

Reliability Evaluation Method of AC/ DC Hybrid Distribution Network Considering Voltage Source Converter Restoration Capability and Network Reconfiguration

Lu Zhang¹, Shunjiang Yu¹, Yongxiang Cai², Wei Tang¹* and Hongkai Cheng¹

¹College of Information and Electrical Engineering, China Agricultural University, Beijing, China, ²Electric Power Research Institute of Guizhou Power Grid Co., Ltd., Guiyang, China

In the AC/DC hybrid distribution network, non-faulty areas can maintain uninterrupted power supply by adjusting the control mode of the voltage source converter (VSC) after a fault. In addition, the non-faulty areas can also be restored through network reconfiguration. To account for the impact of these two restoration methods on reliability accurately, this article proposed a reliability evaluation method for the AC/DC hybrid distribution network considering VSC restoration capability and network reconfiguration. First, a restoration optimization model of the AC/DC hybrid distribution network considering network reconfiguration and control modes of VSC is established, which can give full play to these two restoration methods while ensuring the radial constraints of the network. Then, the failure mode and effects analysis (FMEA) method is introduced and combined with the restoration optimization model to analyze the impact caused by faults on the network. Among them, the FMEA method is utilized to determine the network topology after fault isolation, and on this basis, the restoration optimization model is solved to obtain the outage time of loads in the network. Finally, the aforementioned work is combined with the sequential Monte Carlo method to evaluate the reliability of the AC/DC hybrid distribution network to adequately simulate the fluctuation characteristics of distributed generation (DG) and load. The case study shows that the proposed method can accurately evaluate the reliability of the AC/DC hybrid distribution network.

Keywords: reliability evaluation, AC/DC hybrid distribution network, VSC restoration capability, network reconfiguration, restoration optimization model, failure mode and effects analysis, sequential Monte Carlo method

1 INTRODUCTION

With the continuous development of the DC distribution technology and the large-scale access to DC equipment such as distributed generation (DG) and electric vehicles, the AC/DC hybrid distribution network has become the development trend of the distribution network in the future (Eajal et al., 2016; Zhang et al., 2019; Xu et al., 2021; Wei et al., 2022). Reliability is the first factor to be considered in power grid construction; therefore, it is of great significance to evaluate the reliability of the AC/DC hybrid distribution network (Zhang et al., 2022).

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> *Correspondence: Wei Tang wei_tang@cau.edu.cn

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During reliability evaluation, the restoration capacity of the distribution network needs to be fully considered in order to accurately analyze the outage time of load caused by the fault of components in the network. In the AC/DC hybrid distribution network, due to voltage source converter's (VSC's) ability of low voltage ride through (LVRT) and fast control mode switching, the non-fault area can maintain uninterrupted power supply by adjusting the VSC control mode after a fault (Liu et al., 2021). In addition, the AC/DC hybrid distribution network contains a large number of contact lines, so the non-fault area can also be restored through network reconfiguration with the assistance of local resources such as DG. In order to accurately evaluate the reliability of the AC/DC hybrid distribution network, the VSC restoration capability and network reconfiguration need to be fully accounted for.

The current research on the reliability of the AC/DC power grid is mainly focused on transmission networks (Wang et al., 2017; Li et al., 2018; Guo et al., 2020), while less research has been conducted on distribution networks. In Ghadiri et al. (2014), several structures of the AC/DC hybrid distribution network are proposed, and the simulation-based single fault analysis method is used to evaluate their reliabilities. In Zhao et al. (2019), the sequential Monte Carlo method is combined with the minimum path method to evaluate the reliability of the AC/DC hybrid distribution network. However, the aforementioned two references do not take into account the impact of VSC restoration capability on reliability, which will lead to a lowreliability evaluation result of the AC/DC hybrid distribution network.

In response to this problem, some researchers (Cui et al., 2019; Wei et al., 2019; Wu et al., 2020) propose new fault impact analysis methods considering VSC restoration capability and evaluate the reliability of the AC/DC hybrid distribution network based on the Monte Carlo method. In Wu et al. (2020), the minimum path method is combined with power flow verification to analyze the impact of faults on the network. The failure mode and effects analysis (FMEA) method is combined with power flow verification to analyze the impact of faults on the network in Cui et al. (2019). In Wei et al. (2019), VSC control modes are modeled under different faults, and an optimal load shedding model is proposed considering the optimization of VSC parameters to analyze the impact of faults on the network. However, the aforementioned studies do not consider the impact of network reconfiguration on reliability. For the AC/DC hybrid distribution network with contact lines, the reliability results evaluated by the aforementioned methods are lower than the actual value.

In the existing studies, mostly optimization models are adopted to account for the impact of network reconfiguration on the reliability of the distribution network. In Li et al. (2020a), a distribution network reliability evaluation method based on an optimization model is proposed, fully considering detailed placement and actions of circuit breaker (CB) and switch. In Li et al. (2020b), an analytical distribution network reliability evaluation method is proposed which considers the optimal network reconfiguration strategy. An optimization model is proposed to improve the reliability of the distribution network



by optimizing feeder reconfiguration and DG placement in Tian et al. (2016). However, the research objects of the aforementioned studies are all AC distribution networks, which means that VSC restoration capability is not taken into account. In Cheng et al. (2016), the restoration capability of multi-terminal DC interconnection (MTDI) is explained, and the FMEA method is combined with the restoration optimization model considering network reconfiguration to evaluate the reliability of the AC distribution network with MTDI. However, it does not consider the operating states and constraints of DC networks. When applied to the AC/DC hybrid distribution network, it not only fails to adequately account for the impact of VSC restoration capability on reliability but also may lead to unsafe operating states of the network, which in turn leads to errors in the results of reliability evaluation.

As mentioned earlier, how to take into account the impact of VSC restoration capability and network reconfiguration on reliability so as to obtain reasonable and accurate reliability evaluation results is a problem to be solved. Aiming at this issue, this article had proposed a reliability evaluation method for the AC/DC hybrid distribution network considering VSC restoration capability and network reconfiguration. The main contributions of this study are summarized as follows:

- We established a restoration optimization model of the AC/ DC hybrid distribution network considering network reconfiguration and control modes of VSC, which can completely utilize the aforementioned two restoration methods while ensuring the radial constraints of the network.
- 2) A reliability evaluation method combining the FMEA method, restoration optimization model, and sequential Monte Carlo method is proposed. The FMEA method is utilized to determine the network topology after fault isolation, and on this basis, the restoration optimization model is solved to obtain the outage time of loads in the network. The aforementioned work is combined with the sequential Monte Carlo method to evaluate the reliability of the AC/DC hybrid distribution network to adequately simulate the fluctuation characteristics of DG and load.



2 OVERALL FRAMEWORK OF THE RELIABILITY EVALUATION METHOD OF AC/DC HYBRID DISTRIBUTION NETWORK

2.1 Operation Mode and Restoration Method of AC/DC Hybrid Distribution Network

The typical hand-in-hand AC/DC hybrid distribution network is shown in **Figure 1**, where the DC and AC networks are connected through the VSC. The VSC has two controllable operating parameters. According to the different control parameters, the three most typical control modes of the VSC are as follows (Eajal et al., 2016; Wei et al., 2019):

- 1) DC voltage and reactive power control $(U_{dc}Q)$;
- 2) Active and reactive power control (PQ);
- 3) AC voltage and phase angle control $(U_{ac}\theta)$.

Under normal operation, multiple VSCs in the DC network are coordinated by master–slave control. One VSC works in $U_{dc}Q$ control to provide voltage support for the DC network, while the remaining VSCs work in the PQ control to improve power flow distribution (Wang et al., 2020). After a fault, due to VSC's ability of LVRT and fast control mode switching, the non-fault area can maintain uninterrupted power supply by adjusting the VSC control mode (Liu et al., 2021). In addition, since the AC/DC hybrid distribution network contains more contact lines and accesses a large number of DGs, the non-fault area can also be restored by network reconfiguration with the assistance of local resources such as DGs.

Therefore, in order to accurately evaluate the reliability of the AC/DC hybrid distribution network, it is necessary to fully take into account the impact of VSC restoration capability and network reconfiguration on reliability. Aiming at this problem, this study proposes a reliability evaluation method for the AC/ DC hybrid distribution network combining the FMEA method, restoration optimization model, and sequential Monte Carlo method, which can account for the impact of VSC restoration capability and network reconfiguration on reliability and simulate the fluctuation characteristics of DG and load.

2.2 Overall Framework of the Reliability Evaluation Method

The overall framework of the reliability evaluation method proposed in this study is shown in **Figure 2**. First, the fault component is sampled using the sequential Monte Carlo method. Then, according to the location of the fault and the placements of protection devices, the FMEA method is used to divide the network into four types of areas with different degrees of impact from the fault, and further obtain the network topology after fault isolation. On the basis, the restoration optimization model with the objective of maximizing restored loads is solved to yield the outage time and outage times of the load in the network. The specific evaluation process is described in **Section 5**.

3 RESTORATION OPTIMIZATION MODEL OF AC/DC HYBRID DISTRIBUTION NETWORK

3.1 Objective

The sub-objective f_1 is to maximize the weighted restored loads in the process of fault repair. The sub-objective f_2 is used to minimize the network losses in the process of fault repair, including the AC and DC network losses, then

$$maxf_1 = \sum_{\forall t} \sum_{\forall i \in N} \omega_i \rho_{i,t} P_{i,t}^L, \qquad (1)$$

$$\min f_2 = \sum_{\forall t} \left(\sum_{\forall ij \in B^{AC}} I_{2,ij,t} R_{ij} + \sum_{\forall ij \in B^{DC}} I_{2,ij,t} R_{ij} \right),$$
(2)

where *N* is the set of all nodes in the AC/DC hybrid distribution network. B^{AC} and B^{DC} are the sets of AC and DC lines in the AC/ DC hybrid distribution network, respectively; ω_i is the weight of the load at node *i*. $\rho_{i,t}$ indicates whether the load at node *i* is restored at time *t*. If the load at node *i* is restored, $\rho_{i,t} = 1$; otherwise, $\rho_{i,t} = 0$. $P_{i,t}^L$ is the active power consumed by the load at node *i* at time *t*. $I_{2,ij,t}$ is the squared current from node *i* to node *j* at time *t*. R_{ij} is the resistance of line *ij*.

The setting weight method is used to realize the transformation from a multi-objective function to a

single-objective function. The objective function can be transformed into

$$minF = -\lambda_1 f_1 + \lambda_2 f_2, \qquad (3)$$

where λ_1 and λ_2 are the weight coefficients.

3.2 Topology Constraints of AC/DC Hybrid Distribution Network

The topology constraints are developed to coordinate network reconfiguration and control modes of VSC to ensure the radial constraints of the network during the restoration process, they also include topology constraints of the DC network and AC network.

3.2.1 Topology Constraints of DC Network

$$\boldsymbol{\beta}_{ii,t} + \boldsymbol{\beta}_{ii,t} = \boldsymbol{u}_{ij,t}, \; \forall \boldsymbol{ij} \in \boldsymbol{B}^{DC}, \tag{4}$$

$$\sum_{i \in N^{DC}} \beta_{ij,t} \leq 1, \ \forall j \in N^{DC} \setminus \left(N^{DC}_{mVSC} \cup N^{DC}_{sVSC} \cup N^{DC}_{DG} \right), \tag{5}$$

$$\sum_{i \in N^{DC}} \boldsymbol{\beta}_{ij,t} = \mathbf{0}, \ \forall j \in N^{DC}_{mVSC},$$
(6)

$$\sum_{i \in N^{DC}} \beta_{ij,t} \le 1, \ \forall j \in N^{DC}_{sVSC} \cup N^{DC}_{DG},$$
(7)

where B^{DC} , N^{DC} , N^{DC}_{mVSC} , N^{DC}_{sVSC} , and N^{DC}_{DG} are the sets of lines, nodes, master VSC node, slave VSC nodes, and DG nodes in the DC network, respectively. $u_{ij,t}$ indicates the connection state of line *ij* at time *t*. If line *ij* is connected at time *t*, $u_{ij,t} = 1$; otherwise, $u_{ij,t} = 0$. $\beta_{ij,t}$ indicates the relationship between nodes *i* and *j* at time *t*. If node *i* is the parent node of node *j* at time *t*, $\beta_{ij,t} = 1$; otherwise, $\beta_{ij,t} = 0$. Constraint (**Eq. 4**) indicates the relation between $u_{ij,t}$ and $\beta_{ij,t}$. Constraint (**Eq. 5**) indicates that the ordinary load node has at most one parent node. Constraint (**Eq. 6**) indicates that since the master VSC at node *j* controls the DC voltage, node *j* has no parent node, that is, $\sum \beta_{ij,t} = 0$. Constraint (**Eq. 7**) indicates that if the slave VSC or DG at node *j* controls the DC voltage, node *j* will have no parent node, that is, $\sum \beta_{ij,t} = 0$; if the slave VSC or DG at node *j* only controls the active power, node *j* will have one parent node, that is, $\sum \beta_{ij,t} = 1$.

3.2.2 Topology Constraints of the AC Network

$$\boldsymbol{\beta}_{ij,t} + \boldsymbol{\beta}_{ji,t} = \boldsymbol{u}_{ij,t}, \ \forall ij \in \boldsymbol{B}^{AC},$$
(8)

$$\sum_{i \in N^{AC}} \beta_{ij,t} \le 1, \ \forall j \in N^{AC} \setminus \left(N^{AC}_{Sub} \cup N^{AC}_{VSC} \cup N^{AC}_{DG} \right), \tag{9}$$

$$\sum_{i\in N^{AC}} \boldsymbol{\beta}_{ij,t} = 0, \; \forall j \in N^{AC}_{Sub}, \tag{10}$$

$$\sum_{i \in N^{AC}} \beta_{ij,t} \le 1, \ \forall j \in N^{AC}_{VSC} \cup N^{AC}_{DG},$$
(11)

where B^{AC} , N^{AC} , N^{AC}_{Sub} , N^{AC}_{VSC} , and N^{AC}_{DG} are the sets of lines, nodes, substation node, VSC nodes, and DG nodes in the AC network,

respectively. Constraint (**Eqs 8, 9**) are essentially the same as constraint (**Eqs 4, 5**), respectively. Constraint (**Eq. 10**) indicates that since the substation at node *j* controls the AC voltage, node *j* has no parent node, that is, $\sum \beta_{ij,t} = 0$. Constraint (**Eq. 11**) indicates that if the VSC or DG at node *j* controls the AC voltage, node *j* will have no parent node, that is, $\sum \beta_{ij,t} = 0$; if the VSC or DG at node *j* only controls active power, node *j* will have one parent node, that is, $\sum \beta_{ij,t} = 1$.

3.3 Power Flow Constraints of AC/DC Hybrid Distribution Network

3.3.1 Power Balance and Capacity Constraints of Voltage Source Converters

$$P_{i,t}^{VSC} + P_{j,t}^{VSC} = 0, \forall ij \in B^{VSC}, i \in N^{AC}, j \in N^{DC},$$
(12)
$$\sqrt{\left(P_{i,t}^{VSC}\right)^2 + \left(Q_{i,t}^{VSC}\right)^2} \le u_{ij,t}S_{ij}^{VSC}, \forall ij \in B^{VSC}, i \in N^{AC}, j \in N^{DC},$$
(13)

where B^{VSC} is the set of lines with VSC. $P_{i,t}^{VSC}$ and $Q_{i,t}^{VSC}$ are the active power and reactive power injected by the VSC in line *ij* to AC node *i* at time *t*, respectively. $P_{j,t}^{VSC}$ is the active power injected by the VSC in line *ij* to DC node *j* at time *t*. S_{ij}^{VSC} is the capacity of the VSC in line *ij*.

3.3.2 Power Flow Constraints of the AC Network

$$\begin{cases} \sum_{ik\in B^{AC}} P_{ik,t} = \sum_{ji\in B^{AC}} \left(P_{ji,t} - R_{ji}I_{2,ji,t} \right) + P_{i,t}, \\ \sum_{ik\in B^{AC}} Q_{ik,t} = \sum_{ji\in B^{AC}} \left(Q_{ji,t} - X_{ji}I_{2,ji,t} \right) + Q_{i,t}, \forall i \in N^{AC}, \end{cases}$$
(14)

$$\begin{cases} P_{i,t} = P_{i,t}^{DG} + P_{i,t}^{YSC} - \rho_{i,t} P_{i,t}^{L} \\ Q_{i,t} = Q_{i,t}^{DG} + Q_{i,t}^{YSC} - \rho_{i,t} Q_{i,t}^{L}, \forall i \in N^{AC}, \\ \end{cases}$$
(15)

$$-M(1-u_{ij,t}) \leq U_{2,i,t} - U_{2,j,t} - 2(R_{ij}P_{ij,t} + X_{ij}Q_{ij,t}) + (R_{ij}^2 + X_{ij}^2)I_{2,ij,t} \leq M(1-u_{ij,t}), \forall ij \in B^{AC},$$
(16)

$$I_{2,ij,t} = \frac{\left(P_{ij,t}\right)^2 + \left(Q_{ij,t}\right)^2}{U_{2,i,t}}, \forall ij \in B^{AC},$$
(17)

where X_{ij} is the reactance of line *ij*. $P_{ij,t}$ and $Q_{ij,t}$ are the active power and reactive power from node *i* to node *j* at time *t*, respectively. $P_{i,t}$ and $Q_{i,t}$ are the active power and reactive power injected to node *i* at time *t*, respectively. $P_{i,t}^{DG}$ and $Q_{i,t}^{DG}$ are the active power and reactive power outputs of the DG at node *i* at time *t*, respectively. $Q_{i,t}^{L}$ is the reactive power consumed by the load at node *i* at time *t*, and $U_{2,i,t}$ is the squared voltage of node *i* at time *t*. Constraint (**Eq. 16**) represent the DistFlow model-based power flow equation for closed lines with $u_{ij,t} = 1$, and get relaxed for open lines with $u_{ij,t} = 0$. *M* needs to be big enough, so that for any open line *ij*, $U_{2,i,t}$ and $U_{2,j,t}$ do not directly influence each other. It is adequate to set $M = \max(U_{2,i,t})$ -min $(U_{2,i,t})$.

3.3.3 Power Flow Constraints of DC Network

$$\sum_{ik\in B^{AC}} P_{ik,t} = \sum_{ji\in B^{AC}} \left(P_{ji,t} - R_{ji}I_{2,ji,t} \right) + P_{i,t}, \forall i \in N^{DC},$$
(18)

$$P_{i,t} = P_{i,t}^{DG} + P_{i,t}^{VSC} - \rho_{i,t} P_{i,t}^{L}, \forall i \in N^{DC},$$

$$-M(1 - u_{i,t}) \leq U_{2,t} - U_{2,t} - 2R_{t}P_{t,t},$$
(19)

$$+ \mathbf{R}_{ij}^2 \mathbf{I}_{2,ij,t} \le M \Big(1 - \boldsymbol{u}_{ij,t} \Big), \forall ij \in \mathbf{B}^{DC},$$
(20)

$$I_{2,ij,t} = \frac{\left(\boldsymbol{P}_{ij,t}\right)^2}{\boldsymbol{U}_{2,i,t}}, \forall \boldsymbol{ij} \in \boldsymbol{B}^{AC}.$$
(21)

3.3.4 Voltage Constraint

$$\begin{cases} \left(\boldsymbol{U}_{min}^{AC}\right)^2 \leq \boldsymbol{U}_{2,i,t} \leq \left(\boldsymbol{U}_{max}^{AC}\right)^2, \forall i \in N^{AC}, \\ \left(\boldsymbol{U}_{min}^{DC}\right)^2 \leq \boldsymbol{U}_{2,i,t} \leq \left(\boldsymbol{U}_{max}^{DC}\right)^2, \forall i \in N^{DC}, \end{cases}$$
(22)

where U_{max}^{AC} and U_{min}^{AC} are the maximum and minimum voltage of the AC network, respectively. U_{max}^{DC} and U_{min}^{DC} are the maximum and minimum voltage of the DC network, respectively.

3.3.5 Line Capacity Constraints

$$\sqrt{\left(\boldsymbol{P}_{ij,t}\right)^{2} + \left(\boldsymbol{Q}_{ij,t}\right)^{2}} \le \boldsymbol{u}_{ij,t}\boldsymbol{S}_{ij}, \ \forall ij \in \boldsymbol{B}^{AC},$$
(23)

$$\boldsymbol{P}_{ij,t} \leq \boldsymbol{u}_{ij,t} \boldsymbol{S}_{ij}, \; \forall \boldsymbol{ij} \in \boldsymbol{B}^{DC}, \tag{24}$$

where S_{ij} is the capacity of line *ij*.

3.4 Second-Order Cone Conversion of the Constraints

Constraints (Eq. 13) and (Eq. 23) are transformed into the standard second-order cone constraints (Eq. 25) and (Eq. 26):

$$\left\| \begin{bmatrix} 2P_{i,t}^{VSC} & 2Q_{i,t}^{VSC} \end{bmatrix}^T \right\| \le u_{ij,t}S_{ij}^{VSC}, \forall ij \in B^{VSC}, i \in N^{AC}, j \in N^{DC},$$
(25)

$$\left\| \begin{bmatrix} 2\boldsymbol{P}_{ij,t} & 2\boldsymbol{Q}_{ij,t} \end{bmatrix}^T \right\| \leq \boldsymbol{u}_{ij,t}\boldsymbol{S}_{ij}, \ \forall ij \in \boldsymbol{B}^{AC}.$$
(26)

Constraints (Eq. 17) and (Eq. 21) are relaxed and then transformed into the standard second-order cone constraints (Eqs 27, 28).

$$\left\| \begin{bmatrix} 2P_{ij,t} & 2Q_{ij,t} & I_{2,ij,t} - U_{2,i,t} \end{bmatrix}^T \right\| \le I_{2,ij,t} + U_{2,i,t}, \ \forall ij \in B^{AC}, \ (27)$$

$$\left\| \begin{bmatrix} 2\boldsymbol{P}_{ij,t} & \boldsymbol{I}_{2,ij,t} - \boldsymbol{U}_{2,i,t} \end{bmatrix}^T \right\| \leq \boldsymbol{I}_{2,ij,t} + \boldsymbol{U}_{2,i,t}, \ \forall ij \in \boldsymbol{B}^{DC}.$$
(28)

4 FAILURE MODE AND EFFECT ANALYSIS METHOD BASED ON THE SEGMENT

This study introduces the FMEA method based on the segment proposed in (Wang, 2012). The segment is a collection of

components with the same entry component (Broadwater et al., 1994). The entry component is a switch or protection device, and each segment includes only one switch or protection device (Atwa et al., 2010). The main idea of the method is as follows, and the specific process is described in detail in Wang (2012) and will not be repeated here.

- 1) First, the switch nodes in the distribution network are encoded by the one-dimensional array. The code represents the location of the switch nodes in the distribution network and the topological relationships between the switch nodes and other switch nodes.
- 2) Then, the segment to which the switch node belongs and the other nodes in this segment are encoded with the same code as that of the switch node. At this point, all nodes in the distribution network are encoded.
- 3) Finally, based on the code of the fault component and the code of each segment, the segments in the network are divided into four types of areas with different degrees of impact from fault through the fault impact classification method and code finding technique. Table 1 shows the definition of the four types of areas and the outage time of the loads in them.

5 RELIABILITY EVALUATION PROCESS BASED ON THE SEQUENTIAL MONTE CARLO METHOD

The aforementioned work is combined with the sequential Monte Carlo method to evaluate the reliability of the AC/DC hybrid distribution network. The specific evaluation process is as follows (Billinton and Wang, 1999):

- 1) Read the data and set the simulation period. Initial simulation clock *t*. Simultaneously, the renewable energy output and load value are sampled.
- 2) Calculate the time to failure (TTF) of each component according to the fault rate, and TTF_i indicates the TTF of component *i*.
- 3) Find the component *i* with the smallest TTF_i as the fault component, and get the time to repair (TTR) which is the repair time of component *i*. Increase the simulation clock *t* by TTF_i .
- 4) Divide the network into the fault area, backward area, forward area, and no-impact area through the FMEA method. Record the outage time of the loads in the fault area as fault repair time and the outage time of the loads in the forward area as fault isolation time. Construct the network topology after fault isolation based on the forward area, backward area, and no-impact area.
- 5) Solve the restoration optimization model to yield the restoration scheme of the loads in the backward area in each period of [t, t+TTR]. Considering the power supply continuity of the load, select the restoration scheme of the period with the least restored loads as the restoration scheme during [t, t + TTR]. Record the outage time of the load that can be restored as fault isolation and transfer time, and the outage time of the load that cannot be restored as fault repair time.

TABLE 1 | Definition of the four types of areas.

Type of area	Definition of the area and outage time of the load in the area		
Fault area	The fault area is the area where the fault component is located. The outage time of the loads in this area is fault repair time		
Backward area	The backward area is the area downstream of the fault area. If the loads in this area can be restored, the outage time is fault isolation and transfer time; otherwise, the outage time is fault repair time		
Forward area	The forward area is located upstream of the fault area and can be connected with the main power supply after fault isolation. The outage time of the loads in this area is fault isolation time		
No-impact area	The no-impact area is the area other than the aforementioned areas. The loads in this area are not affected by the fault component, so they do not cut off power		

TABLE 2 Types and parameters of DG.			
Node	Type of DG	Capacity (kVA)	Power factor
12, 44	Photovoltaic	800	0.9
22, 54	Photovoltaic	700	0.9
29, 61	Wind turbine	600	0.9

- 6) Increase the simulation clock *t* by *TTR*, and calculate the new *TTF_i* of the component *i* according to the fault rate.
- 7) Determine whether t reaches the simulation period. If t reaches, go to step (8); otherwise, return to (3).
- 8) End the simulation, and calculate the customer interruption frequency (CIF) and customer interruption duration (CID). On this basis, calculate the system average interruption frequency index (SAIFI), system average interruption duration index (SAIDI), average service availability index (ASAI), and expected energy not supplied (EENS) according to Eqs 29–32.

$$SAIFI = \frac{\sum \lambda_k N_k}{\sum N_k},$$
(29)

$$SAIDI = \frac{\sum t_k N_k}{\sum N_k},\tag{30}$$

$$ASAI = \frac{\sum N_k \times 8760 - \sum t_k N_k}{\sum N_k \times 8760},$$
(31)

$$EENS = \sum t_k P_k^{average}, \qquad (32)$$

where λ_k , t_k , N_k , and $P_k^{average}$ are the CIF, CID, number of customers, and average load value of node k, respectively.

6 CASE STUDY

6.1 Test System Modeling

The proposed method is tested on the AC/DC hybrid distribution network in **Figure 1**, which is composed of two IEEE 33-node distribution networks. The parameters of the network are detailed in Baran and Wu (1989). Circuit breakers are installed at the beginning and end of AC and DC main feeders, and isolation switches are configured on both sides of nodes. The distribution network contains six DGs, which are located at nodes 12, 22, 29, 44, 54, and 61, respectively. The types and parameters of DGs are shown in **Table 2**. The reliability parameters of the components in the AC/DC hybrid distribution network are drawn from Wu **TABLE 3** Reliability parameters of components in the AC/DC hybrid distribution network.

Component	Fault rate (times/year)	Repair time (h)
AC circuit breaker	0.006	4
DC circuit breaker	0.2999	4
VSC	2.6828	4.7193
Line	0.04	30
Substation	0.001	2

et al. (2020) and Wei et al. (2019), as shown in **Table 3**. When the network operates normally, VSC 1 works in the $U_{dc}Q$ control to provide the voltage support for the DC network, and VSC 2 works in the *PQ* control. Set the switch action time to 0.5 h.

6.2 Comparison of Reliability Evaluation Results

The reliability of the AC/DC hybrid distribution network is evaluated by the proposed method and the two methods defined in **Table 4**. The nodal CIF and CID of the three methods are shown in **Table 5**. The SAIFI, SAIDI, ASAI, and EENS of the three methods are shown in **Table 6**.

The comparison in **Table 5** shows that:

- 1) For any nodes 1–64, both the CIF and CID of the proposed method are lower than those of method 1.
- 2) For any nodes 1–64, the CIF of the proposed method is equal to that of method 2. For any nodes 1–17 and 33–49, the CID of the proposed method is equal to that of method 2, and for any nodes 18–32 and 50–64, the CID of the proposed method is lower than that of method 2.

The comparison in Table 6 shows the following :

- 1) The SAIFI and SAIDI of the proposed method are 34.3% and 12.5% lower than those of method 1, respectively; the ASAI is 0.0049% higher than that of method 1; and the EENS is 8.4% lower than that of method 1.
- 2) The SAIFI of the proposed method is equal to that of method 2, the SAIDI is 38.8% lower than that of method 2, the ASAI is 0.0219% higher than that of method 2, and the EENS is 39.2% lower than that of method 2.

TABLE 4	Definition of the evaluation methods.	
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Evaluation method	Definition of the evaluation method
Method 1	Only network reconfiguration is considered in the restoration optimization model (VSC restoration capability is not considered)
Method 2	Only VSC restoration capability is considered in the restoration optimization model (network reconfiguration is not considered)

6.3 Analysis of Differences in Reliability Evaluation Results

This section analyzes the difference in reliability evaluation results of the three methods from the impact of fault on the network. For the convenience of analysis, four areas are constructed in the AC/DC hybrid distribution network, as shown in **Figure 3**. The fault of VSC 2 does not need to be analyzed because it has no impact on the network.

Considering that the fault may occur at any time, nodal customer average outage times (CAOS) and customer average outage time (CAOT) are defined as the average value of outage times and outage time of node when the fault occurs in each period of the day, respectively.

6.3.1 Fault Impact Analysis of CB2 and the Components in Area 1

When one of the components in area 1 fails or CB 2 fails, the nodes 33–64 are not affected. After fault isolation, the main power supply of the DC network fails, then the nodes 1–32 need to be supplied by the AC network. However, due to power flow constraints, only a fraction of the nodes 1–32 can be recovered at times other than low load periods. The recoverable nodes at any time period in these three methods are the same because they all use the restoration optimization model to solve for the recoverable nodes. We analyze the impact of the aforementioned two types of faults on nodes 1–32 separately.

1) When one of the components in area 1 fails, CB 2 disconnects to directly isolate the fault, which means the fault isolation time is 0 h. In the three methods, the outage time of the unrecoverable node is fault repair time, and there are differences in the outage time of the recoverable node. In the proposed method and method 2, VSC 2 is quickly adjusted to the $U_{dc}Q$ control to provide the voltage support for the DC network, so the recoverable node can maintain uninterrupted power supply during the fault repair, which means the outage time is 0 h. Method 1 does not consider VSC restoration capability, the DC network needs to be powered by the AC network through transfer, so the outage time of the recoverable node is switch action time of 0.5 h. Therefore, when one of the components in area 1 fails, for any nodes 1-32, both the node average outage times of the three methods and the node average outage time of the three methods have the following relationship: proposed method = method 2 < method 1.

2) When CB 2 fails, the fault should be isolated through the isolation switch. In the three methods, the outage time of unrecoverable node is fault repair time, and the analysis process of the outage time of the recoverable node is the same as the aforementioned paragraph, except that the fault isolation time is different. In the proposed method and method 2, the outage time of the recoverable node is switch action time of 0.5 h. In method 1, the outage time of the recoverable node is this study believes that the isolation switch, contact switch, and transfer switch can operate simultaneously. Therefore, when CB 2 fails, for any nodes 1–32, both the CAOS of the three methods and the CAOT of the three methods have the following relationship: proposed method = method 1 = method 2.

6.3.2 Fault Impact Analysis of the Components in Area 2

When one of the components in area 2 fails, the fault need be isolated through the isolation switch, and the nodes 33–64 are not affected. The faults in area 2 can be divided into the faults of the DC main feeder and the DC branch line, and the impacts of these two types of faults on nodes 1–32 are analyzed separately.

- 1) When the DC main feeder fails, the nodes upstream of the fault are restored by the main power supply and the outage time of these nodes is switch action time of 0.5 h in the three methods. The outage time of the nodes downstream of the fault is different in the three methods. In the proposed method and method 1, the nodes downstream of the fault are restored by the main power supply through network reconfiguration, and the outage time is switch action time of 0.5 h. Method 2 does not consider network reconfiguration, VSC 2 is adjusted to the $U_{dc}Q$ control to provide the voltage support for the nodes downstream of the fault, and the outage time is switch action time of 0.5 h. However, if there are many nodes downstream of the fault, limited by the power flow constraints, only a fraction of these nodes can be restored and the nodes on the branch line will be cut off preferentially. The outage time of the nodes that cannot be restored is fault repair time, which is greater than 0.5 h.
- 2) When the DC branch line fails, except for the nodes downstream of the fault on the branch line, the other nodes are still restored by the main power supply, and the outage time is switch action time of 0.5 h. There are differences in the outage time of the nodes downstream of the fault on the branch line. In the proposed method and method 1, these nodes are still restored by the main power

TABLE 5 | Nodal CIF and CID of the three methods.

Node	Proposed	Proposed method		od 1	Method 2	
	CIF (times/year)	CID (hour/year)	CIF (times/year)	CID (hour/year)	CIF (times/year)	CID (hour/year)
l	1.9198	0.9599	4.6096	2.3048	1.9198	0.9599
2	1.9198	0.9599	4.6096	2.3048	1.9198	0.9599
3	1.9198	0.9599	4.6096	2.3048	1.9198	0.9599
4	1.9198	0.9599	4.6096	2.3048	1.9198	0.9599
5	1.9198	0.9599	4.6096	2.3048	1.9198	0.9599
6	1.9198	0.9599	4.6096	2.3048	1.9198	0.9599
7	1.9198	0.9599	4.6096	2.3048	1.9198	0.9599
8	1.9198	0.9599	4.6096	2.3048	1.9198	0.9599
9	1.9198	0.9599	4.6096	2.3048	1.9198	0.9599
10	1.9198	0.9599	4.6096	2.3048	1.9198	0.9599
11	1.9198	0.9599	4.6096	2.3048	1.9198	0.9599
12	1.9198	0.9599	4.6096	2.3048	1.9198	0.9599
13	1.9198	0.9599	4.6096	2.3048	1.9198	0.9599
14	1.9198	0.9599	4.6096	2.3048	1.9198	0.9599
15	1.9198	0.9599	4.6096	2.3048	1.9198	0.9599
16	1.9198	0.9599	4.6096	2.3048	1.9198	0.9599
17	1.9198	0.9599	4.6096	2.3048	1.9198	0.9599
18	3.3767	9.5805	4.6096	9.6561	3.3767	10.7605
19	3.4886	10.1081	4.6096	10.1715	3.4886	12.4681
20	3.7130	11.2976	4.6096	11.3526	3.7130	14.8376
21	4.2732	14.1591	4.6096	14.1798	4.2732	18.8791
22	3.1526	8.4358	4.6096	8.5251	3.1526	9.6158
23	4.0485	12.9247	4.6096	12.9486	4.0485	15.2847
24	4.0488	12.9695	4.6096	12.9987	4.0488	16.5095
25	2.8161	6.6739	4.6096	6.7785	2.8161	7.8539
26	3.6008	10.7250	4.6096	10.7869	3.6008	13.0850
27	2.4805	3.8665	4.6096	5.1823	2.4805	7.4065
28	2.0319	1.5323	4.6096	2.8703	2.0319	6.2523
29	2.0319	1.5323	4.6096	2.8703	2.0319	7.4323
30	3.6003	10.6355	4.6096	10.6868	3.6003	17.7155
31	3.3765	9.5357	4.6096	9.6060	3.3765	17.7957
32	3.6013	10.7702	4.6096	10.8373	3.6013	20.2102
33	1.3322	1.8516	1.3330	1.8520	1.3322	1.8516
34						
	1.3320	0.6660	1.3330	0.6665	1.3320	0.6660
35	1.3320	0.6660	1.3330	0.6665	1.3320	0.6660
36	1.3320	0.6660	1.3330	0.6665	1.3320	0.6660
37	1.3320	0.6660	1.3330	0.6665	1.3320	0.6660
38	1.3320	0.6660	1.3330	0.6665	1.3320	0.6660
39	1.3320	0.6660	1.3330	0.6665	1.3320	0.6660
40	1.3320	0.6660	1.3330	0.6665	1.3320	0.6660
41	1.3320	0.6660	1.3330	0.6665	1.3320	0.6660
42	1.3321	1.8506	1.3330	1.8511	1.3321	1.8506
43	1.3320	0.6660	1.3330	0.6665	1.3320	0.6660
44	1.3320	0.6670	1.3330	0.6674	1.3320	0.6670
45	1.3320	0.6660	1.3330	0.6665	1.3320	0.6660
46	1.3320	0.6660	1.3330	0.6665	1.3320	0.6660
47	1.3321	1.8497	1.3330	1.8501	1.3321	1.8497
	1.3320	0.6660	1.3330	0.6665	1.3320	0.6660
48						
49	1.3320	0.6660	1.3330	0.6665	1.3320	0.6660
50	1.3325	1.8574	1.3330	1.8577	1.3325	3.0374
51	1.3325	1.8601	1.3330	1.8604	1.3325	4.2201
52	1.3325	1.8620	1.3330	1.8622	1.3325	5.4020
53	1.3326	1.8629	1.3330	1.8631	1.3326	6.5829
54	1.3326	1.8629	1.3330	1.8631	1.3326	3.0429
55	1.3324	1.8556	1.3330	1.8559	1.3324	4.2156
56	1.3327	1.8658	1.3330	1.8659	1.3327	5.4058
57	1.3324	1.8564	1.3330	1.8567	1.3324	3.0364
58	1.3325	1.8584	1.3330	1.8586	1.3325	4.2184
59	1.3325	1.8574	1.3330	1.8577	1.3325	5.3974
60	1.3328	1.8659	1.3330	1.8660	1.3328	6.5859
61	1.3330	1.8690	1.3330	1.8691	1.3330	7.7690
62	1.3328	1.8650	1.3330	1.8651	1.3328	8.9450
63	1.3328	1.8659	1.3330	1.8660	1.3328	10.1259
64	1.3329	1.8679	1.3330	1.8679	1.3329	11.3079

TABLE 6 | System reliability indicators of the three methods.

Evaluation method	SAIFI (times/year)	SAIDI (hour/year)	ASAI (%)	ENS (kWh)
Proposed method	1.9517	3.0293	99.9654	17507.7
Method 1	2.9713	3.4602	99.9605	19115.5
Method 2	1.9517	4.9468	99.9435	28781.3



supply through network reconfiguration, and the outage time is switch action time of 0.5 h. Method 2 does not consider network reconfiguration, so these nodes cannot be restored and the outage time is fault repair time.

To sum up, when one of the components in area 2 fails, for any nodes 1–32, the CAOS of the three methods has the following relationship: proposed method = method 1 = method 2; for any nodes on the main feeder, the CAOT of the three methods has the following relationship: proposed method = method 1 = method 2; for any nodes on the branch line, the CAOT of the three methods has the following relationship: proposed method = method 1 < method 2.

6.3.3 Fault Impact Analysis of CB 3

When CB 3 fails, the fault need be isolated through the isolation switch, the nodes 33-64 are not affected and the nodes 1-32 are restored by the main power supply. In the three methods, the outage time of nodes 1-32 is switch action time 0.5 h. Therefore when CB 3 fails, for any nodes 1-32, both the CAOS of the three methods and the CAOT of the three methods have the following relationship: proposed method = method 1 = method 2.

6.3.4 Fault Impact Analysis of CB 4–5 and the Components in Areas 3–4

As can be seen from **Figure 3**, the topology of the AC network is similar to that of the DC network, so the fault impact analysis of CB 5, CB 4, the components in area 3, and the components in area 4 are the same as that of CB 2, CB 3, the components in area 1, and the components in area 2, respectively. Therefore, under these faults, for any nodes 33–64, the relationship among CAOS/ CAOT of the three methods is the same as before.

6.3.5 Summary of Fault Impact Analysis

The relationships among nodal CAOS/CAOT of the three methods under various types of faults are summarized in **Table 7**. Since the reliability evaluation takes into account, all faults including CB 2–5, VSC 2, and the components in areas 1–4, the relationships among nodal CIF/CID of the three methods can be obtained by superimposing the relationships in **Table 7**, as shown in **Table 8**.

According to the results in **Table 8** and **Eqs 29–32**, the relationship between the system reliability indicators of the three methods can be obtained as follows. The SAIFI, SAIDI, and EENS of the proposed method are lower than those of method 1, and the ASAI of the proposed method is higher than that of method 1. The SAIFI of the proposed method is equal to that of method 2, the SAIDI and EENS of the proposed method are lower than those of method 2, and the ASAI of the proposed method 2.

From the aforementioned analysis, we can summarize the impact of considering VSC restoration capability and network reconfiguration on the reliability of the AC/DC hybrid distribution network as follows:

- Since the AC/DC hybrid distribution network contains more contact lines, more nodes can be restored through network reconfiguration after fault isolation. Therefore, considering network reconfiguration cannot reduce the nodal CIF, but can reduce the nodal CID and thus improve the reliability of AC/ DC hybrid distribution networks.
- 2) Due to VSC restoration capability, the nodes in non-faulty areas can maintain uninterrupted power supply by adjusting the VSC control mode when the fault can be quickly isolated by circuit breakers. Therefore, considering VSC restoration capability can reduce both the nodal CIF and CID at the same time, and thus improve the reliability of the AC/DC hybrid distribution network.

Based on the aforementioned results, we can draw the following conclusions: the proposed method fully considers the impact of VSC restoration capability and network reconfiguration on reliability, thus the reliability of the AC/DC hybrid distribution network can be accurately evaluated.

6.4 Analysis of the Impact of Reliability of Key Components on System Reliability

Taking the parameters in **Table 3** as the base values, we calculate the system reliability indicators when the fault rates of DC circuit breaker, AC circuit breaker, and VSC are 20%–90% of the base values, respectively, as shown in **Figure 4**.

	Belationships among	nodal CAOS/CAOT	of the three methods unde	r various types of faults
IADLE /	neialionships among	TIQUAL CAOS/CAOT		various types of faults.

Type of fault	Type of node	Relationship among CAOS	Relationship among CAOT
Components in area 1 Components in area 3	All node	Proposed method = method 2 < method 1	Proposed method = method 2 < method 1
CB 2 CB 3 CB 4 CB 5	All node	Proposed method = method 1 = method 2	Proposed method = method 1 = method 2
Components in area 2 Components in area 4	Node on the main feeder Node on the branch line	Proposed method = method 1 = method 2 Proposed method = method 2 = method 1	Proposed method = method 1 = method 2 Proposed method = method 1 < method 2

TABLE 8	Relationships	among noda	I CIF/CID of the	he three methods.

Type of node	Relationship among CIF	Relationship among CID
Node on the main feeder	Proposed method = method 2 < method 1	Proposed method = method 2 < method 1
Node on the branch line	Proposed method = method 2 < method 1	Proposed method < method 2, proposed method < method 1



FIGURE 4 | Impact of the reliability parameters of components on system reliability indicators. (A) Impact of the reliability parameters of components on SAIFI. (B) Impact of the reliability parameters of components on SAIDI. (C) Impact of the reliability parameters of components on ASAI. (D) Impact of the reliability parameters of components on SAIDI. (C) Impact of the reliability parameters of components on ASAI. (D) Impact of the reliability parameters of components on SAIDI. (C) Impact of the reliability parameters of components on ASAI. (D) Impact of the reliabil



From the comparison in the figure, the following conclusion can be drawn:

- As the fault rates of the three components decrease, the reliability of the AC/DC hybrid distribution networks increases. Among them, the fault rate of VSC has the most significant impact on SAIFI, SAIDI, EENS, and ASAI, the fault rate of the DC circuit breaker is the second most significant, and the fault rate of the AC circuit breaker has almost no effect. Therefore, priority should be given to improving the reliability of the AC/DC hybrid distribution network by reducing the fault rate of VSC.
- 2) Similarly, as the repair time of the three components decreases, the reliability of the AC/DC hybrid distribution networks increases. Among them, the repair time of VSC has the most significant impact on SAIFI, SAIDI, EENS, and ASAI, the repair time of the DC circuit breaker is the second most significant, and the repair time of the AC circuit breaker has almost no effect. Therefore, priority should be given to improving the reliability of the AC/DC

hybrid distribution network by reducing the repair time of VSC.

6.5 Analysis of the Impact of Voltage Source Converter Capacity on System Reliability

We calculate the system reliability indicators when the capacity of VSC 2 is increased to 1.1–2.0 times of the initial value, respectively, as shown in **Figure 5**.

As seen from the figure, increasing the capacity of the VSC connecting DC network and AC network can improve the reliability of the hybrid AC/DC distribution network. However, when the capacity of VSC is larger enough, the reliability of the hybrid AC/DC distribution network no longer increases with the capacity of VSC. This is because the capacity of the VSC is already larger than the maximum power that can be exchanged between the two networks while satisfying the power flow constraint. Therefore, the capacity of VSC connecting the AC and DC networks can be increased

within a certain range to improve the reliability of the AC/DC hybrid distribution network.

7 CONCLUSION

This study developed a restoration optimization model of the AC/ DC hybrid distribution network considering network reconfiguration and control modes of VSC. Based on this, a reliability evaluation method for the AC/DC hybrid distribution network combining the FMEA method, restoration optimization model, and sequential Monte Carlo method was proposed. The following conclusions were drawn from case studies:

- Considering VSC restoration capability and network reconfiguration can improve the reliability of the AC/DC hybrid distribution network. The proposed method fully accounts for these two restoration methods; thus, the reliability of the AC/DC hybrid distribution network can be accurately evaluated.
- 2) Among the key components, the reliability of VSC has the most significant impact on the reliability of AC/DC hybrid distribution networks, followed by the reliability of the DC circuit breaker, while the reliability of the AC circuit breaker is the weakest. Reducing the fault rate and repair time of VSC simultaneously is the most effective way to improve the reliability of the AC/DC hybrid distribution network.

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3) Increasing the capacity of the VSC connecting AC network and DC network within a certain range can improve the reliability of the AC/DC hybrid distribution network.

DATA AVAILABILITY STATEMENT

The original contributions presented in the study are included in the article/Supplementary Material, further inquiries can be directed to the corresponding author.

AUTHOR CONTRIBUTIONS

LZ developed the research framework and put forward suggestions on the revision and improvement. SY completed the programming work and wrote the manuscript. YC put forward suggestions on the revision and improvement. WT put forward suggestions on the revision and improvement. HC put forward suggestions on the revision and improved the English written of this paper.

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