable cycles are grouped into 497 strong cycles and 187 weak cycles.

3.2.1 Impact of the modified roughness lengths ($z0_type = 6$)

Many investigations have shown that the intensity and structure of a TC simulated by numerical models are sensitive to surface drag coefficients (i.e., Cd and Ck) (e.g., Montgomery et al., 2010; Bryan, 2012; Smith et al., 2014). Ck and Cd characterize the turbulent exchanges of heat and momentum between the ocean and atmosphere in numerical models, respectively. In the atmospheric model of HAFS, the surface fluxes are calculated through the MO similarity theory by specifying the momentum and thermal roughness lengths, rather than directly specifying Cd and Ck values. To compare with observations, we calculate Cd and Ck at 10-m level using the output of HFSA and HAZ0 simulations and display them as a function of 10-m wind speed in Figure 6. The

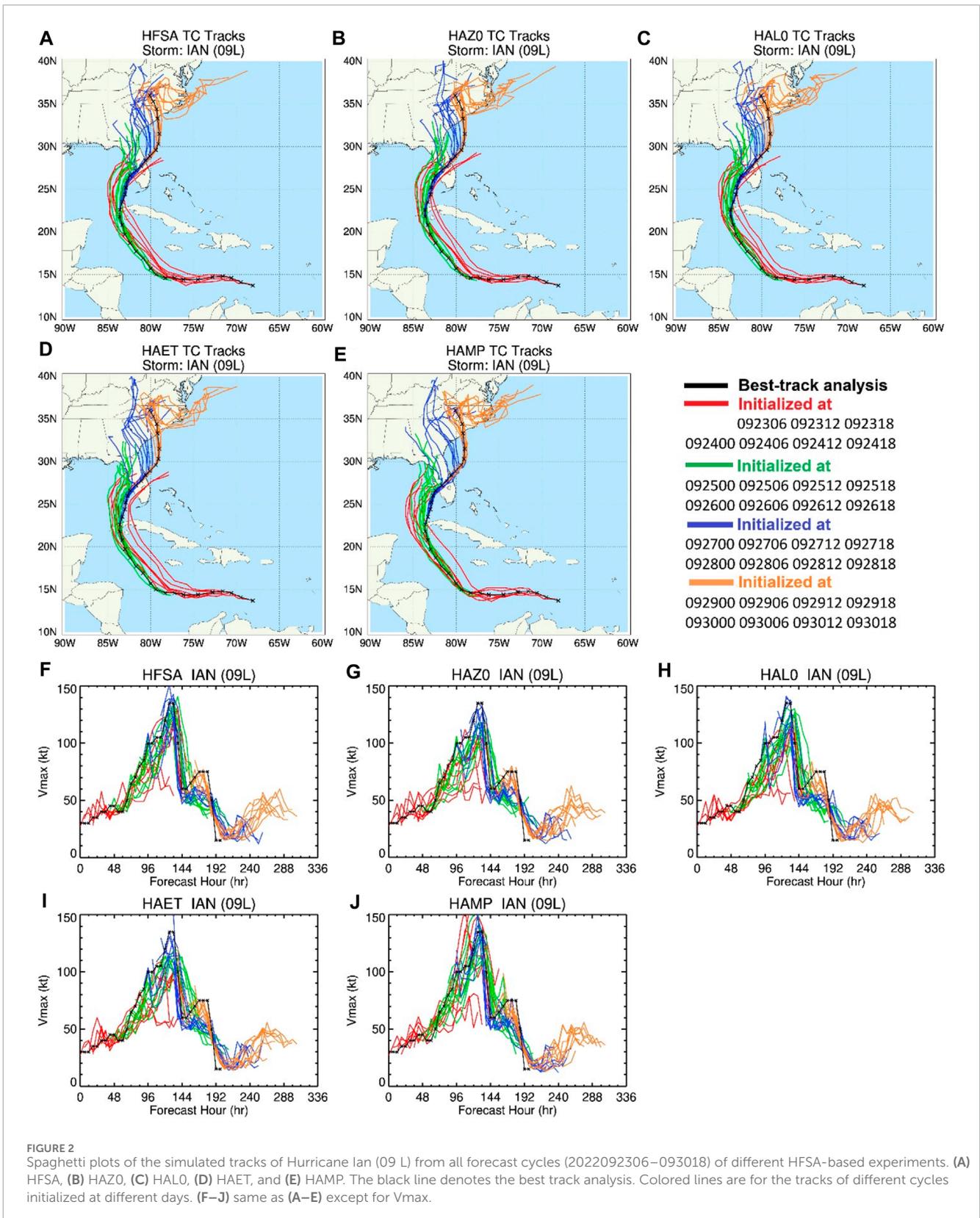


FIGURE 2 Spaghetti plots of the simulated tracks of Hurricane Ian (09 L) from all forecast cycles (2022092306–093018) of different HFS-based experiments. (A) HFSA, (B) HAZO, (C) HALO, (D) HAET, and (E) HAMP. The black line denotes the best track analysis. Colored lines are for the tracks of different cycles initialized at different days. (F–J) same as (A–E) except for Vmax.

default momentum roughness length over the open ocean in the NCEP GFSv16 model is based on a Charnock relation (Charnock, 1955), capped by a constant (0.0317 m). This relation results in a

nearly constant drag coefficient (approximately 0.0025) when 10-m winds are stronger than 30 m/s (Figure 6A). With the modified roughness length described in Section 2.2, the drag coefficient

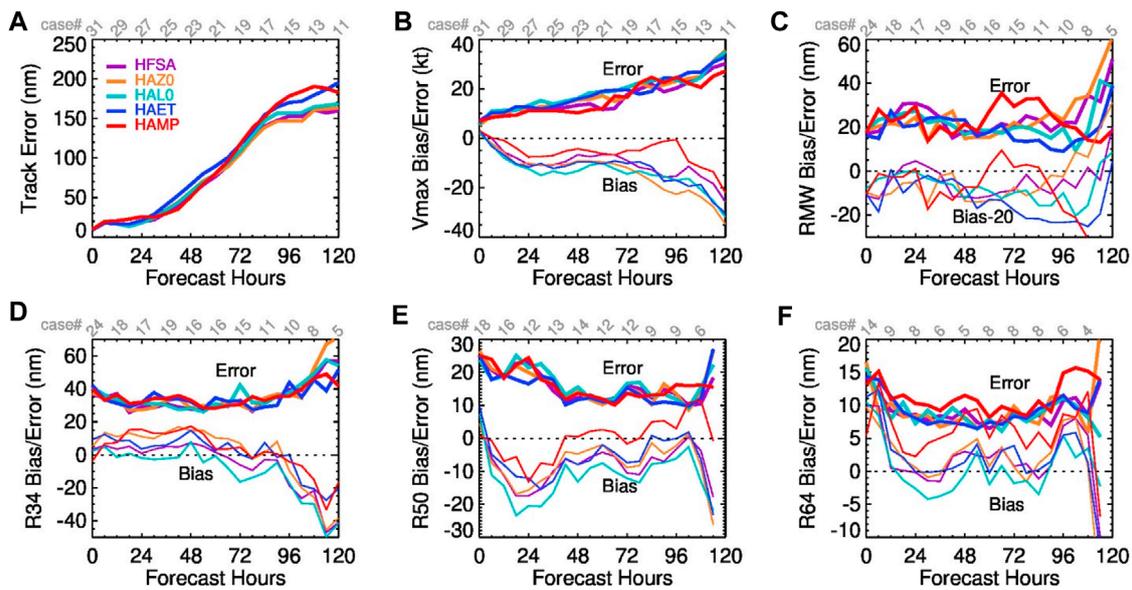


FIGURE 3 (A) RMS errors of track from the simulated IAN (09 L) cycles from HFSA-based experimental runs, RMS errors and biases of (B) V_{max} , (C) RMW, (D) R34, (E) R50, and (F) R64. Note that the bias of RMW minus 20 is shown in (C).

increases generally with 10-m wind speed to approximately 0.0025 from 5 m/s to approximately 30 m/s, then decreases to 0.0016 until 50 m/s, and levels off afterward. This variation is more consistent with the observations (symbols in Figure 6A) than that of the drag coefficient derived from the default momentum roughness length, despite large uncertainty in C_d under strong wind conditions. The values of C_k , derived from the MO similarity theory respectively with the default and modified thermal roughness lengths, are close and much less variable than C_d when 10-m wind speeds are stronger than 5 m/s. For strong winds, C_k is approximately 0.0013–0.0014, despite large uncertainty from observations (Figure 6B).

Figure 7 compares the HAFS performance using the default (HAZ0) and modified (HFSA) roughness lengths, showing that the modification to the sea surface roughness lengths is necessary for simulating strong TCs. For strong cycles, the largest improvement with the modified roughness lengths is in the V_{max} bias, without degrading RMS errors in track (Figure 7A) and V_{max} (Figure 7B). While the mean intensities of both HAZ0 and HFSA at all lead times are weaker than those from the best-track analysis, the negative bias on day 5 of HFSA is reduced by 60%, compared with HAZ0. In regard to vortex size, RMS errors and biases in RMW, R34, R50, and R64 near the surface of HFSA are close to those of HAZ0 except that the mean R34 and R50 values of HFSA are reduced. For weak cycles, using the modified roughness lengths does not change the overall performance of HAFS, except for slightly improved track and reduced mean in R34 and R50. This is expected because C_d and C_k in HFSA are very close to those in HAZ0 for weak winds (Figure 6).

3.2.2 Impact of the mixing length adjustment in HFSA ($sf_rlm = 1$)

HFSA and HAL0 experiments are identical except that the options of $sf_rlm = 1$ and 0 are used in HFSA and HAL0, respectively.

With $sf_rlm = 1$, the vertical mixing length in the TKE-EDMF PBL scheme is modified to make sure it is consistent with the MO similarity theory near the surface (within the level of 5% of PBL height). HAL0 uses the original TKE-EDMF PBL scheme (i.e., $sf_rlm = 0$). Wang et al. (2023a) described and analyzed the modification and the sensitivity of HAFS performance to different formulations of vertical mixing length. They also showed that the modification improves the vertical profiles of near-surface wind in the eyewall area.

Figure 8 compares the HAFS performance with and without the modification. Compared with HAL0, the RMS errors in track and V_{max} of HFSA are slightly reduced for both weak and strong cycles. A more notable improvement is that the negative V_{max} bias is reduced by 40%–50% for strong cycles (Figure 8B). The increased mixing length near the surface enhances the downward momentum mixing, and hence strengthens the radial wind to maintain dynamic balance, in favor of vortex intensification. The RMS errors in the vortex sizes of HAL0 and HFSA are close. However, the mean sizes of R34, R50, and R64 in HFSA are increased with the modification; this makes R34 and R50 of HFSA closer to the best-track analysis at all lead times than those of HAL0 (Figures 8C, D) but produces too large R64 (Figure 8F). Despite the differences in mean R34, R50, and R64, the modification does not noticeably change the mean RMW values. For weak cycles, the performances of HAL0 and HFSA are close except that HFSA slightly increases the positive bias of V_{max} and reduces the negative R34 bias (Figures 8H, J). As the number of strong cycles is approximately twice that of weak cycles, the modification improves the operational HFSA in general but more efforts are still needed to reduce the positive V_{max} bias of weak cycles and positive R64 bias of strong cycles. The detailed analyses on the impact of the modification on storm structure can be found in Wang et al. (2023a).

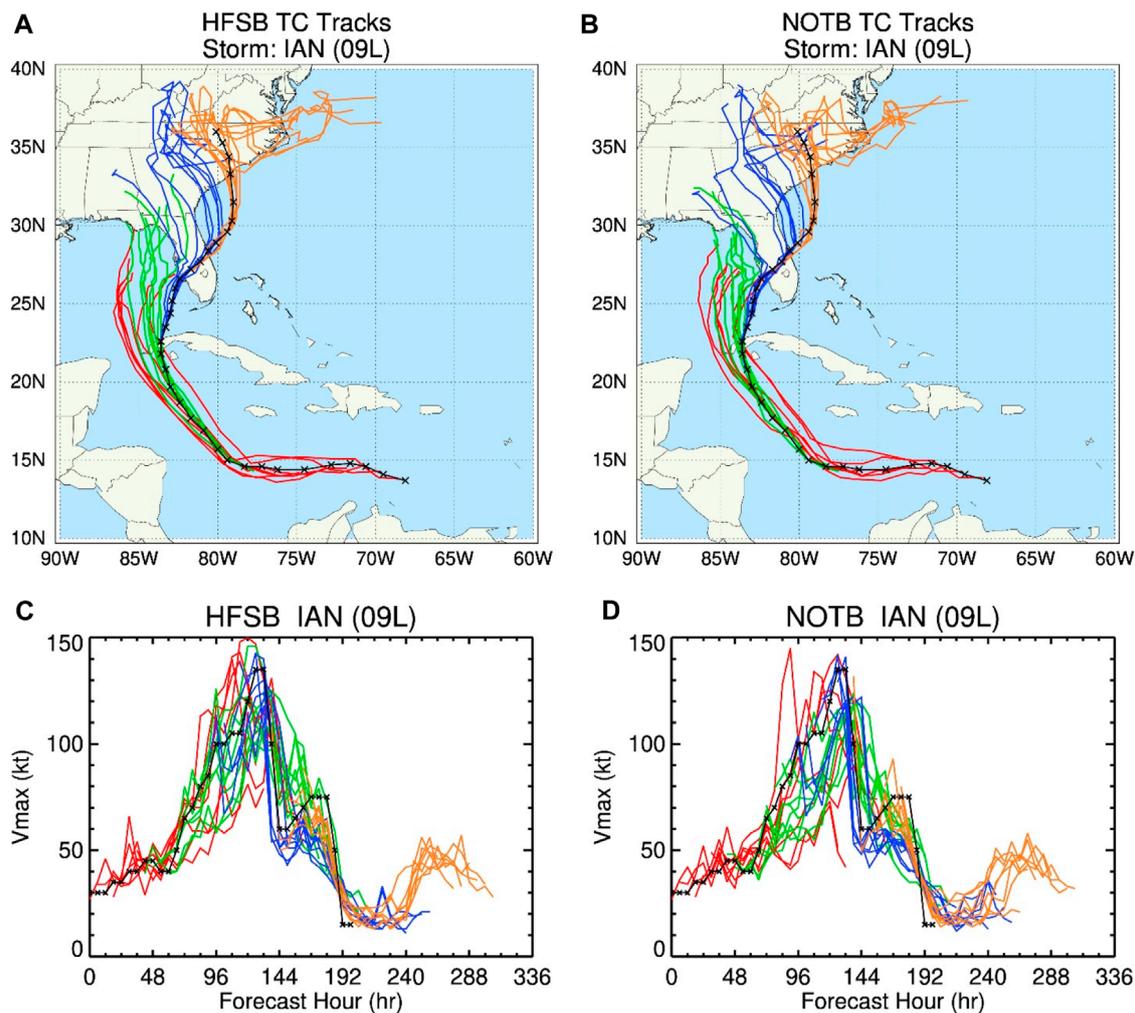


FIGURE 4
Spaghetti plots of track from all cycles of Hurricane Ian (09 L) simulated by (A) HFSB and (B) NOTB. (C, D) are the same as (A, B) except for Vmax. Same color legend as in Figure 2.

3.2.3 Entrainment rate adjustment in HFSA

The deep convection entrainment rate (ϵ) of the scale-aware Simplified Arakawa-Schubert (SAS) convection scheme is formulated as (Han and Pan, 2011; Han et al., 2017),

$$\epsilon = \frac{c}{z} \left(\frac{q_s}{q_{sb}} \right)^2 + d_1 (1 - RH) \left(\frac{q_s}{q_{sb}} \right)^3,$$

where z is the height; c a tunable parameter (called clam_deep in the model namelist) whose default value is set to be 0.1 (Han and Pan, 2011; Han et al., 2017); q_s and q_{sb} the saturation specific humidity values at the parcel level and the cloud base, respectively; d_1 a tunable parameter of $O(10^{-4})$; RH the environmental relative humidity. Shin et al. (2022) have showed that the storm Vmax is sensitive to this parameter and the overall Vmax forecast can be improved when the c value is increased based on the previous real-time HAFS experiments conducted in the 2020–2022 hurricane seasons. They also found that the simulated storms can respond differently to changes in the entrainment rate of the SAS deep

convection scheme. Figure 9 compares the 60 h forecasts of 850-hPa radar reflectivity distributions from HAFS simulations using the c values of 0.1 (C010) and 0.13 (C013), respectively, for Hurricane Teddy initialized at 2020091600 and Hurricane Danielle initialized at 2022090300. For Hurricane Teddy, both C010 and C013 experimental runs produce well-developed strong vortices and do not produce large differences in Vmax and convective structure (Figures 9A–C). However, this is different for Hurricane Danielle simulation (Figure 9D). The storm generated by the C010 experiment exhibits a compact structure with a well-defined eyewall while the C013 experiment produces a relatively weaker and larger storm with more diffusive convective patterns (Figures 9E, F). As described in Shin et al. (2022), changing c and hence different storm environments could cause large differences in the Vmax forecast. Details about the influence of c on the Vmax forecast will be analyzed in a separate paper.

Given that increasing c appears to be beneficial for the Vmax forecast, a slightly higher c (clam_deep) value of 0.15 is adopted in the first version of operational HFSA. Figure 10 demonstrates that

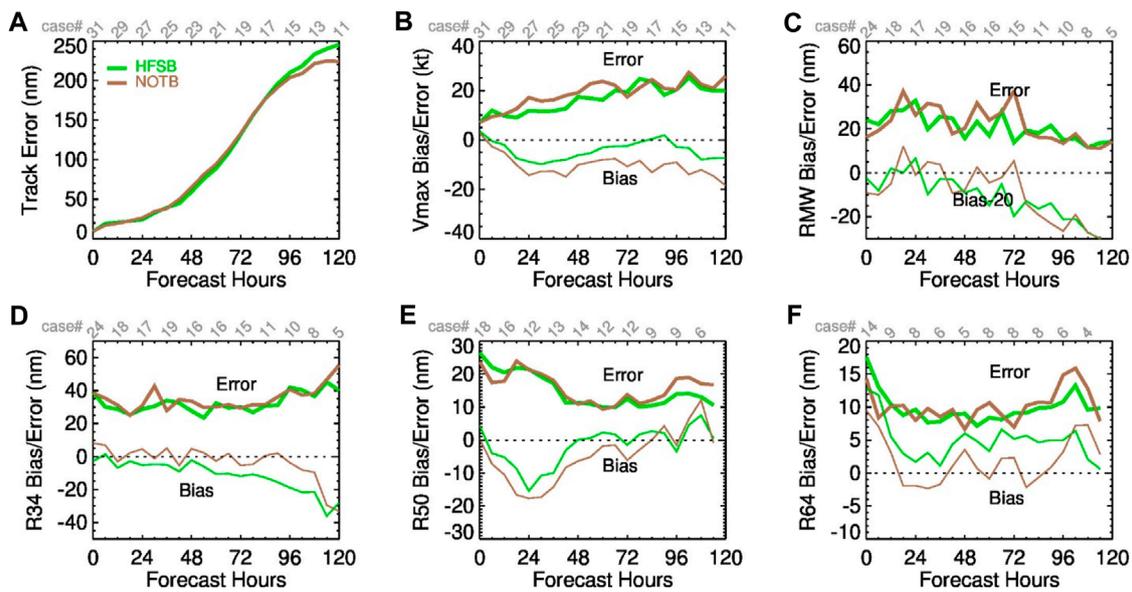


FIGURE 5 Same as Figure 3 except for HFSB and NOTB.

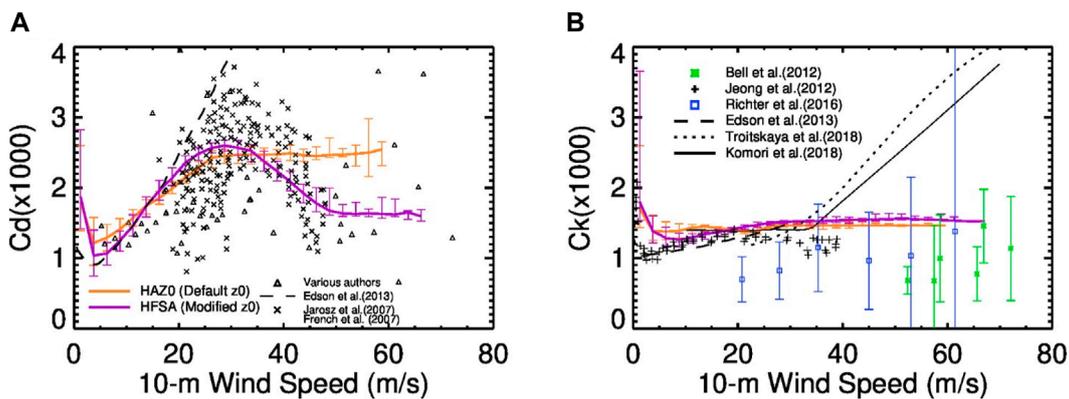


FIGURE 6 (A) Momentum drag coefficient (C_d) at 10 m as a function of 10-m wind speed used in HAFS experiments and derived from various field or laboratory studies (symbols and black line). Error bars on the purple and orange lines denote the 5th and 95th percentiles in each bin of wind speed of 2 m/s. Triangles represent C_d values from several studies (Bell et al., 2012; Holthuijsen et al., 2012; Bi et al., 2015; Potter et al., 2015; Zhao et al., 2015; Richter et al., 2016); (B) enthalpy exchange coefficient (C_k). C_d and C_k in HAFS are calculated from the HFSB and HAZO simulations of Hurricane IAN (09 L), initialized at 2022092806.

the operational version of HFSB predicts the storm V_{max} better for both strong and weak cycles in terms of RMS errors and biases when 0.15 is used instead of the default value of 0.1. Track RMS errors are also improved. The RMS errors and biases in vortex sizes are nearly unchanged except that the mean R34 of HFSB is slightly smaller than that of HAET.

3.2.4 Impact of microphysics schemes

Given the uncertainty in physics schemes, the purpose of using different microphysics schemes in HFSB and HFSB configurations is to increase the forecast diversity in addition to other differences in both configurations (Section 2). To highlight the impact of different microphysics schemes on HAFS performance, we run

HFSB with the Thompson microphysics scheme (HAMP) replacing the GFDL microphysics scheme. In the literature, numerous studies have reported that varying cloud microphysics assumptions, resulting in different thermal and dynamical effects induced by phase changes, can have major impacts on the intensity of TCs simulated by mesoscale models with different microphysics schemes (see a review paper by Tao et al. (2011), and references therein). Fovell et al. (2009) showed that TC track forecast may also be influenced by different microphysics assumptions via cloud–radiative interaction.

Figure 11 shows the statistical errors in track, V_{max} , and vortex size of TCs simulated by the HAFS model with GFDL (HFSB, purple lines) and Thompson (HAMP, red lines) microphysics

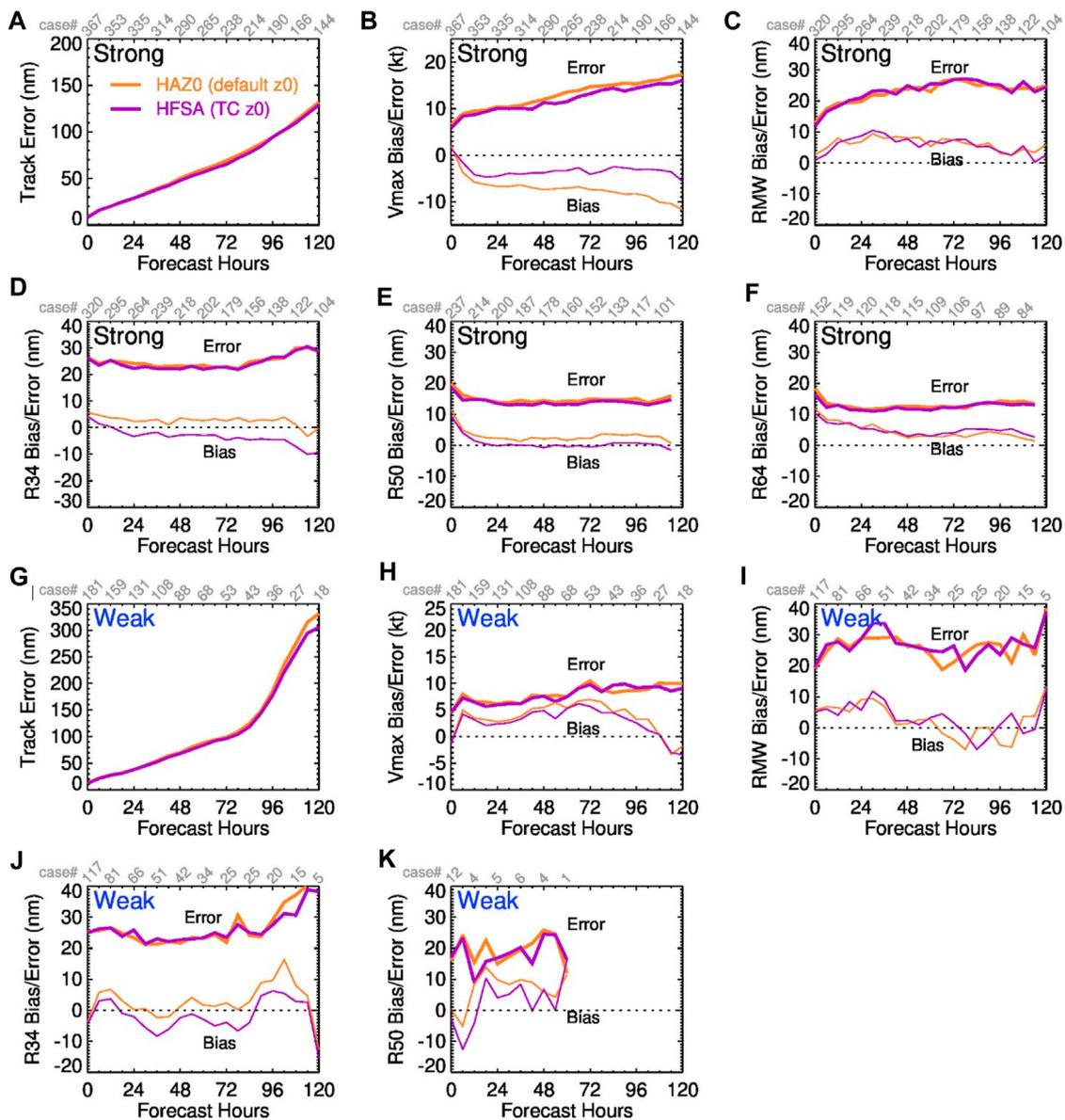


FIGURE 7

(A) Comparisons of RMS track errors for strong cycles simulated in HFSA and HAZ0 experiments, and RMS errors and biases of (B) Vmax, (C) RMW, (D) R34, (E) R50, (F) R64. (G–K) are the same as (A–E), except for weak cycles. Case count is shown in gray in the upper x-axis.

schemes. The simulations with the two microphysics schemes have noticeable impacts on track and Vmax. For strong cycles, it appears that HAMP produces larger track errors for lead times beyond 48 h than HFSA, while it produces smaller Vmax RMS errors for nearly all lead times with larger mean intensities (and smaller negative biases) within 48 h. The RMW errors and biases of HAMP are generally close to those of HFSA, except that HAMP has slightly smaller RMW errors and smaller mean RMW for the lead times beyond 72 h. The RMS errors in R34, R50, and R64 from both runs are also close, but HAMP produces smaller mean values of R34 and R50 than HFSA. The mean R64 values of HAMP are larger than those of HFSA for the lead times within 60 h, and smaller afterward. For weak cycles, HAMP has smaller track errors for nearly all lead times,

especially for the lead times beyond 84 h. The RMS errors and biases in Vmax and vortex size of HAMP are generally close to those of HFSA.

As described in Section 2, major differences in the two microphysics schemes are in the treatments of ice processes and the number concentrations of hydrometeors. In-depth comparisons of the impact of the two schemes are beyond the scope of this document. Here we only show the vertical distributions of azimuthally-averaged mixing ratios of hydrometeors from the two schemes in one cycle simulation of Hurricane Fiona (07 L) as an example to highlight differences in hydrometeors simulated by the two schemes (Figure 12). An apparent difference in the distributions of hydrometeors is that the Thompson microphysics scheme produces much more snow than the GFDL microphysics

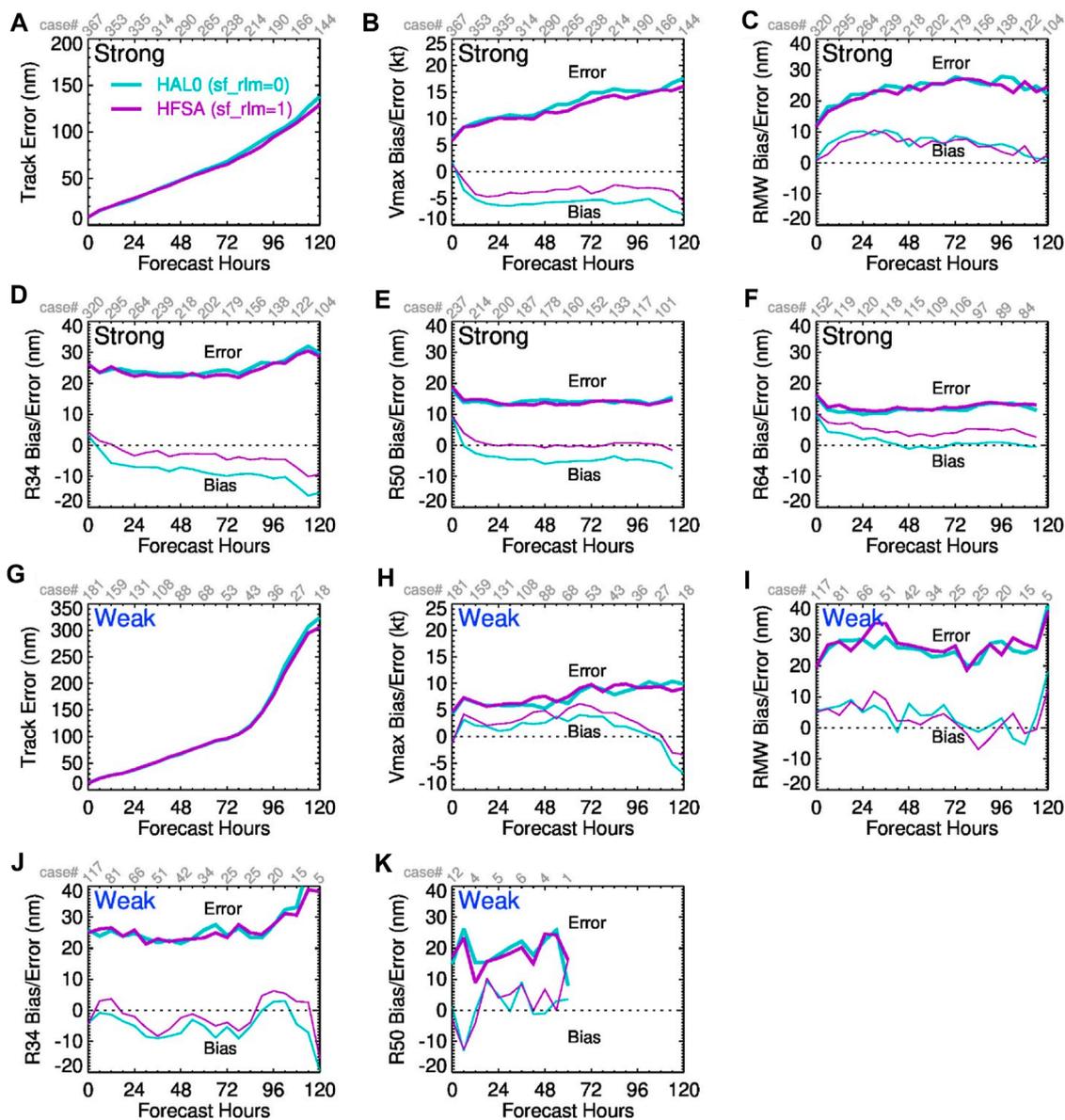


FIGURE 8
Same as Figure 7, except for HALO and HFSA to assess the impact of $sf_rlm = 1$ option.

scheme and less cloud ice and graupel, although we do not have sufficient observational data to verify those results. Different treatments of the conversion of water vapor and hydrometeors are likely to generate different condensational heating rates and cloud-radiative interactions, affecting the simulations of the Vmax and track of TCs. Some case studies also showed that using the Thompson microphysics scheme in HAFS tends to produce a slightly taller vortex than using the GFDL microphysics scheme. The Thompson scheme has notably weaker reflectivity than the GFDL microphysics scheme aloft probably due to the larger bias of snow and lack of small ice particles being lifted far above the freezing level. In addition, HAFS with the GFDL microphysics scheme has slightly higher vertical

velocity maxima aloft. For detailed analyses, see Hazelton et al. (2023b).

3.2.5 Impact of TCPBL adjustment in HFSA ($tc_pbl = 1$)

The configuration of the NOTB run is identical to that of the HFSA run except that the default PBL scheme ($tc_pbl=0$) is used in NOTB, while the TCPBL adjustment in the PBL scheme ($tc_pbl = 1$) is used in HFSA. For strong cycles, the TCPBL adjustment improves the Vmax bias by 50% (Figure 13B), despite a slight increase in track errors for lead times beyond 96 h (Figure 13A). It does not have major impacts on the RMS errors in vortex sizes (RMW, R34, R50, and R64), but results in some improvements to mean biases

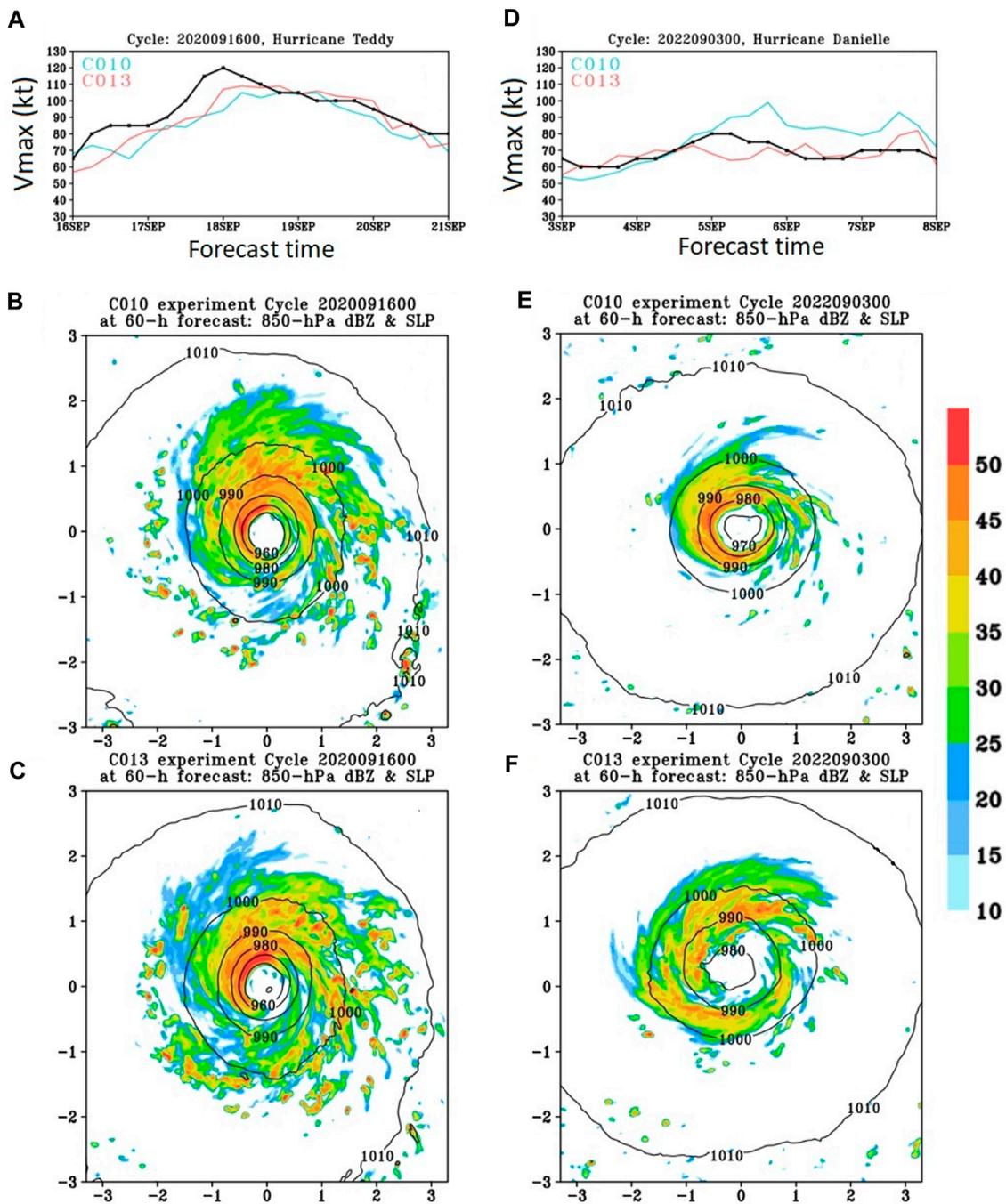


FIGURE 9
 (A) V_{max} time series from two HFSA-based experiments (cyan: C010 and red: C013) and from NHC best-track analysis (black) for the Hurricane Teddy simulation initialized at 2020091600. (B) 850-hPa radar reflectivity (shaded: dBZ) and isobar (black contours with 10-hPa interval) from the 60 h forecast of the C010 experiment for the Hurricane Teddy simulation shown in (A). (C) is the same as (B) but from the C013 experiment; (D), (E, F) are the same as (A–C), respectively, but for the Hurricane Danielle simulation initialized at cycle 2022090300. The horizontal and vertical axes are the distance (unit: degree) from the storm center in (B, C, E, F).

in RMW, R50, and R64. One noticeable impact is on the mean R34 bias, as shown in Figure 13D. Both HFSB and NOTB have negative biases in R34. Using the TCPBL adjustment increases the negative R34 bias with forecast time. This issue is primarily attributable to

the setting of turning off surface-driven mass fluxes (M_u) where the surface stability parameter is greater than -0.5 (Chen and Marks, 2024). The objective of this setting is to retain M_u only in convective boundary layers, as M_u essentially represents buoyant

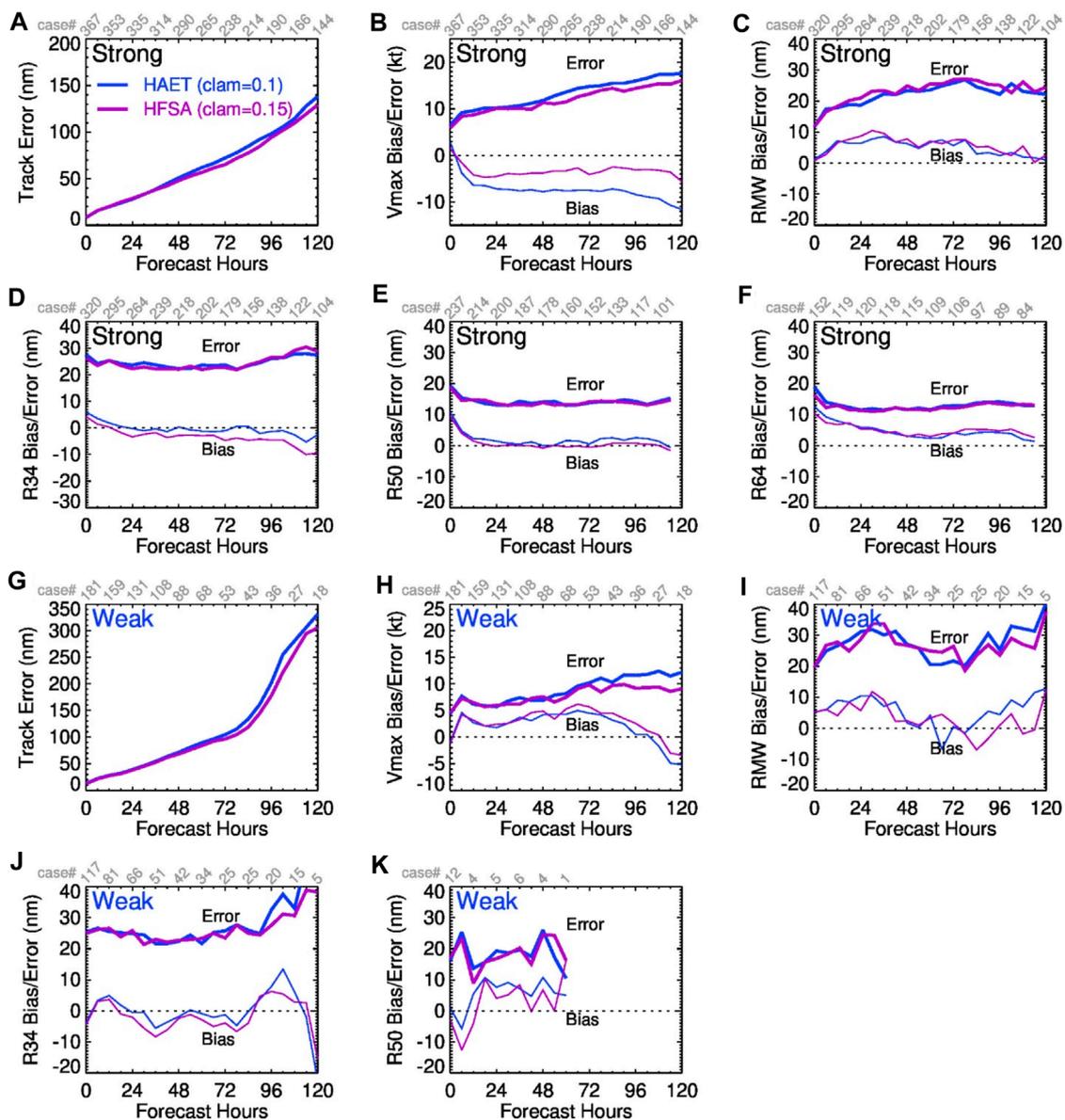


FIGURE 10 Same as Figure 7, except for HAET ($\text{clam_deep} = 0.1$) and HFSA ($\text{clam_deep} = 0.15$) to assess the impact of the increased entertainment rate.

thermal plumes in convective boundary layers. Exploring a suitable threshold of surface stability parameter differentiating buoyancy-driven and shear-driven boundary layers is currently underway. For weak cycles, the impact of the TCPBL adjustment is small as expected, except that track errors are increased for the lead times beyond 72 h.

Other testing has also shown that the TCPBL adjustment improves the simulated structure of TCs in HAFS (Chen et al., 2022; Chen et al., 2023). An examination of the relative impacts of TCPBL adjustment and the Thompson microphysics scheme in HFSB retrospective forecasts has also demonstrated that the TCPBL adjustment was critical to the improved detection of RI in HFSB (Hazelton et al., 2023a; Hazelton et al., 2023b). Composite structures have shown that the TCPBL adjustment increases the boundary layer inflow strength, leading to more compact and

robust vortices that spin up more quickly (Hazelton et al., 2023a; Hazelton et al., 2023b).

3.3 Pressure-wind relation

Numerous early investigations have shown that the V_{max} of a TC is closely related to its minimum central pressure (e.g., Holland, 2008 and references therein), called pressure-wind relation. Near the TC center, the horizontal pressure gradient and centrifugal forces are approximately balanced. The pressure-wind relation is a useful metric to evaluate the model performance. Figure 14 presents the fitted pressure-wind relationships from all the experiments and the best-track analysis, respectively. It is seen that all HAFS experiments generally produce a weaker V_{max} than the best-track analysis does

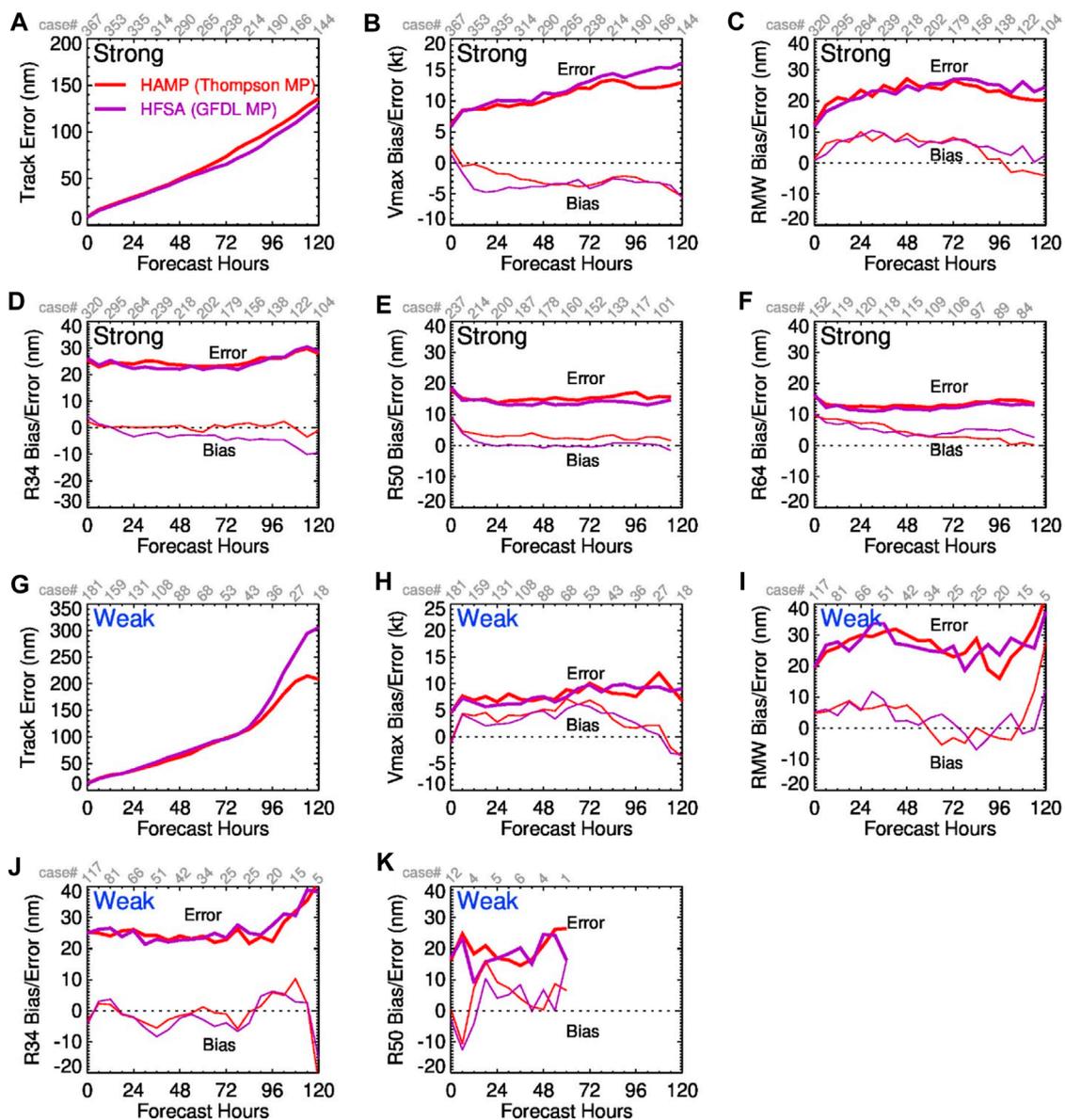


FIGURE 11
Same as Figure 7, except for HAMP and HFSA to assess the impact of different microphysics schemes.

under a given central pressure. This is consistent with the general negative biases in V_{max} of HAFS runs as shown in Section 3.2. In the HFSA-based experiments, using the Thompson microphysics scheme (HAMP) and the modified mixing length near the surface (HAL0) do not significantly change the pressure-wind relation, as compared with that of HFSA. However, using the modified roughness length and increased entrainment rate can noticeably improve the pressure-wind relation for intensities stronger than 80 kt, with an increased V_{max} at a given central pressure lower than 960 hPa, respectively (HFSA vs. HAZ0, and HFSA vs. HAET). For intensities weaker than 80 kt, all experimental runs produce nearly the same pressure-wind relation. In the HFSB-based experiment, the TCPBL adjustment in the PBL scheme (HFSB) improves the

pressure-wind relation, compared with that without the adjustment (NOTB). Specifically, the TCPBL allows greater V_{max} at a given central pressure when the central pressure is lower than 980 hPa (or for V_{max} stronger than 60 kt).

3.4 RI analysis

The probability of detection (POD) index of the observed RI events and false alarm ratio (FAR) index of the forecasted RI events are used to characterize the model performance in predicting RI events. We calculated POD and FAR indices for the observed and forecasted RI events, respectively, by aggregating the forecasts at all

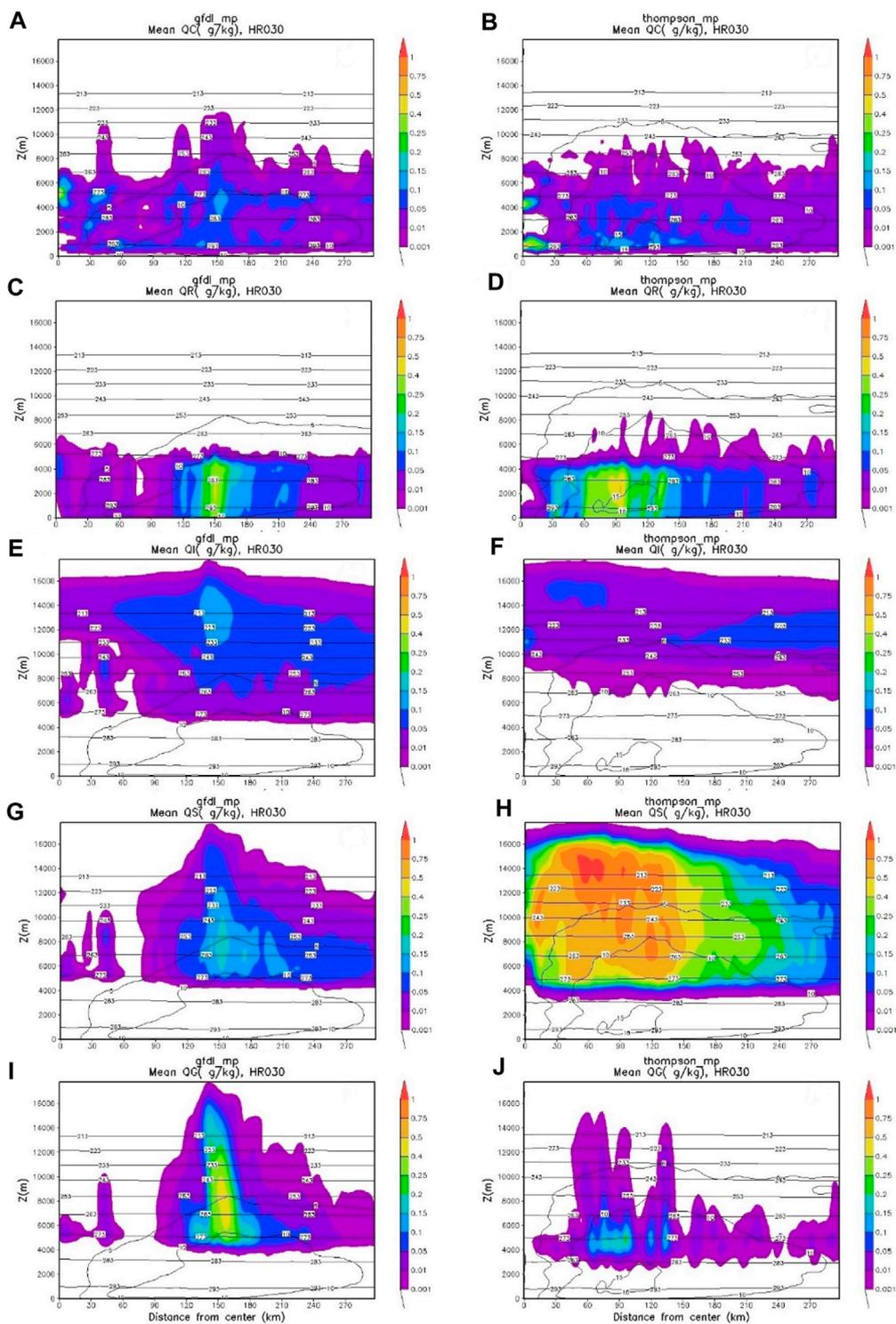


FIGURE 12 Vertical distributions of azimuthally-averaged mixing ratios (g/kg) of hydrometeors at the forecast time of 30 h for Hurricane Fiona (07 L) simulated by HAFS using the GFDL (left column) and Thompson (right column) microphysics schemes with the same initial conditions at 2022092106. (A,B) liquid cloud, (C,D) rain, (E,F) cloud ice, (G,H) snow, and (I,J) graupel. Horizontal lines are the contours of temperature (K) and curved lines are the contours of tangential winds.

lead times of all cycles in each experiment. **Figure 15A** shows the performance diagram summarizing POD, success ratio (SR = 1 - FAR), and critical success index (CSI, also known as threat score)

of each experiment. The POD values of all HAFS experiments are smaller than their respective SR values, although both POD and SR are not high. Compared with HAZ0, using the modified

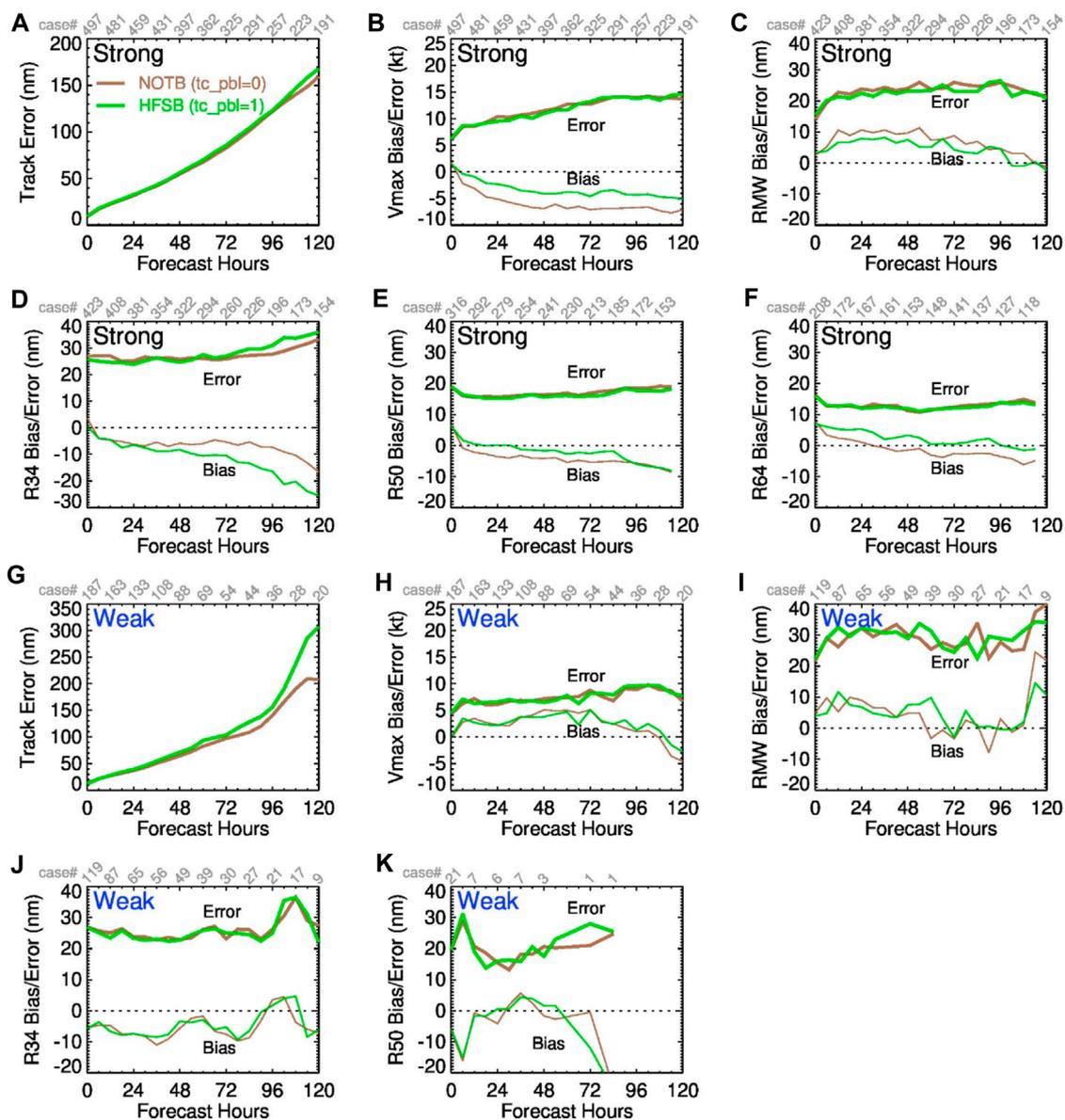


FIGURE 13 Same as Figure 7, except for NOTB and HFSB to assess the impact of $tc_pbl=1$ option in HFSB.

roughness lengths in HFSB increases POD by 15% and reduces FAR by 5%. Likewise, the increased entrainment rate leads to an increased POD by 12% and a reduced FAR by 3% (HAET vs. HFSB). Adjusting the near-surface mixing length increases POD by 9% without increasing FAR (HAL0 vs. HFSB). Using the Thompson microphysics scheme in HFSB further increases POD by 7% and reduces FAR by 14% (HAMP vs. HFSB), improving FAR more than POD. In the HFSB-based experiment, using the TCPBL adjustment increases POD by 8% without increasing FAR (NOTB vs. HFSB). All TC-specific modifications increase POD and reduce or do not increase FAR in both HFSB and HFSB; this improves the CSI values of RI forecasts. The improvement of POD is more noticeable than that of FAR. Nevertheless, the POD is

still low for both HFSB and HFSB; this needs to be addressed in future upgrades.

In addition, we analyzed POD and FAR during each single 5-day forecast period, referred to as POD5 and FAR5, respectively, to assess the performance of RI forecasts of each cycle (Wang et al., 2023c). A forecast cycle is thought to successfully detect the observed RI events if POD5 is larger than 0.5, and falsely predicts RI events if FAR5 is larger than 0.5. Figures 15B, C show the percentages of the cycles successfully detecting the observed RI events and falsely predicting RI events during 5-day forecasts in each experiment. All TC-specific modifications do improve the ratio of the cycles successfully detecting the observed RI events. They also slightly reduce the ratio of the cycles falsely predicting RI events except

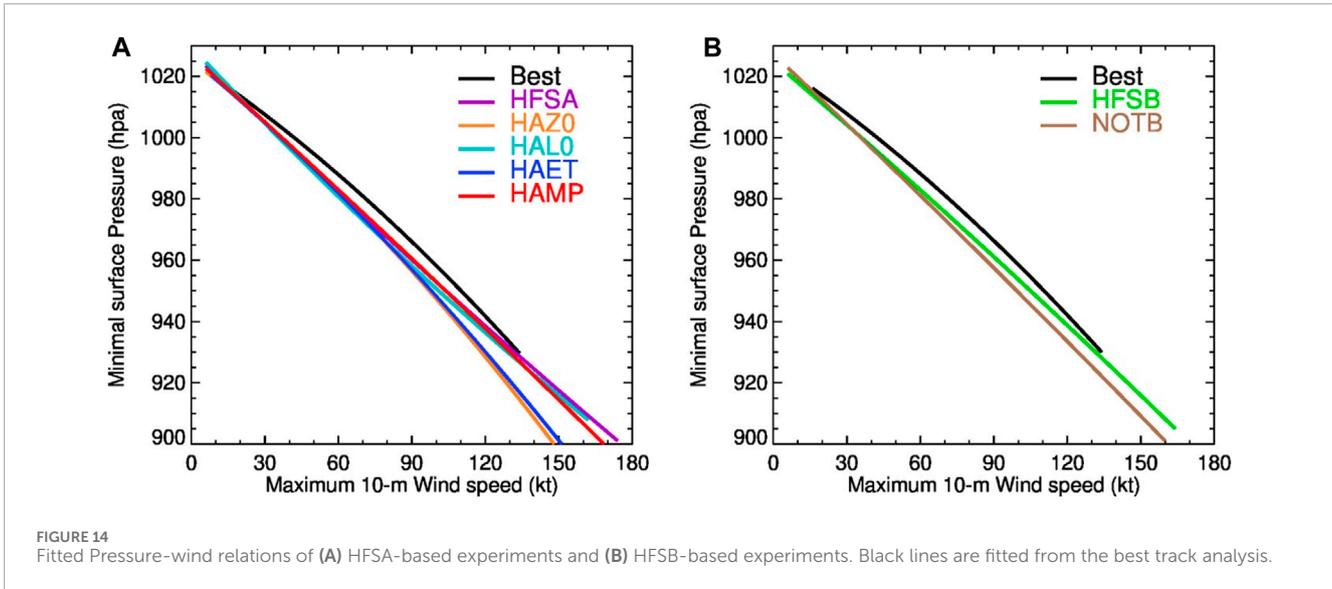


FIGURE 14 Fitted Pressure-wind relations of (A) HFS-based experiments and (B) HFSB-based experiments. Black lines are fitted from the best track analysis.

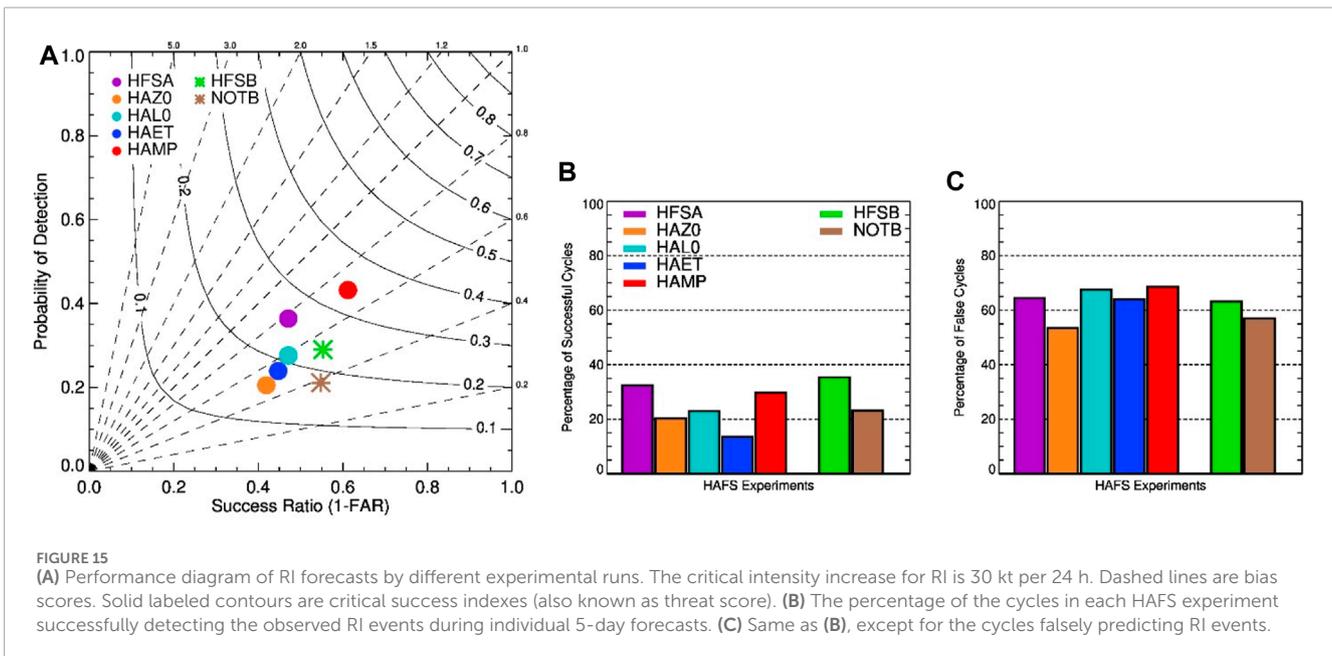


FIGURE 15 (A) Performance diagram of RI forecasts by different experimental runs. The critical intensity increase for RI is 30 kt per 24 h. Dashed lines are bias scores. Solid labeled contours are critical success indexes (also known as threat score). (B) The percentage of the cycles in each HAFS experiment successfully detecting the observed RI events during individual 5-day forecasts. (C) Same as (B), except for the cycles falsely predicting RI events.

for the modified roughness lengths and the TCPBL adjustment increasing the number of false RI prediction cycles. Comparing HAMP with HFSA, using the Thompson microphysics scheme slightly decreases the percentage of successful cycles and increases the percentage of false cycles.

4 Challenges and future plan

Future HAFS upgrades focus mainly on increasing the diversity between HFSA and HFSB, improving the forecasts of rapid changes in intensity, particularly for NATL basin, reducing intensity forecast errors at long lead times, and improving vortex structure forecasts. Both HFSA and HFSB are capable of forecasting rapid changes in Vmax, but they still suffer from high biases in Vmax, false

prediction of RI, underpredicting Vmax changes, and the timing of onset of rapid intensity changes. These forecasting challenges also remain for other regional dynamic models as summarized by Zhang et al. (2023). These are one of the major challenges for the further development of HAFS. For example, both HFSA and HFSB predicted RI of hurricane Lee (13 L) 12–24 h later than the best-track analysis for the cycles initialized earlier than 2023090706, and struggled to predict rapid weakening after the intensification period. This led to large intensity errors and biases for lead times beyond 24 h, resulting in underperformance compared to the legacy HWRF model. Although the reasons for the underperforming forecast of rapid intensity changes are not clear yet, preliminary experimental studies suggested that it could be related to model dynamics and physics (Liu et al., 2023; Zhang and Zhang, 2023). Another challenge is to improve the

structure of the forecasted vortex. As shown in Figure 1, RMW errors and biases of HAFS are still larger than those of the legacy HWRF.

To further improve physics schemes in the operational HAFS, we will continue to explore the upgraded physics schemes for NCEP GFS in TC simulations using HAFS, including the improved PBL and convection schemes in strong shear environment conditions (Han et al., 2021; Han et al., 2024) as well as the next version of the GFDL microphysics scheme. Given the critical role of the PBL in TC forecasts, the MYNN-EDMF PBL scheme (Olson et al., 2019), which has been extensively tested in the regional Rapid Refresh Forecast System at NCEP and can be well performed in simulating hurricane boundary layers (Chen and Bryan, 2021; Chen, 2022), is also worth testing in HAFS with some modifications for strong wind conditions. Despite the high horizontal resolution used in HAFS, convection schemes still play an important role in modulating both intensity and track of TCs in HAFS. Therefore, other convection schemes such as Tiedtke cumulus scheme (Tiedtke, 1989) and Grell-Freitas scheme (Freitas et al., 2021) are being tested in HAFS. Other upgrade plans include the use of NOAA-MP (Niu et al., 2011) in HAFS, testing different options in the advection scheme, and testing the physics-dynamics interaction.

Research efforts should be made to further improve the capability of a single physics scheme applied to multiple scales, i.e., scale-awareness, and to test model parameters such as the entrainment rate in convection schemes and diffusivity in PBL schemes as well as different treatments of microphysical processes for TC scenarios. It is worth mentioning that the entrainment rate is an important parameter in convection schemes and has noticeable impacts on TC intensity forecasts as shown in Section 3.2.3. There are many studies on how to improve the entrainment parameterization (e.g., Zhang et al., 2016; Xu et al., 2021; Villalba-Pradas and Tapiador, 2022). It is warranted to test the impact of different entrainment rate parameterizations on TC forecasts of HAFS. In addition, the role of microphysical processes in TC simulations should be further investigated, given that the performance of HAFS is sensitive to microphysics schemes it chooses. It is beneficial for HAFS to test the sensitivity of TC simulations in HAFS to different treatments of microphysical processes such as mixing evaporation and autoconversion processes and their relationships (Liu et al., 2023; Lu et al., 2023).

5 Summary

This paper describes the physics schemes used in the first version of operational HAFS. The physics schemes are the same as those used in NCEP GFS version 16, with the exception of four TC-specific modifications and a different microphysics scheme in one of the two HAFSv1 configurations. The four modifications include (1) the observation-based sea-surface roughness lengths, (2) increased near-surface mixing length in the PBL, (3) increased entrainment rate in the SAS deep convection scheme, and (4) adjustments for TC PBL including reduced maximum allowable mixing length, the adjusted two coefficients in the eddy viscosity and TKE dissipation term, and tapering nonlocal mass fluxes in high-wind conditions. Experiments show that all of the modifications improve Vmax

forecasts, particularly for mean Vmax biases of strong cycles, without degrading track forecasts. The modifications have nearly negligible impacts on RMS errors in R34, R50, and R64, but have noticeable impacts on mean biases, with the largest impact on mean R34 bias. RMW errors and biases are not affected by the modifications. All modifications improve the POD of the observed RI events and FAR of the forecast RI events. The improvement of the POD is larger than that of the FAR, although the POD is still low and the FAR is still high. The use of the Thompson microphysics scheme in one HAFSv1 configuration was originally intended to increase the diversity of HAFS forecasts between the two configurations. However, the experiment indicates that using the Thompson microphysics scheme can greatly improve HFSA intensity forecasts for both strong and weak cycles as well as POD and FAR of RI forecasts.

In addition to the analyses of track and intensity as presented in this paper, it is worth further investigating the impact of physics schemes and their modifications on the structure of TCs simulated by HAFS. This is needed to identify issues common for all models or specific to HAFS. Priority issues to be addressed include the over prediction of intensity in low shear environment, RI onset timing, large cycle-to-cycle variability, and other common issues of regional dynamic models identified by forecasters (Wang et al., 2023b; Zhang et al., 2023). Future work on the HAFS physics package includes:

- (1) Testing the upgraded GFS physics schemes in HAFS configurations and making adjustments if necessary.
- (2) Exploring other existing PBL and convection schemes in UFS suitable for TC simulations.
- (3) Developing new modifications or schemes tailored to HAFS based on research efforts such as improving scale-awareness and sensitivities of HAFS simulations to model parameters (e.g., entrainment rate, diffusivity, and others) and to different treatments of microphysical processes.

Data availability statement

The raw data supporting the conclusion of this article will be made available by the authors, without undue reservation.

Author contributions

WW: Conceptualization, Formal Analysis, Investigation, Methodology, Visualization, Writing–original draft, Writing–review and editing. JH: Conceptualization, Writing–original draft, Writing–review and editing. JuS: Conceptualization, Formal Analysis, Investigation, Writing–original draft, Writing–review and editing. XC: Conceptualization, Formal Analysis, Investigation, Writing–original draft, Writing–review and editing. AH: Formal Analysis, Investigation, Methodology, Writing–original draft, Writing–review and editing. LZ: Formal Analysis, Investigation, Writing–original draft, Writing–review and editing. H-SK: Investigation, Methodology, Writing–original draft, Writing–review and editing. XL: Investigation, Writing–original draft, Writing–review and editing. BL: Formal

Analysis, Investigation, Methodology, Writing—original draft, Writing—review and editing. QL: Formal Analysis, Investigation, Writing—original draft, Writing—review and editing. JoS: Investigation, Writing—original draft, Writing—review and editing. RS: Investigation, Writing—original draft, Writing—review and editing. WZ: Formal Analysis, Investigation, Writing—original draft, Writing—review and editing. ZZ: Conceptualization, Formal Analysis, Funding acquisition, Investigation, Methodology, Project administration, Resources, Supervision, Writing—original draft, Writing—review and editing. FY: Conceptualization, Formal Analysis, Funding acquisition, Investigation, Methodology, Project administration, Resources, Supervision, Writing—review and editing, Writing—original draft.

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