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# Numerical simulation of transient cavitation characteristics of valve-controlled liquid-filled hydrodynamic coupling

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In high-power impeller industries, valve-controlled liquid-filled hydrodynamic couplings are widely used in the soft startup of heavy-duty scraper conveyors for mining. However, the water circulation speed in internal flow fields is higher at lower speed ratios, making the hydrodynamic couplings prone to severe cavitation, which further results in severe performance degradation, noise, vibration, or even erosion failure. Meanwhile, because a hydrodynamic coupling is a piece of closed-loop multicomponent turbomachinery, internal transient cavitation flow behavior cannot be easily controlled. To reasonably predict the characteristics of cavitation and its influence on the working performance of the hydrodynamic coupling, a high-quality structured mesh model of the internal flow field for an impeller was established. Considering the periodic structural characteristics of the impeller, a scale-resolving simulation turbulence model was combined with a Rayleigh-Plesset cavitation model to establish a single-cycle hydrodynamic coupling calculation model. The cavitation distribution characteristics and torque transmission of the flow field under different working conditions were obtained, and the effect of cavitation on the soft startup performance was analyzed. The results demonstrated that cavitation in the hydrodynamic coupling mainly occurred under low speed ratios. The degree of cavitation decreased as speed ratio increased. The worst-case scenario for cavitation occurred when the speed ratio was zero. Most of the cavitation bubbles were generated at the tip of the blades, resulting in unstable variation in torque characteristics and deterioration of the working performance of the hydrodynamic coupling. The analysis reveals that the cavitation process in the impeller is highly unstable and periodic, and the cavitation development near the tip of the blades occurs in four stages: birth, growth, separation, and disintegration. The generated steam accumulates in the inner ring of the impeller. Therefore, a method for accurately predicting the cavitation characteristics of hydrodynamic couplings based on high-precision technology is proposed, and a theoretical basis for coupling design and cavitation suppression technology is provided.

#### KEYWORDS

valve-controlled liquid-filled hydrodynamic coupling, cavitation, scale-resolving simulation, CFX, torque characteristic

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## **1** Introduction

Efficient and safe mining equipment plays a vital role in coal mining and utilization. Scraper conveyors often encounter harsh working conditions, such as excessively hard coal walls, sudden changes in coal production, stagnation of scraper chains, and unbalanced loads. These conditions can cause unexpected shutdowns, affect production efficiency, and affect the reliability and service life of the motor and scraper conveyor. Commonly used transmission devices in mines include valve-controlled liquid-filled hydrodynamic couplings, controlled start transmission, and frequency conversion drive devices. Compared with other transmission valve-controlled liquid-filled methods, hydrodynamic couplings use water as the working medium. The amount of liquid in the hydrodynamic coupling is varied via a hydraulic valve; speed regulation and soft starting of the load are then realized. As a commonly used soft start device on conveyors, this hydrodynamic coupling exhibits the advantages of a large starting torque coefficient, flexible transmission, simple structure, reliable performance, low equipment investment, and low maintenance cost (Zhang et al., 2020).

With the rapid development of computing power and various commercial finite-element software packages, the application of computational fluid dynamics (CFD) technology has become crucial to solve the problem of fluid calculation. To study hydraulic transmission, several researchers have conducted numerical computations for various hydraulic components based on CFD technology.

At present, most scholars focus on the cavitation characteristics of torque converter flow field in various operating conditions. Liu Cheng et al. revealed the fluid field mechanism of the influence of charging oil conditions on torque converter cavitation behavior, providing practical guidelines for suppressing cavitation in torque converter (Liu et al., 2022). Ran Zilin et al. developed a cavitation suppression technique by slotting one side of the stator suction side, which was proven to be able to significantly shorten the cavitation duration (Ran et al., 2022). Guo Meng et al. developed a full flow passage geometry and a computational fluid dynamics (CFD) model with cavitation to analyze the flow behavior in the torque converter (Guo et al., 2022a). Xiong Pan et al. optimized the Joukowsky airfoil used in the design of stator blades, which greatly reduced the probability of cavitation and improved the performance and service life of the torque converter (Pan et al., 2021).

Cavitation is a transient phase change phenomenon. Vapor bubbles occur, grow, and collapse in liquids with variations in the local pressure. This is a common issue in fluid machinery. To face complex coal conditions underground, mining equipment with high power that can sustain high loads are being developed. This has increased the demand for the soft start and stable transmission capabilities of the hydrodynamic coupling. A higher power density results in a higher circulation velocity and lower local pressure in the internal flow field. Simultaneously, because the working medium of the high-power hydrodynamic coupling for mining is water, a large amount of dissolved gas and undissolved microbubbles are present in the medium. Therefore, cavitation can easily occur, particularly on the blade surface, leading to unstable transmission and reduced power, thus reducing the life of the impeller.

At present, research on the cavitation phenomenon of the hydraulic transmission device primarily entails the torque converter. Anderson et al. (Anderson et al., 2003) investigated cavitation signatures under the stall condition in an automotive torque converter using a microwave telemetry technique. Liu et al. (Liu et al., 2018a; Liu et al., 2019) studied the influence of the stator blade shape on the cavitation process of a hydraulic torque converter and found that cavitation is directly related to the internal mass flow rate. Robinette et al. (Robinette, 2007; Robinette et al., 2008a; Robinette et al., 2008b) investigated the effects of torque converter design and operating conditions on the onset of cavitation during vehicle launch using a nearfield acoustical technique. From their numerical results, Dong et al. (Yu et al., 2002) determined that the cavitation on the stator leading edge grew in size with increasing pump speed, resulting in severe performance degradation in the torque converter. Zhao (Zhao et al., 2016) used the full channel transient CFD calculation model to simulate the mechanism of bubble breakup in a hydraulic torque converter by implanting bubbles in it, and they calculated the high incidence area of bubble breakdown. Watanabe et al. (Watanabe et al., 1996; Watanabe et al., 1997; Watanabe et al., 2007) established a cavitation observation model based on a transparent plastic torque converter. A high-speed camera was used to observe the cavitation in the torque converter, which was combined with dynamic torque testing to confirm that the cavitation process produced high-frequency torsional vibration. Kang (Kang et al., 2017) and Dong (Dong et al., 2017) studied the flow structure and cavitation phenomena in a hydraulic retarder. In addition, several important results have been obtained from research on hydrofoil cavitation (Sun et al., 2019; Bai et al., 2018; Cheng et al., 2020). Chai et al. (Chai et al., 2022) revealed the three-dimensional morphological characteristics of cavitation flow under extreme working conditions through high-precision numerical simulation and analysis of the cavitation flow field of a flat torque converter. Guo et al. (Guo et al., 2021; Guo et al., 2022b) proposed full-flow CFD models with and without cavitation for torque converters, and studied the effects of different pump impeller speeds, pump turbine speed differences and cavitation parameters on the internal flow field of the torque converter. Xiong et al. (Xiong et al., 2021) modified the torque converter stator blades through Joukowsky airfoil transformation, which greatly reduced the probability of cavitation.

Because hydraulic transmission machinery is a closed multiimpeller rotating machine, the internal two-phase flow phenomenon cannot be easily observed (Timoshevski et al., 2016). The current research results are mainly on the torque characteristics and twophase flow field under part filling conditions (Da Silva et al., 2008; Hur et al., 2016; Hur et al., 2017). However, there is still no reasonable explanation for the formation of two-phase flow in the coupling. Xuesong Li (Li et al., 2020) studied the formation of two-phase flow state and flow mechanism of the flow field in the hydraulic retarder from the point of view of cavitation phenomenon, and the object of the study is highly similar to the structure of the hydrodynamic coupling, so similar theories can be used to analyze the two-phase flow. In addition, theoretical speculations suggest that, owing to the particularity of the working medium and working conditions of the mining high-power valve-controlled liquid-filled hydrodynamic coupling, the cavitation phenomenon has a greater



impact on the working characteristics of the coupling under the condition of an impeller high-speed difference. Therefore, this study aims to analyze the occurrence and development of cavitation in the flow field of high-power hydrodynamic couplings as well as to examine their external characteristics. This is of great significance for improving the accuracy of the prediction of hydrodynamic coupling characteristics and for improving performance and durability.

The research object in this study was a high-power mineadjustable double-chamber hydrodynamic coupling with a circulation circle outer diameter of 575 mm. A single-channel calculation model of the impeller flow field on the output side was established. A SBES(Stress-Blended Eddy Simulation) calculation model was used to study the effect of cavitation on the performance of the fluid coupling. The development of the torque characteristics and cavitation distribution of the fluid coupling under closed working conditions was analyzed. The results provide a high-precision research method for the cavitation characteristics of fluid couplings; they also provide a reliable theoretical basis for the optimization of the structure of fluid couplings.

### 2 Numerical simulation

#### 2.1 Geometric and mesh model

The structure and working principle of the valve-controlled liquid-filled hydrodynamic coupling are shown in Figure 1.

The speed-adjusting double-chamber hydrodynamic coupling with the outer diameter D = 575 mm was considered as the analysis model. The numbers of pump wheels and turbine blades were 46 and

<b>TABLE 1 Structure</b>	parameters	of the	coupling	impeller.

Parameters	Value
Circular circle outer diameter, D (mm)	575
Circular circle inner diameter, $d$ (mm)	276
Baffle diameter, $d_{\rm B}$ (mm)	320
Baffle thickness, $h_{\rm B}$ (mm)	5
Impeller material	ZL101 A
Rotation speed of pump, $n_{\rm P}$ (r/min)	1475
Number of pump blades, BN <sub>P</sub>	46
Number of turbine blades, $BN_{\rm T}$	45
Minimum blade thickness, $h$ (mm)	3

45, respectively. Because the two pairs of impellers of this coupling had symmetrical structures, the flow field of the output impeller was used as the calculation model. The speed ratio of the hydrodynamic coupling was defined as  $i = n_T/n_P$ ,  $n_T$  was the turbine rotation speed and  $n_P$  was the pump rotation speed. To describe the spatial position of the impeller blades accurately, the surfaces of the different side blades of the pump and turbine were defined according to the impeller rotation direction. The parameters of the coupling impeller are listed in Table 1, and the process of establishing the flow field model is shown in Figure 2A.

To improve the computation efficiency and obtain a high flow field mesh density, a single flow channel calculation model of 1/x (where x is the number of impeller blades) was obtained by utilizing the cyclically symmetric structural characteristics of the inner flow field. The structured hexahedral grid in ICEM CFD was used to discretize the flow field model of a single channel of a fluid coupling. Moreover, o-division and mesh refinement were performed at the circle of curvature and the blade wall surface to improve the computational efficiency and mesh quality. This was because the three-dimensional circulation of the flow field in the coupling was complicated, and the cavitation was distributed under extremely unsteady conditions. Therefore, a high-quality mesh was required to calculate the actual flow state and capture the transient cavitation flow behavior. The process of establishing the single-channel mesh model is shown in Figure 2B.

Taking the internal flow field of the pump wheel as an example, the boundary condition setting method is shown in Figure 3, which mainly includes the no-slip wall at the wall surface of the pump wheel blades and the wall surface of the flow channel, the periodic surface of the pump wheel field according to its own geometric cycle symmetry structure, and the coupling surface of the flow solving area between the pump wheel internal flow field and the turbine internal flow field. Interface). Based on the viscous qualities of the fluid, the flow field near the wall of the existence of a thin layer of flow velocity and the wall of the same speed of the fluid, the thin layer of fluid and the wall of the wall of the relative slip does not exist, so the wall of the wall of the speed of the fluid unit of the velocity of the surface layer to take the value.

The accuracy and efficiency of the solution are directly affected by the quality and quantity of the mesh. In theory, a higher number of grids produce better calculation accuracy, but more grids require



greater computing resources. Therefore, an appropriate mesh density should be determined to achieve an appropriate balance between accuracy and computational cost. The calculated torque change rate f(n) of the mesh with different grid densities is

$$f(n) = \frac{T(n-1) - T(n)}{T(n)}$$
(1)

where T(n) is the computation result under the current density mesh, and T(n-1) is the computation result under the previous mesh with lower density. When the change rate of the calculation result between the two meshes with different densities is less than 2%, the influence of

the current mesh density on the calculation result is acceptable—that is, the calculation result is independent of the grid. Mesh independence tests were performed on seven models with different grid resolutions. The results are listed in Table 2 and shown in Figure 4.

When the global size of the mesh is less than 1.7 mm, the torque change generated by further increasing the number of grids is less than 2% and the model is considered to be mesh-independent. Considering the calculation efficiency and precision comprehensively, the global grid size is selected to be 1.7 mm. The grids number of the turbine flow field is 948,230, and the grids number of the turbine flow field is 1,157,138.



#### TABLE 2 Structural mesh independence analysis results.

Number of grids in pump flow field	Global size setting (mm)	Time consumption (min)	Pump wheel torque (N·m)	<i>f</i> (n) <sub>pump</sub> (%)
83,036	3.5	6	286.377	
121,512	3	10	277.062	3.24
163,254	2.5	16	269.734	2.96
248,045	2	30	261.862	2.66
364,704	1.7	50	258.997	1.59
679,386	1.3	89	257.700	0.89
1,406,380	1	140	256.837	0.34



To ensure the accuracy of the boundary layer flow field computation, the minimum boundary layer size was set to 0.01 mm, which ensured that the minimum y + value around the blade was less than 10. The grid thickness growth rate was set to 1.15.

#### 2.2 Multiphase model

In this study, the multiphase flow field caused by cavitation in the completely filled liquid flow field was obtained. In addition to the general set of mass conservation equations, the mass exchange between liquid and non-condensable vapor is governed by the following transport equation (Zhou et al., 2017):

$$\frac{\delta}{\delta t} \left( f_l \rho_l \right) + \frac{\delta}{\delta x_j} \left( f_l \rho_l v_j \right) = \dot{m} \tag{2}$$

The key to solving the cavitation problem is the determination of the interphase mass transfer rate, i.e., cavitation rate, which is driven by the difference between local pressure and vapor pressure (Wang et al., 2013). Assuming that no interphase slip or heat transfer exists between the liquid and vapor, the radius of a spherical vapor bubble can be described by the Rayleigh–Plesset equation in its first-order approximation form as follows:

$$\frac{\mathrm{d}R_B}{\mathrm{d}t} = \sqrt{\frac{2}{3}} \frac{p_v - p}{\rho_l} \tag{3}$$

Then, the cavitation rate during vaporization can be given as

$$\dot{m} = \frac{3f_{\nu}\rho_{\nu}}{R_{B}}\sqrt{\frac{2}{3}\frac{p_{\nu}-p}{\rho_{l}}}$$
(4)

#### TABLE 3 CFD model settings.

		1			
Analysis step			Ш	IV	
Analysis type	Steady state	Steady state	Steady state	Transient	
Interface model	Stage	Stage	Stage	Transient rotor-stator	
Cavitation model	None	None	Rayleigh-Plesset	Rayleigh-Plesset	
Turbulence model	SST	SST	SST	SBES	
Advection scheme	Upwind	High resolution	High resolution	High resolution	
Time step	1e-3s	Auto timescale	Auto timescale	Auto timescale	
Convergence target	RMS 1e-4	RMS 1e-5	RMS 1e-5	RMS 1e-5	
Fluid properties	$\rho_{water} = 970 \text{ kgm}^{-3}, \mu_{water} = 8.9e\text{-}4 \text{ Pas}$				
Vapor properties	$\rho_{vapor} = 2.3e-2 \text{ kgm}^{-3}, \mu_{vapor} = 9.8e-6 \text{ Pas}$				
Pump status	Fixed at 1475 rpm				
Turbine status	Varied from 0 to 1465.2 rpm				
Boundary details	No slip and smooth wall				
Heat transfer model	50 °C isothermal				
Saturation pressure	12333.43 Pa				



Because the nucleation site density decreases when the vapor volume fraction increases, the vapor volume fraction  $f_v$  is replaced by  $f_{nuc}(1 - f_v)$  to yield the following (Jin et al., 2018):

$$\dot{m}^{-} = -F_{vap} \frac{3f_{muc} \left(1 - f_{v}\right) \rho_{v}}{R_{B}} \sqrt{\frac{2}{3}} \frac{p_{v} - p}{\rho_{l}}$$
(5)

When the partial pressure exceeds the vapor condensation pressure, the mass transfer rate becomes

$$\dot{m}^{+} = F_{cond} \frac{3f_{\nu}\rho_{\nu}}{R_{B}} \sqrt{\frac{2}{3} \frac{p - p_{\nu}}{\rho_{l}}}$$
(6)

Because the condensation process is generally much slower than vaporization, different empirical factors are assumed as follows:  $F_{vap} = 50$ ,  $F_{cond} = 0.01$ ,  $f_{nuc} = 5e-4$ , and  $R_B = 1e-6$  m.

A homogeneous multiphase condition is also assumed to simplify the model; thus, the liquid and vapor share the same velocity and turbulence profiles. The mixture of fluid and vapor is treated as a pseudofluid whose density  $\rho_m$  and dynamic viscosity  $\mu_m$  are defined as follows:

$$\rho_m = (1 - f_v)\rho_l + f_v\rho_v \tag{7}$$

$$\mu_m = (1 - f_v)\mu_l + f_v\mu_v \tag{8}$$





#### 2.3 Simulation settings

First, the upwind steady-state model was used to determine the flow field characteristics of the fluid coupling without cavitation. The high-resolution convection scheme was then used to perform steady-state computations to provide accurate flow field conditions. Based on the results of the noncavitation model, a high-resolution scheme was used to simulate the steady-state cavitation behavior. Finally, with the steady-state cavitation output as the initial condition, a transient CFD cavitation model was established to simulate the dynamic cavitation process in the internal flow field. For the interface between the flow field and impeller wall surface and blade wall surface, the nonslip wall surface treatment was adopted, while the wall surface roughness was neglected. In the steady-state computation stage, the stage interface model was used to exchange data between the pump-turbine flow field interface. In the transient computation stage, the transient rotor-stator interface model was used to capture more transient flow characteristics. The corresponding CFD multistep solution model settings are listed in Table 3.

To obtain accurate cavitation characteristics and corresponding flow field characteristics, the SST SBES DSL model in the scaleresolving simulation is used in transient computations. Compared with the DES, this model features a considerably improved shielding function to protect RANS boundary layers from the impact of the grid-dependent term; further, this model can automatically switch between existing RANS and LES models (Liu et al., 2018b).

The shielding function developed can be used in the following manner for achieving a blending on the stress level between RANS and LES formulations (Li, 2018):

$$\tau_{ij}^{SBES} = f_{SBES} \tau_{ij}^{RANS} + (1 - f_{SBES}) \tau_{ij}^{LES}$$
(9)

where  $\tau_{ij}^{RANS}$  is the RANS portion and  $\tau_{ij}^{LES}$  is the LES portion of the modeled stress tensor. In cases where both models are based on eddy viscosity concepts, the formulation can be simplified as follows:

$$v_t^{SBES} = f_{SBES} v_t^{RANS} + (1 - f_{SBES}) v_t^{LES}$$
(10)

### **3** Experimental research

A macro characteristic test was conducted, wherein a motor was used to provide power at the input end and load at the output end, to





simulate the working conditions of the downhole fluid coupling. A pump station was used to control the inlet and outlet pressures of the valve control oil and working water, complete the startup of the coupling, and test the macroscopic characteristics of the hydrodynamic coupling at different speed ratios. The rotation speed and torque sensors were used to obtain the dynamic hydraulic performance of the coupling. According to the comprehensive analysis results of the torque transmission characteristic computation data and test data, the prediction accuracy of the torque characteristic was verified. The macro



characteristic test plan and parameter settings of the hydrodynamic coupling are shown in Figure 5. Test device parameters mainly include that the power of power motor was set to 2500kW, rated input rotation speed of test bench and hydrodynamic coupling was set to 1475rpm, the water supply flow was greater than 240L/min, and rated power of hydrodynamic coupling was 1200 kW.

Data collection system: The test system data were collected by an efficiency meter industrial control computer. The main collection parameters were as follows: input torque, input speed, output torque, output speed, coupling liquid level pressure, coupling working chamber temperature, filling and discharging liquid valve action signal, and other data.

According to the test plan, a macro characteristic testbed was built. Carry out several repeated tests from starting and running to complete filling, draining, circulating and changing fluids. The working performance and reliability of the equipment were examined.

Test procedure: The drag motor was started at no load, drag motor was maintained at 1475 rpm, and coupling was filled with liquid. The coupling was then loaded until it reached the rated power and remained at the rated working conditions. After 8 h of operation, the coupling ran smoothly without abnormal noise. The input and output speed and torque data were collected and analyzed during the loading process.

# 4 Results and discussion

# 4.1 Cavitation distribution characteristics of steady flow field

According to the numerical analysis results of steady-state cavitation two-phase flow under fully filled working conditions, following the multicycle cavitation and steam accumulation processes in the flow field of the hydrodynamic coupling, a stable inner ring steam accumulation area was formed. The field resulted in a more stable circulation characteristic. The distribution characteristics of cavitation were analyzed at different speed ratios, combined with the liquid velocity and blade pressure distribution trends obtained before and after the cavitation computation model was opened at different speed ratios, which was required to realize complete filling. This analysis was then used to analyze the influence of cavitation on the flow field distribution characteristics.

Figure 6 and Figure 7 show the distribution characteristics of the flow field velocity streamlines when the cavitation computation model is turned off (Figure 6A) and turned on (Figure 6B), respectively. Comparative analysis shows that the water–liquid circulationSR velocity gradually decreased as the speed ratio increased. Because the steam generated in the cavitation process accumulated in the inner ring of the impeller, the water–liquid circulation state changed, and the circulation velocity was lower than that without the cavitation model. With an increase in the speed ratio, the volume of the vapor accumulation zone decreased because of the decrease in the degree of water cavitation, and its influence on the state of water circulation and flow velocity also decreased.

A comparative analysis of the effects of steam accumulation on the blade pressure field distribution under different steady-state cavitation simulation conditions is shown in Figure 8. The overall pressure distribution trends at the blade wall before and after opening the cavitation computation model were the same. Owing to the change in the circulation characteristics, the overall pressure distribution of the blade after cavitation was reduced. Simultaneously, because of the existence of the vapor accumulation area, the corresponding area generates low-pressure areas A and B, and the pressure gradient of the blade was evident.

#### 4.2 Characteristics of transient cavitation

According to the distribution law of cavitation bubbles, the bubbles are mainly generated in the pump flow field. To analyze the distribution pattern and evolution law of the cavitation field in the pump flow field, a speed ratio of 0.6 was considered as an example to



analyze the volume rate distribution of cavitation in different development stages.

Because the flow field in the fluid coupling is complex and threedimensional, the cavitation bubble movement in the flow field is also complex and three-dimensional. Figure 9 shows the development of the cavitation bubble characterized by the 90% steam volume rate isosurface. The figure shows that the evolution of cavitation bubbles can be divided into four stages. In Stage 1, the banded bubble is born around the tip on the suction surface side of the pump blade; this bubble follows the steam in the cavitation bubble. Cloudy bubbles form in the accumulation of phases. In Stage 2, cavitation bubbles always adhere to the surface of the blades. As the bubbles leave the blades, some bubbles enter the flow channel and gradually form ellipsoidal bubbles. In Stage 4, when the volume of ellipsoidal bubbles increases and reaches a certain level, they break away from the surface of the blade. They then enter the flow channel and burst after covering a certain distance. Some steam condenses, and the remaining gas continues to move in the flow field, forming broken bubbles with irregular shapes and sizes and moving toward the inner ring of the pump wheel. Eventually, as cavitation continues to accumulate, a vapor concentration area is formed.

To obtain the volume rate, pressure, and speed distribution data of the cavitation observed near the blade tip of the pump wheel, located near the inner ring, at a speed ratio of 0.6, a circular data





analysis cross section with a diameter of da = 180 mm was established, as shown in Figure 10.

Figure 11A shows the distribution of the steam volume fraction at the cross section. Figure 11B shows the distribution of water speed streamline. The evolution of cavitation from birth, growth, separation, and disintegration is evident. According to the transient changes in cross-sectional pressure and velocity, combined with the volume fraction distribution characteristics, part of the high-speed water from the turbine inner ring outlet enters the pump wheel and hits the blade tip; the flow rate then decreases rapidly and a local high pressure forms at the blade tip area. After passing through the tip area, the flow is affected by the local high pressure. Simultaneously, this flow is driven by other incoming flows to form a high-speed jet close to the blade surface as well as an angle with the surface. Therefore, on the pressure surface side of the impeller blades, a low-pressure region, wherein the pressure is below the vapor pressure, is formed near the tip of the blade; a severe cavitation phenomenon occurs in this region. As the cavitation bubble grows, the flow into the pump wheel is hindered by the bubble, and the jet angle increases. When the growth of cavitation is large, reverse flow can be found near the blade wall, and strong vortices are observed in the corresponding areas. This causes the internal pressure to decrease and promotes the formation of bubbles. As the cavitation bubble moves toward the inner circle of the circulation circle and breaks up, the jet angle decreases and promotes the birth of new cavitation bubbles.

The pressure distribution in Figure 11C shows that, owing to the increase in the jet angle and the appearance of strong vortices near the blade, the range of the low-pressure area near the tip area of the blade pressure surface becomes large, which promotes the growth of cavitation.

As the cavitation bubble grows further, under the influence of the bubble surface tension and the surrounding high-pressure water flow, the shape of the cavitation bubble gradually becomes irregular. As the bubble volume increases, the surface tension is insufficient to maintain the growth of the bubble, the bubble ruptures under the surrounding high pressure, and a small range of low-pressure fragmented bubble areas and new cavitation bubble birth areas form in the flow channel.

#### 4.3 Torque characteristics

Figure 12 shows a characteristic diagram of torque transmission in a fluid coupling considering cavitation and noncavitation. Without cavitation computation, the overall output torque tends to decrease. As the speed ratio increases, the rate of decline continues to increase. The overall trend remains unchanged when the cavitation model is considered. Further, the transmission torque under cavitation is lower than that under noncavitation.

At low speed ratios, owing to the large rotational speed difference between the pump and turbine, the water-liquid circulation speed was rapid, and the cavitation phenomenon was severe. At this time, the torque transmission characteristic also severely deteriorated, and the output torque dropped significantly. As the speed ratio increased, the degree of cavitation in the flow field continued to decrease. At a speed ratio of approximately 0.9, cavitation had little effect on the flow state. Therefore, the occurrence of the cavitation phenomenon considerably affected the overload starting and working ability of the coupling. This phenomenon had relatively little influence on the torque transmission ability under rated working conditions.

To analyze the degree of influence of cavitation on the torque transmission characteristics accurately,  $P_T$  was defined as the torque forecast correction ratio,  $T_{N-C}$  as the torque computational result without considering the cavitation,  $T_C$  as the torque computational result considering the cavitation, and  $\Phi_T$  as the characteristic difference.

The characteristic difference is

$$\Phi_T = T_{N-C} - T_C \tag{11}$$

The torque characteristic prediction correction is

$$P_T = \Phi_T / T_C \tag{12}$$

A comparative analysis of the correction of the torque transfer value of the flow field at different speed ratios is shown in Figure 13. The  $P_T$  is affected by the amount of cavitation vapor accumulation and the degree of cavitation occurrence, and the overall trend is a

downward trend as SR increases. At i = 0,  $P_T$  and  $\Phi_T$  reach the maximum. At this time, the characteristic difference is 1468.35 N·m, and the correction ratio is 12.85%. At a speed ratio of 0.99, because the degree of cavitation is the lowest at this time, the correction factor is 0.32%.

## 5 Conclusion

In this study, CFD technology and experiments were used to investigate the unsteady flow field affected by the cavitation characteristics of fluid coupling. Based on the numerical simulation data, the cavitation distribution, evolution characteristics, and their effects on the torque transmission characteristics were analyzed. The study clarified the following:

- 1) The flow field results demonstrate that the severity of cavitation in the internal flow field of the coupling decreases with increasing SR, and the generated steam mainly accumulates at the inner ring of the pump wheel. The formation of a stable steam accumulation area reduces the circulation velocity and flow state of the flow field. Compared with the pressure distribution gradient obtained in the region not affected by cavitation, that on the blade surface affected by cavitation is larger, forming a low-pressure region near the inner ring.
- 2) Transient cavitation simulation demonstrates that cavitation bubbles are generated near the tip of the blade pressure surface of the internal flow field. Affected by the flow characteristics of water, the evolution process has four stages: birth, growth, separation, and disintegration. This is a periodic cyclic process. The generated steam is finally concentrated inside the circulation circle of the pump wheel. The flow velocity and pressure at the blade surface are both reduced.
- 3) An analysis of the torque transmission characteristics revealed that the torque drop is considerably affected by severe cavitation at a low speed ratio. The computation results demonstrate that the introduction of the cavitation calculation model can improve the accuracy of torque prediction by approximately 13% under a low speed ratio. The effect of cavitation is smaller at high speeds.

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### Data availability statement

The raw data supporting the conclusion of this article will be made available by the authors, without undue reservation.

### Author contributions

The author contributions are as follows: HC was in charge of the whole trial; JZ wrote the manuscript; LL and GW assisted with sampling and laboratory analyses. All authors contributed to the article and approved the submitted version.

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# Conflict of interest

The authors declare that the research was conducted in the absence of any commercial or financial relationships that could be construed as a potential conflict of interest.

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# Nomenclature

DM	NT 1	c		11 1
$BN_P$	Number	0Î	pump	blades

- $BN_T$  Number of turbine blades
- D Circular circle outer diameter [mm]
- d Circular circle inner diameter [mm]
- da A circular data analysis cross section diameter [mm]
- d<sub>B</sub> Baffle diameter [mm]
- Fvap Cavitation vaporization coefficient
- Fcond Cavitation condensation coefficient
- f(n) Torque change rate
- $f_l$  Liquid volume fraction
- $f_{v}$  Vapor volume fraction
- $f_{nuc}$  The nucleation site volume fraction
- $f_{\it SBES}$  The fraction of RANS in the SBES model
- h Minimum blade thickness
- $h_B$  Baffle thickness [mm]
- i  $i = n_T/n_P$ , The speed ratio
- m The interphase mass transfer rate
- $\dot{m}^+$  Mass condensation rate
- *m*<sup>-</sup> Mass vaporization rate
- $n_T$  The turbine rotation speed [r/min]
- $n_P$  The pump rotation speed [r/min]
- $P_v$  Pressure in the bubble [Pa]
- $P_T$  The torque forecast correction ratio
- P Liquid pressure [Pa]
- $R_B$  Mean radius the cavitation [m]
- T(n) The computation result under the current density mesh [N·m]
- T (n-1) The computation result under the previous mesh with lower density  $[{\rm N}{\cdot}{\rm m}]$
- $T_C$  The torque computational result considering the cavitation [N·m]
- $T_{N-C}$  The torque computational result without considering the cavitation [N·m]
- *v<sub>j</sub>* Liquid phase velocity [m/s]
- $v_t^{SBES}$  Model viscosity [m2/s]
- $v_t^{RANS}$   $v_t^{RANS}$ :RANS portion of the mdeled viscosity [m2/s]
- $v_t^{LES}$   $v_t^{LES}$ :LES portion of the mdeled viscosity [m2/s]
- $\rho_l \qquad \rho_l$ :Liquid density [kg/m3]
- $\rho_v \qquad \rho_v$ :Vapor density [kg/m3]
- $\rho_m \qquad \rho_m$ :Mixed fluid density [kg/m3]
- $\mu_m$   $\mu_m$ :Mixed fluid dynamic viscosity [Pa·s]
- $\mu_l$   $\mu_l$ :Liquid dynamic viscosity [Pa·s]
- $\mu_v$   $\mu_v$ :Vapor dynamic viscosity [Pa·s]

- $\tau_{ij}^{SBES}$   $\tau_{ij}^{SBES}$ :Model stress [Pa]
- $\tau_{ij}^{RANS}$   $\tau_{ij}^{RANS}$ :RANS portion of the modeled stress tensor [Pa]
- $\tau_{ij}^{LES}$   $\tau_{ij}^{LES}$ :LES portion of the modeled stress tensor [Pa]
- $\Phi_T$   $\Phi_T$ : The characteristic difference of the torque [N·m]