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Two-stage low-carbon optimal dispatch of the power system considering demand response to defend large uncertainties and risks

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Introduction: In order to promote the consumption of renewable energy, reduce carbon emissions, and take into account the uncertainty of renewable energy output and load fluctuations in the new power system that can affect the normal operation of market mechanism, a two-stage low-carbon optimization scheduling method for power system that considers demand response under multiple uncertainties is proposed in this paper.

Methods: Uncertain scene sets are generated through Latin hypercube sampling and heuristic synchronous backpropagation method is used to reduce scenes to obtain typical scenes and their probabilities. Then, a one-stage optimization model is established with the goal of maximizing energy efficiency and corresponding demand response strategies are obtained. Green certificate carbon trading joint mechanism model consisting of tiered green certificate trading and time-sharing tiered carbon trading are established, and the output of two-stage units are optimized with the goal of minimizing comprehensive operating costs.

Result: The simulation results show that the carbon emissions are decreased by 251.57 tons, the consumption rate of renewable energy is increased by 8.64%, and the total costs are decreased by 124.0612 million yuan.

Discussion: From this, it can be seen that the dual layer low-carbon optimization scheduling strategy for power system considering demand response under multiple uncertainties can effectively reduce the operating costs and carbon emissions of the system, while balancing the economic and environmental aspects of power system operation.

KEYWORDS

power system, uncertainty, demand response, low carbon, optimal scheduling

1 Introduction

The growing prevalence of renewable energy (RE) poses numerous challenges for the power system, including issues related to reliability, efficiency, energy loss, and emissions (Jordehi, 2019; Liu et al., 2020a). Simultaneously, with the development of the electricity market, consumer engagement in the demand-side response is increasing. Hence, the achievement of power system optimization dispatch with the consideration of the demand response (DR) under the dual-carbon target requirements has become a current research hotspot (Wang et al., 2018).

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The optimal dispatch of a power system is widely employed across various operational scopes, spanning from real-time execution to longrange planning. Liu et al. (2021) considered the interaction between power generation and consumption the basis in a comprehensive optimization dispatch model, and three different scheduling commands were proposed before electric vehicle (EV) charging and discharging, such as stochastic scheduling command, load interruption, and transfer command. Zhang and Zheng (2019) presented a dynamic multiple target optimal scheduling method for the electrical system, including economics, pollutant emissions, and power rejections. Wan et al. (2020) employed an improved MOEA/D algorithm to overcome the optimization dispatch problem of the hierarchical model, in which the load-side demand was considered. Li and Xu (2018) developed a globally optimal scheduling strategy for microgrids under grid connection and islanding conditions. Jiang et al. (2020) established a hierarchical scheduling model based on the boundary variable feasible domain-coordinated power system and district heating system operators. A conservative boundary variable feasible domain-based approximation method was provided for a district heating system based on simplex approximation. Hou et al. (2020) employed a multiobjective optimal method and fuzzy membership function approach to overcome the transferable loads and other distributed generation models in microgrids. Liu J. et al. (2020) proposed a multi-task power scheduling method by introducing a multi-objective multi-factor optimization algorithm. Zhang et al. (2018) established a two-phase robust optimal mold, accounting for the uncertainty associated with distributed RE and DR within power systems. This served as the basis for proposing a coordinated optimal operational strategy. Yang et al. (2021) developed a coordinated interval optimization scheduling method by taking into account the uncertainty of RE. However, the scheduling scheme obtained through the robust approach is too conservative, while interval optimization based on interval mathematics still encounters the limitations of complex modelsolving techniques and too large interval values. Therefore, by sampling a considerable number of error scenarios for the assumed probability distributions of random variables, the scenario approach is used to describe the uncertainty, which has a more intuitive model and yields highly accurate computational results.

Moreover, utilizing market mechanisms for carbon dioxide transaction offers advantages of flexibility and benefit. By optimizing the allocation of resources within the carbon emission space and aligning with economic incentives, carbon emission trading mechanisms facilitate the trading of carbon credits while maintaining a constant total carbon emission volume (Hou et al., 2023; Yang et al., 2023; Zhong et al., 2023). Considering the uncertainty of RE generation and customer price responses, a two-stage integrated planning and DR model was proposed by Zeng et al. (2014). The method facilitated the transition from RE generation to low-carbon distribution systems through multiple probability scenario representations, thereby establishing a low-carbon distribution system. To resolve the model, the optimal scheduling approach about suppositional electricity plants incorporated both the carbon dioxide transaction market and green certificate transaction market, alongside the proposal of a selfconcluding variational particle swarm optimization approach by Zhang et al. (2023). Considering the generalized electric-heat DR, Cui et al. (2022) proposed a scheduling method of an energy system with source-load coordination. By combining the organic Rankine cycle and DR for electric heating, the difficulty caused by an inadequate

carbon capture level over spike load periods in the low-carbon transformation procedure of thermal power units has been improved. Leveraging the enhanced two-stage electric gas operation model and the comprehensive thermoelectric DR model within the constructed electric hydrogen production device, Chen et al. (2023) developed a scheduling method of multiple energy production involving electricity and hydrogen on the basis of short-period wind power forecasting. It is noteworthy that the variational mode decomposition and gated recurrent unit approach enhances the exactitude of very short-period wind power generation prediction. Dong et al. (2022) developed a deep reinforcement learning-based energy scheduling strategy using the double-delay depth-determined strategy gradient approach to resolve low-carbon mathematical and multi-objective optimization models. The model involves cogeneration units, carbon capture systems, and electricity-to-gas units. The prevalent carbon trading mechanisms in current research within carbon and green certificate trading markets solely focus on the carbon emission quota trading system across the entire daily cycle timeframe. The green certificate transaction market solely accounts for the fixed green certificate transaction parameter costing model, limiting its maximal potential efficacy.

DR serves as a pivotal mechanism for ensuring the safety and steadiness of the power system by harmonizing equilibrium between supply and demand. To enhance operational efficiency and alleviate power overload resulting from the integration of large-scale electric vehicles, Ran et al. (2021) proposed a hybrid integer planning model that amalgamates DR operations and policies. By concurrently addressing DR requisites, user comfort regarding electric water heaters, and electricity prices, Song et al. (2022) introduced a deep reinforcement learning strategy for DR optimization, leveraging cloud computing. Wu et al. (2022) introduced a buyer-seller auction model based on the principles of benefit distribution among diverse trading entities in DR transactions. Considering the user-side elastic change inherent in heat construct systems, a numerical optimization difficulty in distribution network planning was delineated by Troitzsch et al. (2020). The problem was structured as a mixed-integer quadratic programming endeavor directed toward minimizing both the capex of the grid and running expenses associated with flexible loads. By introducing two-phase forces to promote the search ability of the particle swarm algorithm, a hybrid peaking optimal method on the basis of regenerative electric heaters and electric vehicle load control constraints was established by Song et al. (2019). To overcome the difficulty of large fluctuations in the magnitude and phase of the voltage of an uncertain system at both ends of the source load, an adaptive cubature Kalman filtering algorithm was proposed by Palaniyappan et al. (2023). The bidirectional long short-period recollection method was utilized to improve the generalization ability of the model in dealing with DR problems, and an excitation-based integrated DR model was constructed by Liu et al. (2023). Nonetheless, the compensation amount for DR in the aforementioned studies predominantly adheres to a fixed value and fails to consider the active response behavior of users, which limits its capacity to substantially incentivize user participation in the response.

In this paper, considering user responsiveness and multiple uncertainties, a two-layer low-carbon optimal scheduling method is proposed to enable low-carbon running for the power system and deal with risks brought through RE and load uncertainty. Initially, scenarios encompassing photovoltaic (PV), wind power, and load are produced by using Latin hypercube sampling (LHS). Then, the scenarios are refined using the heuristic synchronized back generation method. Additionally, a model incorporating both green certificate trading and carbon trading, along with a stepped DR incentive mechanism, is proposed as a joint market mechanism. Subsequently, a two-stage optimization dispatch method for the power system is developed. The model aims to maximize user energy benefit and minimize system operating costs. Then, the rationale and validity of the proposed method are demonstrated through diverse scenario setups.

2 Modeling of uncertainty

External factors frequently result in unpredictable variations in both RE generation and load. These fluctuations can disrupt the normal functioning of market mechanisms and significantly influence the security and solidity of the power system (Su et al., 2023). Addressing the challenge of achieving low-carbon economic dispatch within the green certificate carbon trading mechanism amid uncertain conditions involves employing LHS. This approach generates scenes derived from the probability distributions of wind power, PV output, and load. Subsequently, the heuristic synchronous backpropagation approach is used to refine the generated scenarios.

2.1 Model of source and load uncertainty

The actual values of wind output, PV, and load are regarded as the total of the forecasted value and the forecasted deviation, which can be given by

$$\begin{cases}
P_{WV,z,t} = P_{WV,z,t}^{pre} + \Delta_{WV,z,t} \\
P_{PV,z,t} = P_{PV,z,t}^{pre} + \Delta_{PV,z,t} , \\
P_{load,z,t} = P_{load,z,t}^{pre} + \Delta_{load,z,t}
\end{cases}$$
(1)

where $P_{WV,j,t}$ and $P_{WV,j,t}^{pre}$ are the actual and predicted wind power of scenario z at time t, respectively. $\Delta_{WV,z,t}$ represents the forecast deviation of wind power. $P_{PV,z,t}$ and $P_{PV,z,t}^{pre}$ are the actual and predicted PV of scenario z, respectively. $\Delta_{PV,z,t}$ is the prediction deviation in the PV output. $P_{load,z,t}$ and $P_{load,z,t}^{pre}$ are the actual and predicted electrical load of scenario z at time t, respectively. $\Delta_{load,z,t}$ is the forecast deviation in the electrical load. It is usually assumed that wind power follows a Weibull distribution, PV follows a beta distribution, and load follows a normal distribution (Baharvandi et al., 2018; Gupta, 2020; Mahdavi et al., 2023).

2.2 Latin hypercube sampling

A multidimensional sampling theory is introduced, considering the probability distributions of wind power, PVs, and electric load. LHS is a significant multidimensional stratified sampling approach used to reflect the global distribution of stochastic variables through samples drawing values. LHS effectively enhances sampling efficiency and ensures the coverage of all sampling areas by points, rendering it suitable for power system reliability analysis. This paper uses LHS to generate scenarios encompassing wind power, PVs, and load.

Assume that a hypercube has input random variables $x_1, x_2, x_3, ..., x_p$, and the dimension of the variables is p. Then,

the cumulative probability distribution function of each variable is $F_{xz} = f_z(x_z)$, where z = 1, 2, ...p. By using LHS, the sample *N* within the hypercube can be generated as follows:

- (1) The sampling size is defined as N.
- (2) For any random variable x_z , the perpendicular axis of the accumulative probability distribution curved line $F_{xz} = f_z(x_z)$ is divided into N intervals of equal probability. The breadth of each range is 1/N. A value is Stochastically chosen from every range that satisfies $x_{z1} < x_{z2} < x_{z3} \dots < x_{zk} \dots < x_{zN}$ and $P(x_{zk} < x < x_{z(k+1)}) = \frac{1}{N}$.
- (3) For the *k*th sampling value x_{zk} of the stochastic variable x_z, its relevant accumulative distribution probability is given by

$$F(k) = (1/N)r_u + (k-1)/N, k = 1, 2, 3, \dots, N,$$
(2)

where $r_u \sim N(0, 1)$. By computing the contrary function of the accumulative distribution function F_{xz} , the *k*th sampling value x_{zk} can be obtained, which satisfies

$$x_{zk} = F_{xz}^{-1} ((1/N)r_u + (k-1)/N).$$
(3)

(4) When the sampling process is accomplished, the sampled values of each stochastic variable are organized in a column of the matrix to form the sampling matrix. The sampled values of each column in the matrix are sorted to minimize their correlation. In this paper, the Gram–Schmidt sequence orthogonalization approach is used for sorting. In addition, iterative calculation is used to minimize the correlation between each column. In conclusion, Eqs 1–3 describe the uncertainty model.

3 Timeshare stepped carbon trading mechanism

The carbon transaction market implemented in this strategy operates on a time-sharing basis and considers carbon emission quota trading at an hourly scale. The system divides the hourly carbon dioxide trading volume into multiple intervals. Notably, as the carbon transaction volume range increases, both the unit carbon emission transaction price and necessary operating costs correspondingly increase. Conversely, if the carbon emissions of system decrease to below the initial quota, the surplus quota can be introduced to the carbon transaction market for potential sale, yielding profits based on prevailing selling prices. In essence, higher carbon trading volumes lead to increased unit carbon emission trading prices, thereby augmenting the system benefits. The timeshare stepwise carbon trading market model comprises three primary parts: the initial quota model for carbon emissions, actual carbon emission model, and calculation model of costs associated with timeshare stepped carbon trading.

3.1 Initial quota model of carbon emission rights

At present, the incipient allotment of carbon emission quotas is mainly carried out through free allocation. The time period covered by the carbon emission right quota for each carbon emission source is daily. The corresponding carbon emission right quota is calculated according to the output of equipment in the day-ahead dispatch. The regulatory authority will notify the allocated quota 1 day in advance. The carbon emission sources within the system mainly include thermal power units and gas turbines. Their carbon emission quota calculation model can be given by

$$\begin{cases} E_{CET,free,t} = E_{f,free,t} + E_{gt,free,t} \\ E_{f,free,t} = \sum_{m=1}^{n_1} \lambda_e P_{f,m,t} \\ E_{gt,free,t} = \sum_{h=1}^{n_2} \lambda_e P_{gt,e,h,t} \end{cases}$$
(4)

where $E_{CET,free,t}$, $E_{f,free,t}$, and $E_{gt,free,t}$ represent the carbon emission rights of the power system, thermal power units, and gas turbines during time t, respectively. λ_e represents the carbon emission rights for unit power supply. $P_{f,m,t}$ indicates the exportation of thermal power unit m during time t. $P_{gt,e,h,t}$ represents the electrical exportation electricity of gas turbine hduring time t. n_1 and n_2 are the number of thermal power units and gas turbines, respectively.

3.2 Calculation model of actual carbon emissions

The actual carbon emission model in this paper is established according to Chen et al. (2021) and Lu et al. (2023). According to them, the calculation of carbon emission adopts a quadratic function. The constructed actual carbon emission model is given by

$$\begin{cases} E_{CET,a,t} = E_{f,t} + E_{gt,t} \\ E_{f,t} = \sum_{m=1}^{n_1} a_1 P_{f,m,t}^2 + b_1 P_{f,m,t} + c_1 \\ E_{gt,t} = \sum_{h=1}^{n_2} a_2 P_{gt,h,t}^2 + b_2 P_{gt,h,t} + c_2 \end{cases}$$
(5)

where $E_{CET,a,t}$, $E_{f,t}$, and $E_{gt,t}$ are the actual carbon emissions of the power system, thermal power units, and gas turbines at time t, respectively. a_1 , b_1 , and c_1 represent the carbon emission coefficients of the thermal power unit. a_2 , b_2 , and c_2 are carbon emission coefficients of the gas turbine.

The calculation of carbon emission trading volume $E_{CET,t}$ during time *t* is as follows:

$$E_{CET,t} = E_{CET,a,t} - E_{CET,free,t.}$$
(6)

3.3 Calculation model of the timeshare stepped carbon trading cost

Carbon emission trading is conducted in the hourly scale system, and the stepped carbon trading mechanism is adopted. Additionally, the carbon emission reduction compensation price is introduced to incentivize power generation enterprises to actively save energy and reduce emissions. When the total carbon emissions of power generation enterprises remain lower than the incipient carbon emission right, the institution will provide certain cost compensation. The established timeshare stepped carbon transaction cost calculation formula is as follows:

$$f_{CET,t} = \begin{cases} (1 + nv_{CET})\mu_t \left(nl_t^s + E_{CET,t}\right) - \left(n + \frac{n(n-1)}{2}v_{CET}\right)\mu_t l_t^s & E_{CET,t} \le -nl_t^s \\ \vdots & \vdots \\ (1 + 3v_{CET})\mu_t \left(3l_t^s + E_{CET,t}\right) - (3 + 3v_{CET})\mu_t l_t^s & -4l_t^s \le E_{CET,t} \le -3l_t^s \\ (1 + 2v_{CET})\mu_t \left(2l_t^s + E_{CET,t}\right) - (2 + v_{CET})\mu_t l_t^s & -3l_t^s \le E_{CET,t} \le -2l_t^s \\ (1 + v_{CET})\mu_t \left(l_t^s + E_{CET,t}\right) - \mu_t l_t^s & -2l_t^s \le E_{CET,t} \le -l_t^s \\ -\mu_t E_{CET,t} & -l_t^s \le E_{CET,t} \le -l_t^s \\ \xi_t E_{CET} & 0 \le E_{CET,t} \le l_t^p \\ (1 + \sigma_{CET})\xi_t \left(E_{CET,t} - l_t^p\right) + \xi_t l_t^p & l_t^p \le E_{CET,t} \le 2l_t^p \\ (1 + 3\sigma_{CET})\xi_t \left(E_{CET,t} - 3l_t^p\right) + (3 + 3\sigma_{CET})\xi_t l_t^p & 3l_t^p \le E_{CET,t} \le 4l_t^p \\ \vdots & \vdots \\ (1 + n\sigma_{CET})\xi_t \left(E_{CET,t} - nl_t^p\right) + \left(n + \frac{n(n-1)}{2}\sigma_{CET}\right)\xi_t l_t^p & E_{CET,t} \ge nl_t^p \end{cases}$$

$$(7)$$

where $f_{CET,t}$ represents the cost of carbon transaction during time t. ξ_t indicates the carbon trading basic price during time t. μ_t represents the carbon emission reduction compensation basic price during time t. l_t^s denotes the length of the carbon reduction range for selling carbon emission rights at time t. l_t^p represents the length of the carbon transaction range for purchasing carbon emission runge for purchasing carbon emission quotas at time t. σ_{CET} indicates the growth rate of the carbon transaction price. v_{CET} denotes the growth rate of the carbon emission reduction compensation price. When $E_{CET,t} < 0$, the actual carbon emission at time t become less than the free carbon emission right. Excess right is on sale at the carbon reduction compensation price to obtain carbon trading benefits. In conclusion, Eqs 4–7 describe the timeshare stepped carbon trading mechanism.

4 The model of a stepped green certificate trading mechanism

The transaction model for stepwise green certificates involves dividing the overall system green certificate quantity into multiple intervals. Greater trading volumes of green certificates within an interval correspond to increased unit green certificate trading prices, resulting in elevated system costs. Likewise, excess green certificates acquired from integrating RE into the system beyond the green certificate quota of the system can be sold within the green certificate market. The resultant revenue is determined by the prevailing daily selling price. Increased trading volumes within intervals yield higher unit green certificate trading prices, consequently boosting the system revenue. The trading mechanism of the stepped green certificate quota indicator, RE green certificate quantity, and stepped green certificate trading cost calculation models.

4.1 The model of the green certificate quota indicator

According to the regulations of the Chinese government energy department, the sum of the renewable energy consumption (REC)

and green certificate trading volume must not be less than the designated consumption responsibility weight. The green certificate quota is given by

$$E_{GCT,index} = \lambda_{GCT} \sum_{t=1}^{T} \left(P_{load,e,t} + P_{EL,e,t} + P_{ES,e,t}^{cha} + P_{ES,e,t}^{dis} / \eta_{ES,e}^{dis} \right), \quad (8)$$

where $\eta_{ES,e}^{dis}$ is the discharge efficiency. $E_{GCT,index}$ is the green certificate quota indicator of systems. λ_{GCT} is the green certificate quota coefficient. $P_{load,e,t}$ represents the electric load during time t. $P_{EL,e,t}$ denotes the alkaline electrolyzer output at time t. $P_{ES,e,t}^{cha}$ represents the electricity of charging at time t. $P_{ES,e,t}^{dis}$ denotes the electricity of discharging at time t. T represents the scheduling period.

4.2 The model of renewable energy green certificate quantity

The conversion of REC into the quantity of green certificates is set as 1 kWh, where 1 kWh of settled electricity corresponds to 1 green certificate.

$$E_{GCT,a} = \sum_{t=1}^{T} (P_{WT,t} + P_{PV,t}),$$
(9)

where $E_{GCT,a}$ represents the quantity of green certificates obtained from REC. $P_{WT,t}$ represents the actual wind power output at time *t*. $P_{PV,t}$ represents the actual exportation of PV during time *t*.

4.3 The model of stepped green certificate trading cost calculation

The trading mechanism for gradual green certificates includes using a gradual pricing mechanism to divide the number of certificates into intervals. As the quantity of certificates to be bought or sold increases, the unit green certificate trading price in the corresponding interval increases. The established model for calculating the costs of tiered green certificate trading is as follows:

$$E_{GCT} = E_{GCT,index} - E_{GCT,a},$$
(10)
$$= \begin{cases}
(1 + n\sigma_{GCT})c_{GCT} (n_{GCT} + E_{GCT}) - \left(n + \frac{n(n-1)}{2}\sigma_{GCT}\right)c_{GCT}l_{GCT} & E_{GCT} \le -nl_{GCT} \\
\vdots & \vdots \\
(1 + 3\sigma_{GCT})c_{GCT} (3l_{GCT} + E_{GCT}) - (3 + 3\sigma_{GCT})c_{GCT}l_{GCT} & -4l_{GCT} \le E_{GCT} \le -3l_{GCT} \\
(1 + 2\sigma_{GCT})c_{GCT} (2l_{GCT} + E_{GCT}) - (2 + \sigma_{GCT})c_{GCT}l_{GCT} & -3l_{GCT} \le E_{GCT} \le -2l_{GCT} \\
(1 + \sigma_{GCT})c_{GCT} (l_{GCT} + E_{GCT}) - c_{GCT}l_{GCT} & -2l_{GCT} \le E_{GCT} \le -1c_{GCT} \\
(1 + \sigma_{GCT})c_{GCT} (l_{GCT} + E_{GCT}) - c_{GCT}l_{GCT} & -2l_{GCT} \le E_{GCT} \le 0 \\
-c_{GCT}E_{GCT} & 0 \le E_{GCT} \le L_{GCT} \\
(1 + \sigma_{GCT})c_{GCT} (E_{GCT} - 1c_{GCT}) + c_{GCT}l_{GCT} & 1c_{GCT} \le E_{GCT} \le 2l_{GCT} \\
(1 + 3\sigma_{GCT})c_{GCT} (E_{GCT} - 2l_{GCT}) + (2 + \sigma_{GCT})c_{GCT}l_{GCT} & 2l_{GCT} \le 2l_{GCT} \\
(1 + 3\sigma_{GCT})c_{GCT} (E_{GCT} - 3l_{GCT}) + (3 + 3\sigma_{GCT})c_{GCT}l_{GCT} & 3l_{GCT} \le E_{GCT} \le 4l_{GCT} \\
\vdots & \vdots \\
(1 + n\sigma_{GCT})c_{GCT} (E_{GCT} - nl_{GCT}) + \left(n + \frac{n(n-1)}{2}\sigma_{GCT}\right)c_{GCT}l_{GCT} & E_{GCT} \ge nl_{GCT} \le nl_{GCT} \end{aligned}$$
(11)

where E_{GCT} is the green certificate trading volume of the system. F_{GCT} is the cost of the green certificate transaction. c_{GCT} represents the base price of certificate trading. l_{GCT} is the interval length of certificate trading. σ_{GCT} is the growth rate of certificate trading. When $E_{GCT} < 0$,

it indicates that the quantity of green certificates obtained from the consumption of REC in the system exceeds the green certificate quota. Certificates are on sale at the certificate trading price to obtain green certificate trading revenue. In conclusion, Eqs 8–11 describe the model of a stepped green certificate trading mechanism.

5 Two-stage scheduling model for the power system considering the demand response under multiple uncertainties

5.1 The optimization model of the first stage

5.1.1 Objective function

The side of the load cluster adjusts the response quantity of the electric load based on the DR incentive strategy to maximize energy efficiency.

$$\max C_L = C_{dr} - C_{dr}^{\dagger},\tag{12}$$

where C_L is the energy efficiency on the side of the load cluster. C_{dr} is the compensation benefit for DR. C_{dr}^{\dagger} is the response cost on the side of the load cluster.

(1) The compensation benefit for demand response

Traditional DR usually uses fixed compensation prices, which can lead to low user responsiveness. To more efficiently stimulate user participation in DR and optimize the running scheme on the basis of demand-side flexibility resources, a model of stepped DR compensation cost calculation is established. According to the DR quantity of users, the model specifies multiple DR intervals, where the compensation price increases with the DR quantity in each interval. The model of stepped DR compensation cost calculation is as follows:

$$C_{dr} = \begin{cases} \mu_{el} P_{el,dr}^{sum}, P_{el,dr}^{sum} \le m_{el} \\ \mu_{el} m_{el} + (1 + \nu_{el}) \mu_{el} (P_{el,dr}^{sum} - m_{el}), \\ m_{el} \le P_{el,dr}^{sum} \le 2m_{el} \\ (2 + \nu_{el}) \mu_{xl} m_{xl} + (1 + 2\nu_{xl}) \mu_{xl} (P_{xl,dr}^{sum} - 2m_{xl}), \\ 2m_{el} \le P_{el,dr}^{sum} \le 3m_{el} \\ (3 + 3\nu_{el}) \mu_{el} m_{el} + (1 + 3\nu_{el}) \mu_{el} (P_{el,dr}^{sum} - 3m_{el}), \\ 3m_{el} \le P_{el,dr}^{sum} \le 4m_{el} \\ (4 + 6\nu_{el}) \mu_{el} m_{el} + (1 + 4\nu_{el}) \mu_{el} (P_{el,dr}^{sum} - 4m_{el}), \\ P_{el,dr}^{sum} \ge 4m_{el} \end{cases}$$
(13)

where μ_{el} represents the basic price of DR compensation, which is set as 20 yuan/MW. ν_{el} is the rate of increase in the DR price, which is set as 0.1. m_{el} represents the quantity range length of DR, which is set as 150 MW. $P_{el,dr}^{sum}$ is the total power at which the electrical load participates in DR within one scheduling period.

Moreover, the model of traditional DR compensation cost calculation is as follows:

$$C_{dr} = \mu_{el} P^{sum}_{el,dr}.$$
 (14)

(2) The cost of response.

The participation of users in DR will incur discomfort cost, which can be calculated as a quadratic function of the load response amount.

$$C_{dr}^{\dagger} = \sum_{t=1}^{T} \left[\varepsilon_{el} \left(P_{e1,dr} \left(t \right) \right)^2 \right], \tag{15}$$

where ε_{el} is the discomfort coefficient participating in DR, and its magnitude is determined by the energy consumption habits of users. $P_{el,dr}(t)$ is the electricity load participating in DR at time t.

5.1.2 Constraint condition

(1) Load-related constraints

The response types considered in this paper for electrical load include transferable load and reducible load.

$$P_{el}(t) = P_{el}^{o}(t) + P_{el}^{tran}(t) - P_{el}^{cut}(t),$$
(16)

where $P_{el}(t)$ represents the load quantity after participating at time t in the DR plan. $P_{el}^{o}(t)$ represents the initial load quantity at time t. $P_{el}^{tran}(t)$ is the transferred load quantity at time t when the electrical load participates in DR. $P_{el}^{cut}(t)$ is the reduced load quantity at time t when the electrical load participates in DR.

(2) Transferable load constraint

$$\begin{cases} P_{el}^{tran}(t) = \xi_{el,in}^{tran}(t)P_{el,in}^{tran}(t) - \xi_{el,out}^{tran}(t)P_{el,out}^{tran}(t) \\ 0 \le \xi_{el,in}^{tran}(t) + \xi_{el,out}^{tran}(t) \le 1 \\ \sum_{t=1}^{T} P_{el}^{tran}(t) = 0 , \qquad (17) \\ 0 \le P_{el,in}^{tran}(t) \le P_{el,out} \overset{\text{max}}{\text{max}}(t) \\ 0 \le P_{el,out}^{tran}(t) \le P_{el,out} \overset{\text{max}}{\text{max}}(t) \end{cases}$$

where $P_{el,in}^{tran}(t)$ and $P_{el,out}^{tran}(t)$ represent the power that the load can transfer in and out at time *t*, respectively. $\xi_{el,in}^{tran}(t)$ and $\xi_{el,out}^{tran}(t)$ are binary variables. $\xi_{el,in}^{tran}(t) = 1$ denotes the power transferred in. $\xi_{el,out}^{tran}(t) = 1$ denotes the power transferred out. $P_{el,in}^{max}(t)$ represents the upper bound of the electricity load transferred in. $P_{el,out}^{max}(t)$ is the upper limit of the electric load transferred out at time *t*. In Eq. 17, the first two lines ensure that a certain type of load will neither transfer in nor transfer out during the same time period. The third line ensures that the entire demand of the load keeps unchanged within one scheduling cycle.

(3) Reducible load constraints

Some loads can be reduced while satisfying user demands. The constraint for the reducible electric load can be given by

$$0 \le P_{el}^{cut}(t) \le \xi_{el}^{cut}(t) P_{el,o}^{cut}(t),$$
(18)

where $\xi_{el}^{cut}(t)$ is the binary variable. $\xi_{el}^{cut}(t) = 1$ denotes that the power is reduced of the load. $P_{xl,o}^{cut}(t)$ represents the upper bound that the load can be reduced at time *t*.

(4) Constraints on the total power involved in DR

Within one scheduling cycle, the total transferred power of transferrable loads entering is equal to the total transferred power of loads exiting. To avoid duplicate compensation, the total response power of transferrable loads is calculated based on the total entering power or the total exiting power. Here, we choose to calculate it based on the total exiting power. Therefore, the total power $P_{el,dr}(t)$

of the electric load participating in DR within one scheduling cycle is given by

$$P_{el,dr}(t) = P_{el,out}^{rran}(t) + P_{el}^{cut}(t)$$

$$P_{el,dr}^{sum} = \sum_{t=1}^{T} P_{el,dr}(t)$$
(19)

In conclusion, Eqs 12–15 describe the objective function., and Eqs 16–19 describe the constraint condition in the optimization model of the first stage.

5.2 The optimization model of the second stage

5.2.1 Objective function

In a typical scenario involving wind power, PVs, and load, the objective function on the basis of the green certificate carbon trading model is as follows:

$$\min F = \min \left(C_T + C_{ope} + F_{GCT} + F_{CET} \right), \tag{20}$$

where *F* represents the entire cost of the system. C_T represents the thermal power generation cost. C_{ope} represents the equipment running cost. F_{GCT} represents the green certificate transaction cost. F_{CET} represents the carbon transaction cost.

Additionally, the power generation cost calculation expression is given by

$$C_{\rm T} = \sum_{m=1}^{n_1} \sum_{t=1}^{T} \left(a P_{m,t}^2 + b P_{m,t} + c \right), \tag{21}$$

where *a*, *b*, and *c* are the cost coefficients of thermal power units. The expression for calculating device running costs is

$$C_{ope} = \sum_{t=1}^{T} \begin{pmatrix} c_{WT} P_{WT,t} + c_{PV} P_{PV,t} + c_{gt} P_{gt,t} + c_{EL} P_{EL,e,t} \\ + c_{MG} P_{MG,H_{2},t} + c_{HFC} P_{HFC,H_{2},t} + \sum_{n=1}^{5} c_{ES,n} \left(P_{ES,n,t}^{cha} + P_{ES,n,t}^{dis} \right) \end{pmatrix},$$
(22)

where c_{WT} , c_{PV} , c_{gt} , c_{EL} , c_{MG} , c_{HFC} , and c_{GB} represent the unit running costs of wind power, PV, gas turbine, electrolyzers, methane generators, hydrogen fuel cells, and gas boilers in the park, respectively. c_{ESn} represents the unit running costs of a storage battery.

5.2.2 Constraint condition 5.2.2.1 Power flow calculations

The development of its computational methods is closely linked to the advancement of computer tools. For an *n*-node power system, the polar coordinate form of the node injection power equation is as follows (Liu et al., 2020c; Liu et al., 2022):

$$\begin{cases} P_i = V_i \sum_{j \in i} V_j (G_{ij} \cos \theta_{ij} + B_{ij} \sin \theta_{ij}) \\ Q_i = V_i \sum_{j \in i} V_j (G_{ij} \sin \theta_{ij} - B_{ij} \cos \theta_{ij}), \end{cases}$$
(23)

where P_i and Q_i represent the active power and reactive power specified for node *i*, respectively. $j \in i$ denotes the nodes adjacent to node *i*, including the case where j = i. G_{ij} and B_{ij} represent the mutual conductance and susceptance between nodes *i* and *j*, respectively. V_i and V_j represent the voltage magnitude of nodes *i* and *j*, respectively. θ_{ij} represents the voltage phase difference between node *i* and node *j*. Due to the nonlinearity of the power flow equation in Eq. 22, it requires iterative solutions until convergence is achieved. Once the amplitude and the phase angle of node voltages are obtained, the branch power flow can be computed by

$$\begin{cases}
P_{ij} = V_i V_j (G_{ij} \cos \theta_{ij} + B_{ij} \sin \theta_{ij}) - V_i^2 G_{ij} \\
Q_{ij} = -V_i V_j (B_{ij} \cos \theta_{ij} - G_{ij} \sin \theta_{ij}) + V_i^2 B_{ij},
\end{cases} (24)$$

where P_{ij} and Q_{ij} represent the active power and the reactive power flow of branches *i* and *j*, respectively.

In the scenario of direct current, Eqs 23, 24 can be simplified, and the simplification procedure is as follows:

- (1) The voltage at per hybrid in a running system is generally near the specified voltage, and $V_i = V_j = 1$ can be approximated.
- (2) The voltage phase angle difference between the two ends of the line is very small, resulting in θ_{ij} ≈ 0. Thus, sin θ_{ij} = θ_{ij} and cos θ_{ij} = 1.
- (3) In ultra-high voltage networks, the resistance of the line is smaller than the reactance, allowing us to neglect the resistance, represented by $r_{ij} = 0$. Therefore, Eq. 24 can be simplified to

$$\begin{cases} P_{ij} = -b'_i (\theta_i - \theta_j) = (\theta_i - \theta_j) / x_{ij}, \\ Q_{ij} = 0 \end{cases}$$
(25)

where $b'_{ij} = -1/x_{ij}$. x_{ij} represents the resistance of the transmission line. θ_i and θ_j denote the voltage phase angles of nodes *i* and *j*, respectively.

The network of n nodes is written in matrix form as follows:

$$\boldsymbol{P}^{SP} = \boldsymbol{B}\boldsymbol{\theta},\tag{26}$$

where P^{SP} is the power injection matrix of active power for *n* nodes in the network. *B* represents an *n*-order matrix.

$$P_{i}^{SP} = \sum_{j \in i, j \neq i} P_{ij} = \sum_{j \in i, j \neq i} \frac{\theta_{i} - \theta_{j}}{x_{ij}},$$

$$\begin{cases} B_{ii} = \sum_{j \in i, j \neq i} 1 / x_{ij} \\ B_{ij} = -1 / x_{ij} \end{cases}.$$
(27)

5.2.2.2 Energy equipment constraints

1) Wind power

$$0 \le P_{WT,t} \le P_{WT,t}^{pre}.$$
(29)

2) Photovoltaic

$$0 \le P_{PV,t} \le P_{PV,t}^{pre},\tag{30}$$

where $P_{WT,t}$ and $P_{PV,t}$ represent the actual output of wind power and PV at time *t*, respectively. $P_{WT,t}^{pre}$ and $P_{PV,t}^{pre}$ represent the upper limit of wind power and PV at time *t*, respectively.

5.2.2.3 Energy conversion equipment output and climbing constraints

1) Gas turbine

$$\begin{cases} P_{GT,g}^{\min} \le P_{GT,g,t} \le P_{GT,g}^{\max} \\ \Delta P_{GT,g}^{\min} \le P_{GT,g,t+1} - P_{GT,g,t} \le \Delta P_{GT,g}^{\max}, \end{cases}$$
(31)

where $P_{GT,g}^{\min}$ and $P_{GT,g}^{\max}$ represent the ceiling and prescribed minimum of the natural gas consumed by the gas turbine, respectively. $\Delta P_{GT,g}^{\min}$ and $\Delta P_{GT,g}^{\max}$ represent the upper and lower bound of natural gas used by the gas turbine during ramping, respectively.

2) Alkaline electrolyzer

$$\begin{cases}
P_{EL,e}^{\min} \leq P_{EL,e,t} \leq P_{EL,e}^{\max} \\
\Delta P_{EL,e}^{\min} \leq P_{EL,e,t+1} - P_{EL,e,t} \leq \Delta P_{EL,e}^{\max},
\end{cases}$$
(32)

where $P_{EL,e}^{\min}$ and $P_{EL,e}^{\max}$ represent the upper and lower bound of electricity consumed by the alkaline electrolyzer, respectively. $\Delta P_{EL,e}^{\min}$ and $\Delta P_{EL,e}^{\max}$ represent the upper and lower bound of electricity used by the alkaline electrolyzer during ramping, respectively.

3) Methane generator

$$\begin{cases} P_{MG,g}^{\min} \le P_{MG,g,t} \le P_{MG,g}^{\max} \\ \Delta P_{MG,g}^{\min} \le P_{MG,g,t+1} - P_{MG,g,t} \le \Delta P_{MG,g}^{\max} \end{cases}$$
(33)

where $P_{MG,g}^{\min}$ and $P_{MG,g}^{\max}$ represent the upper and lower bound of electricity consumed by the methane generator, respectively. $\Delta P_{MG,g}^{\min}$ and $\Delta P_{MG,g}^{\max}$ represent the upper and lower bound of electricity consumed by the methane generator during ramping, respectively.

4) Hydrogen fuel cell

$$\begin{cases} P_{HFC,H_2}^{\min} \leq P_{HFC,H_2,t} \leq P_{HFC,H_2}^{\max} \\ \Delta P_{HFC,H_2}^{\min} \leq P_{HFC,H_2,t+1} - P_{HFC,H_2,t} \leq \Delta P_{HFC,H_2}^{\max}, \end{cases}$$
(34)

where P_{HFC,H_2}^{\min} and P_{HFC,H_2}^{\max} represent the upper and lower bound of electricity consumed by the hydrogen fuel cell, respectively. $\Delta P_{HFC,H_2}^{\min}$ and $\Delta P_{HFC,H_2}^{\max}$ represent the upper and lower bound of electricity consumed by the hydrogen fuel cell during ramping, respectively.

5) Energy storage

The energy storage equipment model is given by Zhao et al. (2019), Huang et al. (2021)

$$\begin{cases} 0 \le P_{ES,n,t}^{cha} \le B_{ES,n,t}^{cha} P_{ES,n,max}^{cha} \\ 0 \le P_{ES,n,t}^{dis} \le B_{ES,n,t}^{dis} P_{ES,n,max}^{dis} \\ E_n(t+1) = E_n(t) + \left(P_{ES,n,t}^{cha} \eta_{char} - P_{ES,n,t}^{dis} / \eta_{dis}\right) \Delta t , \qquad (35) \\ E_{n,1} = E_{n,25} \\ E_n^{\min} \le E_{n,t} \le E_n^{\max} \end{cases}$$

where $P_{ES,n,t}^{cha}$ and $P_{ES,n,t}^{dis}$ represent the charge and discharge electricity of the battery, respectively. $B_{ES,n,t}^{cha}$ and $B_{ES,n,t}^{dis}$ represent binary variables for the charge and discharge states of the energy storage equipment, respectively. Δt is the unit time period. $P_{ES,n,\max}^{cha}$ and $P_{ES,n,\max}^{dis}$ represent the upper bound of charge and discharge electricity of the energy storage equipment in a single operation, respectively. $E_{n,t}$ is the volume of the energy storage equipment. E_n^{\max} and E_n^{\min} represent the upper and lower bound of the storage equipment volume, respectively. η_{char} is the charge efficiency.

In conclusion, Eqs 20–22 describe the objective function., and Eqs 23–35 describe the constraint condition in the optimization model of the second stage.





5.3 Optimization process of a twostage model

Considering DR under multiple uncertainties, the architecture of the two-stage scheduling method of the power system is shown in Figure 1. Based on predictive scenarios and load response capabilities, the dispatch center optimizes the load structure in the first phase. The load is

divided into fixed and flexible components with the goal of maximizing user energy efficiency. In the second stage, the model introduces green certificate transaction and carbon transaction mechanisms with the goal of minimizing the comprehensive running costs for unit output planning in typical scenarios. The detailed process of scheduling plan formulation is as follows:

Step1: The basic information about the system covering PV and wind power output, forecasted electricity load, and equipment parameters is input.

Step2: A large set of sampling scenarios that conform to the probability distributions of load, wind power, and PV is generated using LHS.

Step3: The heuristic synchronous backtracking method is used for scenario reduction to obtain a small number of representative typical scenarios, along with their probabilities.

Step4: *Gurobi* is used to seek the solution of the first-stage optimal model and determine the corresponding response strategy that maximizes energy efficiency.

Step5: The improved stepped pricing is used to calculate the green certificate trading cost. Then, a stepped green certificate transaction model is introduced, and a green certificate carbon transaction model is jointly built by incorporating a time-of-use stepped carbon trading mechanism. The second-stage unit output plan is optimized with the goal minimizing the overall running costs in typical scenariosl.



6 Case study

6.1 Basic data

An improved IEEE 14-node transmission network is used for analysis and verification. Due to the fact that the power network used in this paper belongs to the transmission network, it can meet the relevant simplification of the DC power flow explained in Section 5.2.2. Therefore, the model established in this paper is applicable to any transmission network that satisfies the simplification of the DC power flow and is not limited to the power grid system model used in the example section. The topology of the power system is shown in Figure 2. The scene reduction outcomes are shown in Figures 3-5. The base value is set as 100 MW. Table 1 outlines the parameters of thermal power units. Table 2 presents the parameters of other equipment. Furthermore, Table 3 delineates the parameters of carbon emissions. The carbon emission quota per unit of electricity generated stands at 0.798 t/(MWh), and for per unit of thermal power generated, it stands at 0.385 t/(MWh). The foundational price for carbon emission compensation stands at 252 yuan/t. The carbon trading price experiences a growth rate of 25%, and the green certificate quota coefficient is fixed at 50%. The foundational price for green certificate transactions is 0.4 yuan, with a growth rate of 25%.

6.2 Analysis of the demand response

In this section, the advantages of DR are discussed. Three different scenarios are set up, which are as follows:.

Scenario a: Not considering DR.

Scenario b: Considering traditional DR with a certain compensation price.

Scenario c: Considering ladder-type DR with varying compensation price.





Table 4 shows that scenario b experiences a reduction of 107.199 million yuan in operating costs compared to scenario a, leading to an overall cost decrease of 107.1589 million yuan. Moreover, a decrease of 222.63 metric tons in carbon emissions and a reduction of 38.56 MW in the variance between electric load peaks and valleys occur. This verifies that the incentive mechanism for DR significantly reduces total costs, carbon emissions, and electric load variances.

Despite scenario c incurring DR compensation costs exceeding 26,000 yuan, it results in a reduction of 15.4828 million yuan in overall costs and a decrease of 17.82 metric tons in carbon emissions. Regarding the DR rate, scenario b achieves a rate of only 67.96%, whereas scenario c attains a rate of 95.14%, marking a 27.18% increase over scenario b. Additionally, the variance between electric load peaks and valleys decreases by 12 MW, verifying that the incentive mechanism based on a ladder-type structure not only effectively encourages user participation but also considers the economic, low-carbon, and peak load shifting aspects of power system operation.

TABLE 1 Parameters of the coal-fired power unit.

Unit number	Cost coefficient <i>a/b/c</i> (yuan/MW ²)/(yuan/MW)/ yuan	Upper and lower limits of power output/pu	Climbing speed/ (pu/h)	Carbon emission intensity/(t/MWh)
G1	0.005/280/500	1.20/0.06	0.240	1.21
G2	0.003/390/400	0.72/0.036	0.144	1.15
G3	0.0047/380/250	0.48/0.024	0.096	0.97
G4	0.003/400/300	0.96/0.048	0.192	1.08
G5	0.002/420/100	5.00/0.250	1.000	1.30

TABLE 2 Parameters of other equipment.

Equipment	Upper limit of output/pu	Climbing speed/(pu/h) Conversion efficiency		Operation cost/(yuan/kWh)	
ES1	0.5	0.15	0.98	0.0180	
ES2	0.5	0.15	0.98	0.0170	
ES3	1.0	0.30	0.98	0.0120	
ES4	1.0	0.30	0.98	0.0220	
H ₂ S	1.5	0.45	0.98	0.0550	
GT1	0.5	0.1	0.3	0.0251	
GT2	0.5	0.1	0.3	0.0251	
EL	1.5	0.3	0.87	0.0525	
HFC	2.0	0.4	0.95	0.0286	
MR	1.5	0.3	0.83	0.0587	

TABLE 3 Parameters of carbon emissions.

a ₁	b1	C ₁	a ₂	b ₂	C ₂
36	-0.38	0.0034	3	-0.04	0.001

Figure 6 shows that the peak electric load predominantly occurs between 10:00 and 22:00. Implementing the ladder-type DR incentive mechanism resulted in a reduction in the electric load during this timeframe. Specifically, a shift in the electric load from the periods of 10:00–14:00 and 19:00–22:00 to the period of 24: 00–04:00 occurred, coinciding with a lower energy demand. This initiative achieved a reduction of 108 MW in the electric load and a transfer of 165.44 MW, effectively smoothing the electric load curve. Concurrently, this strategy involved transferring electric load from high-priced daytime periods to lower-priced nighttime periods, thereby reducing operational costs within the power system.

6.3 Analysis of low-carbon economy

In this section, so as to effectively analyze the benefits of the proposed model regarding low carbon emissions and economy, four scenarios are arranged.

Scenario 1: The transaction volume of green certificates is not divided, and DR is not considered. The setting of the certificate

transaction price is unified. Objectives are optimized by considering the costs of purchasing energy, equipment running, and green certificate trading.

Scenario 2: Green certificate transaction is divided. DR is not considered. Objectives are optimized by considering the costs of energy purchase, equipment running, and green certificate trading.

Scenario 3: Stepped green certificate transaction and timesharing stepped carbon transaction are considered. DR is not considered. Objectives are optimized by considering the costs of purchasing energy, equipment running, green certificate trading, and carbon transaction.

Scenario 4: Stepped green certificate transaction and timesharing stepped carbon transaction are taken into account. DR is considered. Objectives are optimized by considering the costs of purchasing energy, equipment running, green certificate trading, and carbon transaction.

Table 5 shows the scheduling results of power system in different scenarios. The benefits of tiered green certificate trading are compared and analyzed through scenario 1 and scenario 2. As is shown in Table 5 Scenario 2 exhibits a reduction of 16.85 metric tons in carbon emissions compared to scenario 1. Additionally, scenario 2 records a decrease of 67,000 yuan in carbon transaction costs relative to scenario 1. Conversely, the transaction costs for green cards in scenario 2 escalate by 66.72 million yuan compared to scenario 1. This increase is attributed to the adoption of a ladder-type green card trading mechanism featuring a pricing structure

Scenario	Compensation cost/yuan	Carbon User response emission/t enthusiasm/%		Operation cost/yuan	Peak-to-valley difference/MW	Total cost/ yuan
a	\ 2,875		1	$106,073.20 \times 10^4$	295.73	$106,073.20 \times 10^4$
b	3.91×10^{4}	2,652.93	67.96	$95,353.40 \times 10^4$	257.17	$95,357.31 \times 10^4$
с	6.51×10^{4}	2,635.11	95.14	93,802.53 $\times 10^4$	245.17	93,809.03 × 10^4

TABLE 4 Dispatch results of three models.

TABLE 5 Power system scheduling results in different scenarios.

Scenario	Carbon emission/t	Carbon trading cost/yuan	Green certificate transaction cost/yuan	Renewable energy consumption rate/%	Power production cost/yuan	Operation cost/yuan	Total cost/ yuan
1	2,875.68	47.86×10^{4}	40.09×10^{4}	91.36	$106,041.41 \times 10^4$	23.34×10^4	$106,152.70 \times 10^{4}$
2	2,858.83	47.19×10^{4}	106.81×10^{4}	97.96	106,298.51 × 10 ⁴	25.23×10^4	$106,477.74 \times 10^4$
3	2,854.32	46.74×10^{4}	106.21×10^{4}	100.00	$106,041.42 \times 10^4$	25.79×10^4	$106,220.16 \times 10^4$
4	2,624.11	41.45×10^{4}	89.67 × 10 ⁴	100.00	93,583.39 × 10 ⁴	25.55×10^4	93,746.58 × 10 ⁴



with higher unit green certificate transaction prices within corresponding intervals. Notably, scenario 2 demonstrates a 6.60% increase in REC compared to scenario 1. These findings support the assertion that the implementation of stepped green certificate transactions offers superior advantages over traditional methods in reducing system carbon emissions and enhancing REC rates.

The case examines the advantages of the joint mechanism involving green certificates and carbon trading using scenarios 2 and 3. Scenario 3 exhibits a 4.51-ton reduction in carbon emissions compared to scenario 2. Moreover, it exhibits a decrease of 45,000 yuan in carbon transaction costs, and a

reduction of 6,000 yuan in green certificate transaction expenses relative to scenario 2. Overall, scenario 3 demonstrates a notable decrease of 2.5758 million yuan in total costs in contrast to scenario 2. This analysis suggests that incorporating carbon transaction costs into the objective function led to a reduction in system carbon emissions. Furthermore, it resulted in decreased carbon and green certificate transaction expenses, contributing to a whole diminution in entire costs.

Analysis of benefits derived from the DR mechanism is conducted in relation to scenarios 3 and 4. Scenario 4 demonstrates a reduction of 230.21 metric tons in carbon emissions compared to scenario 3. Additionally, scenario 4 displays a decrease in carbon transaction costs by 52,900 yuan and a reduction in the transaction cost of green certificates by 165.4 thousand yuan compared to scenario 3. The overall cost difference illustrates a decrease of 124.7358 million yuan between scenario 4 and scenario 3. Evidently, the incorporation of the DR mechanism effectively mitigates carbon emissions within the power system. Furthermore, the optimization of DR, in conjunction with green certificate and carbon trading mechanisms, aligns with the objective of achieving a low-carbon economy in power system dispatching.

7 Conclusion

In pursuit of low carbon emissions and promoting the absorption of RE while addressing risks posed by multiple uncertainties to the system, a management approach considering uncertainties and DR for the power system was proposed. The primary aim was to facilitate enhanced low-carbon economic operations. First, taking the multiple uncertainties of RE and electric load into account, a large number of scenarios were

formed using LHS. By using the heuristic synchronous back substitution approach to achieve centralized reduction, multiple typical scenarios and their probabilities of PV and load were obtained. Furthermore, a joint market mechanism model of green certificate transaction and carbon transaction was developed, which was applied to promote REC, thus reducing carbon emission. Considering the active response of users, a stepped DR incentive mechanism was constructed on the basis of the transferable and reducible characteristics of electric load. Subsequently, a two-stage optimization dispatch model was constructed with the objective function of both maximizing user energy efficiency and minimizing system operating cost. Finally, the case results showed that carbon dioxide emissions were decreased by 251.57 metric tons, the REC rate was increased by 8.64%, and the total cost was reduced by 124.0612 million yuan. Compared with the model that only considers the traditional green certificate mechanism, the method developed here could significantly promote the economy and low-carbon operation of the power system.

With the ongoing expansion of the energy market, the threshold for engaging in energy trading is progressively diminishing, leading to the continual emergence of diverse market trading models and varieties. The focus will shift toward optimizing the representation of energy commodity attributes, enabling seamless and extensive transactions among diverse entities. This stands as the forthcoming research trajectory.

Data availability statement

The original contributions presented in the study are included in the article/Supplementary Material; further inquiries can be directed to the corresponding author.

Author contributions

LC: conceptualization, data curation, formal analysis, funding acquisition, investigation, methodology, project administration, resources, software, supervision, validation, visualization, writing-original draft, and writing-review and editing. DX:

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Conflict of interest

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