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# Floating debris dynamics in a tidal strait: transport and retention in Sundklakkstraumen, Lofoten

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Understanding the transport and retention of floating plastic debris in fjords and coastal systems is essential for targeted mitigation strategies. This study investigates surface transport dynamics in Storvika and Sundklakkstraumen, a tidally energetic system in the Lofoten archipelago, Northern Norway. We combine GPS-tracked drifter observations with high-resolution 2D and 3D hydrodynamic modeling to assess how tidal forcing shapes transport pathways, convergence zones, and debris retention. Field deployments during spring and neap tides revealed strong contrasts in particle behavior, with spring tides promoting rapid flushing along energetic channels and neap tides supporting localized recirculation and short-term retention. The 3D model outperformed the 2D configuration in resolving sub-basin features, achieving skill scores of ss =0.833 compared to 0.804, and reproducing trajectory structures with endpoint errors under 100 meters. Retention zones increased significantly during weaker tidal forcing relative to strong tidal forcing, with a 40% increase in attracting Lagrangian Coherent Structures and a 50% rise in domain-wide flush-out time. Residence time, revisit probability, and flow structure metrics consistently indicated higher retention during neap tide. Spatial diagnostics identified three possible accumulation hotspots, primarily active under neap conditions, accounting for over 40% of total residence time while occupying only  $\sim$  20% of the basin area. Low kinetic energy, reduced transport efficiency, and strongly attracting FTLE structures characterized these zones. The combined modelingobservation approach highlights the dominant role of the tidal phase in modulating short-term transport versus the temporary entrapment of debris. While the model excludes wind, waves, and high-frequency runoff events, the sheltered nature of the domain and minimal river influence limit their significance in this setting. This validated multi-diagnostic approach provides a transferable methodology for assessing retention in similarly complex coastal environments, supporting pollution mitigation, aquaculture planning, and operational forecasting efforts.

#### KEYWORDS

tidal dynamics, Lagrangian transport, marine debris, hydrodynamic modeling, fjord circulation, convergence zones, drifters, retention hotspots

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## **1** Introduction

Marine plastic pollution is a pervasive global environmental challenge, driven by the continued increase in annual plastic waste production (Lebreton and Andrady, 2019). Plastics persist in aquatic environments for centuries, causing significant ecological and socio-economic impacts (Thompson et al., 2009). Between 1990 and 2015, approximately 90 million tons of plastic waste entered the world's oceans (Bellou et al., 2021). Plastic waste is widely distributed, reaching remote regions via ship leakage and large-scale oceanic currents (Van Sebille et al., 2012). Over time, plastics fragment into microplastics, which are found in various marine species consumed by humans, raising concerns about food safety and human health (Cózar et al., 2014).

Coastal regions are particularly vulnerable to plastic accumulation, as marine litter is transported and deposited by tides, currents, and meteorological forces. Clean-up initiatives aim to address this issue, but beaches often serve as transient reservoirs where plastics accumulate temporarily before being resuspended. Pawlowicz (2021) analyzed trajectories from a large number of GPS-tracked drifters in the Salish Sea and found that the drifters tended to ground soon after entering nearshore zones. They hypothesized that the drifter's approach towards the shoreline was primarily controlled by ocean currents rather than direct wind or wave forcing and described this process as diffusive. Similarly, Adame et al. (2025) used high-resolution drift simulations along the Australian coast to show rapid beaching of marine plastics due to oceanic transport processes.

Understanding nearshore plastic transport dynamics is crucial for predicting debris pathways and developing effective mitigation strategies (Van Sebille et al., 2015). Coastal areas are key accumulation zones where local hydrodynamic structures strongly influence plastic retention. Identifying these retention mechanisms is essential for optimizing clean-up efforts and reducing the impact of plastic pollution in marine ecosystems (Haarr et al., 2024). Certain coastal sites exhibit prolonged retention of plastic debris, suggesting that geophysical factors such as local circulation patterns play a critical role in accumulation. Hydrodynamic ocean models are valuable tools for predicting transport pathways and supporting strategic cleanup operations.

Recent studies by Solbakken et al. (2022) and Haarr et al. (2024) investigated plastic retention at beaches in the Lofoten archipelago, Northern Norway, highlighting the presence of local recirculation features acting as small-scale retention traps. A summary of debris composition and potential sources observed at Storvika is provided in Appendix B. These studies recommend applying ocean models to understand plastic retention mechanisms and trace the origins of marine debris. Building on this, we implement a widely used coastal ocean model focused on the Lofoten region, with particular emphasis on resolving strong tidal currents (up to 2 ms<sup>-1</sup>) that influence floating debris transport (see, e.g., Børve et al., 2021, 2025).

Global-scale modeling studies have identified coastal zones as key areas for plastic accumulation (Onink et al., 2021), yet these efforts often rely on coarse-resolution models that oversimplify critical processes such as beaching, shoreline retention, and nearshore transport (Hernandez et al., 2025). The transport dynamics of floating marine debris in coastal environments remain insufficiently understood, largely due to the geometric complexity and unresolved fine-scale processes that dominate in nearshore regions (Hernandez et al., 2024). High-resolution models are therefore essential for capturing the intricate bathymetry, submesoscale vortices, and dispersive transport mechanisms that strongly influence particle drift and accumulation patterns (Saint-Amand et al., 2023; Ward et al., 2023).

In this study, we apply a high-resolution unstructured grid model (Ghaffari et al., 2019; Børve et al., 2025; Espenes et al., 2023) to resolve the flow field of a high-latitude fjord system in northern Norway. Focusing on a tidally energetic basin with previously documented plastic deposition (Solbakken et al., 2022; Haarr et al., 2024), we integrate model simulations with targeted field observations to assess the system's capacity for debris retention. Two hydrodynamic configurations, a depth-integrated 2D barotropic model and a fully resolved 3D model, were developed and validated to simulate the dominant flow structures. These velocity fields were subsequently coupled with a Lagrangian particle tracking model to examine debris transport dynamics in the upper water column. The study introduces a multi-diagnostic approach that integrates field data, hydrodynamic modeling, and Lagrangian diagnostics to assess short-term retention processes. Sundklakkstraumen-a high-latitude tidal strait in Lofoten, northern Norway-serves as the focal site for applying the multidiagnostic approach in a high-resolution, data-supported coastal setting. While tailored to this specific environment, the approach could be adapted for use in other coastal systems characterized by complex topography and energetic tidal forcing. By combining in situ measurements with dedicated numerical modeling, this study enhances our understanding of transport mechanisms in complex tidal fjord environments.

## 2 Materials and methods

## 2.1 Study area

The Lofoten–Vesterålen region is characterized by a complex hydrodynamic setting shaped by a mosaic of small islands, fjords, and narrow straits. Circulation is primarily governed by the interaction of the Norwegian Atlantic Current (NwAC) and the Norwegian Coastal Current (NCC) with steep seabed topography (Ghaffari et al., 2018; Mitchelson-Jacob and Sundby, 2001). While earlier studies suggested that outflow from Vestfjorden occurred mainly through its southern boundary (Vikebø et al., 2007; Opdal et al., 2008), more recent work highlights the role of narrow tidal straits and strong semi-diurnal tidal currents in modulating local flow and transport (Børve et al., 2021; Nøst and Børve, 2021; Børve et al., 2025).

These semi-diurnal tides, with a typical excursion of approximately 2 m, propagate northward through the archipelago and interact with topography to produce vigorous tidal waves,



locations for both spring (March 23, 2023) and neap (April 14, 2023) tide experiments marked. The small right panel presents a time series of predicted tidal elevation, indicating the exact timing of drifter releases relative to tidal conditions. The inset map (bottom left) provides a broader view of the region, marking locations of current meters (CM1-CM4) and CTD stations used for model validation. Bathymetry is represented by color shading, with shallower areas in lighter tones and deeper regions in darker tones. A complementary figure is provided in Appendix D.

turbulence, and non-linear eddies (Moe et al., 2002; Kurogi and Hasumi, 2019). In narrow straits where current speeds exceed 2–3 ms<sup>-1</sup>, such interactions give rise to rectified tidal currents and net tracer transport via mechanisms such as tidal pumping—where flow separation forms self-propagating dipoles during outflow— and tidal rectification, driven by vortex stretching around islands and slopes (Børve et al., 2021; Moe et al., 2002; Benjamins et al., 2015). These processes play a key role in connecting Vestfjorden to the outer shelf and strongly influence local retention and exchange dynamics.

This study examines Sundklakkstraumen (Figure 1), one of the straits linking Vestfjorden and the Norwegian Sea. The bathymetry of this region is highly complex, characterized by shallow depths, submerged ridges, and varying channel widths that influence flow pathways. Sundklakkstraumen reaches a minimum depth of approximately 2 meters at the lowest astronomical tide and stretches 13 km in a southeast-to-northwest orientation. At its southern end, it connects to Gimsøystraumen, while its northern terminus opens into the Norwegian Sea. The width of the strait varies significantly, with a 260-meter span at the Sundklakkstraumen Bridge narrowing further in its central

section, where multiple small islands divide the flow into three distinct channels with widths ranging from 20 to 50 meters. North of these islands, the channel widens to approximately 2 km.

The role of these straits in marine debris transport has been previously investigated in studies such as Solbakken et al. (2022); Haarr et al. (2024), which examined the biweekly retention and deposition of beach litter at Storvika Bay, a site located along the northern coastline of a semi-enclosed bay within Sundklakkstraumen. These studies suggest that Storvika regularly receives fresh marine debris but may also function as a temporary retention site for floating litter. Plastic particles appear to be intermittently deposited and resuspended by hydrodynamic forces before eventually being advected away by currents or permanently beached. Both regional (matching general patterns across sites in the Lofoten archipelago) and highly local (distinguishing Storvika from other nearby locations within  $\sim 10$  km) sources of marine debris were identified. Consequently, the dynamics of beach litter in Storvika indicate that Sundklakkstraumen represents a compelling case study of the complex processes governing floating marine debris in nearshore waters, including continuous (though temporally variable) litter influx, resuspension and removal of previously beached material, and potential local retention of floating plastic particles.

#### 2.2 Observations

Observations of near-surface currents were conducted using custom-designed GPS drifters to characterize micro- to mesoscale flow patterns and assess the influence of local bathymetry on transport dynamics. The drifters were adapted from CODE surface and MD03i designs (Davis, 1985; Callies et al., 2017), and modified for conditions specific to the study area. Each GPS-tracked surface drifter was custom-designed for current-following behavior and near-surface tracking, with a sampling frequency of 0.5 Hz. A detailed description and images of the instrument design and deployment are provided in Appendix A.

Two field campaigns were conducted on March 23, 2023 (spring tide) and April 14, 2023 (neap tide). The late-winter period was selected to isolate tidally driven transport processes under conditions of minimal freshwater discharge. Moreover, the Sundklakkstraumen channel is well-sheltered by surrounding topography, minimizing direct wind exposure. Consequently, wind and wave influences were considered negligible during both deployments.

A total of 24 unique GPS-enabled drifters were deployed across the two field surveys: 11 units during the spring tide campaign (March 23, 2023) and 13 during the neap tide campaign (April 14, 2023). Individual drifter releases were conducted using a timestaggered cluster strategy to span different tidal phases. Most deployments originated from the southern entrance of Storvika, using the Sundklakkstraumen bridge as a fixed vantage point. During the spring tide experiment, five clusters were released: Clusters 1 through 4 were deployed along the falling limb (ebb tide), and Cluster 5 was deployed during the rising limb (flood tide) to capture the flow reversal. A similar schedule was followed during the neap tide campaign, covering both ebb and flood phases. In addition, one cluster of four drifters was released at the northwestern entrance of the basin to evaluate lateral inflow and retention behavior under weaker tidal forcing.

Drift durations varied depending on tidal phase, grounding, and technical performance. Most drifters remained active between 6 and 12 hours, with typical trajectories lasting around 8 - 9 hours. A few units recorded shorter tracks (1 - 2 hours) due to early grounding or GPS dropout. The full drift duration range was 6-10.2 hours for the spring tide and 1-12.9 hours for the neap tide. These values align well with the 12-hour simulation periods used in the particle tracking experiments, ensuring adequate temporal coverage of both ebb and flood phases (see Appendix A).

During the spring tide campaign, three drifters required redeployment due to grounding or entanglement with sea ice. Usable trajectory data were retrieved from approximately 67% of spring tide drifters and 94% of neap tide drifters. Most data losses were attributed to GPS malfunction, such as non-recording or early cessation of positional logging. Despite these losses, the dataset yielded high-resolution trajectories that captured key tidal phases, supporting robust model validation and quantitative analysis of transport pathways.

#### 2.3 Ocean model

We used the Finite Volume Community Ocean Model (FVCOM) (Chen et al., 2003), a prognostic, free surface, threedimensional primitive equation model, to simulate drift dynamics in the Lofoten archipelago. The model employs unstructured triangular grids for detailed representation of narrow straits and complex bathymetry. Momentum advection is solved with a second-order flux scheme (Chen et al., 2006; Kobayashi et al., 1999), and horizontal diffusion is handled using the Smagorinsky (1963) closure scheme. Bottom friction is represented by a quadratic drag law:

$$(\tau_{b,x}, \tau_{b,y}) = \rho_0 C_d |\vec{u}| \vec{u},\tag{1}$$

where in Equation 1  $C_d$  is the drag coefficient,  $\rho_0$  is the reference seawater density, and  $\vec{u}$  the velocity vector. In the 2D model,  $C_d$  follows the Chézy-Manning relation, which is provided in Equation 2:

$$C_d = g \frac{n^2}{\sqrt[3]{D}},\tag{2}$$

with *g* gravitational acceleration, *n* the Manning coefficient, and *D* water depth. A Manning coefficient of n = 0.02 was selected based on validation against observations (Section 2.6; Børve et al. (2025)). In the 3D setup, bottom drag is calculated using a logarithmic law-of-the-wall formulation. The model equations were integrated using a modified explicit fourth-order Runge-Kutta scheme (Chen et al., 2003).

The model grid, adapted from Ghaffari et al. (2019), covers Nordland and southern Troms counties, extending into the Lofoten Basin. The horizontal resolution was 30-50 meters along coastlines and narrow straits, with refinement to 17 meters in Gimsøystraumen and Sundklakkstraumen (Figure 1) (Lynge et al., 2010; Børve et al., 2021). The 3D model incorporated realistic atmospheric forcing from AROME-Arctic (Müller et al., 2017) and open boundary conditions from ROMS (Röhrs et al., 2018). Freshwater input was provided by river discharge data from NVE (Ghaffari et al., 2019), supplemented with climatology-based synthetic data where real-time observations were unavailable (Beldring et al., 2003). The model ran from December 2022 to June 2023, with a three-month spin-up period to reach equilibrium before drift simulations. The external barotropic time step was set to 0.1 s, and the internal baroclinic time step was 0.8 s, based on a mode-splitting factor of 8, to ensure numerical stability in highresolution coastal zones.

## 2.4 Drift model

We employed the open-source, Python-based Lagrangian framework OpenDrift (Dagestad et al., 2018, 2016), which is widely used for simulating passive particle advection in oceanic

and atmospheric flows. Its modular design supports diverse applications, including oil spill tracking, ecological studies, and search and-rescue operations (Dagestad et al., 2018). For this study, we used the basic advection module assuming passive transport, omitting wind drag and Stokes drift, consistent with currentdominated conditions (Van Sebille et al., 2018).

Particle movement was computed by identifying the nearest horizontal grid cell, followed by vertical and temporal linear interpolation of velocity fields. Land boundaries were defined by the solid boundaries of the ocean model. Particles crossing the solid boundaries were returned to their last valid ocean position to avoid unrealistic accumulation.

Fjords are characterized by complex circulation patterns that include sub-mesoscale processes and residual currents, which can significantly influence particle retention (Bianucci et al., 2024). To assess transport and retention within the fjord-channel system, we integrated OpenDrift with 2D and 3D configurations of our hydrodynamic model. The simulations used idealized digital drifters deployed at 2 meters depth, aligned with the spatial and temporal release patterns of the field drifters, allowing for direct comparison with observed trajectories. This approach aligns with recent validation efforts employing GPS-tracked drifters to evaluate hydrodynamic model performance (Hunter et al., 2022).

Each experiment simulated 12 hours, covering the entire duration of field deployments. Particle depth was held constant, allowing 3D velocity gradients to influence horizontal drift, a method consistent with previous studies on Lagrangian coherence and subsurface transport (Jalón-Rojas et al., 2024).

#### 2.5 Trajectory analysis

The drift model provides time-resolved particle trajectories, tracking where N particles are advected by the simulated ocean circulation throughout the study period. To extract meaningful retention and transport patterns from these trajectories, we applied a set of post-processing diagnostics, including Lagrangian Coherent Structures (LCS), residence time analysis, and revisit probability fields.

Lagrangian Coherent Structures were derived from Finite-Time Lyapunov Exponent (FTLE) fields, which reveal dynamically significant material surfaces acting as transient attractors or repellers in the flow field (Haller, 2015; Peacock and Haller, 2013; Shadden et al., 2005; Lekien and Ross, 2010; Serra et al., 2017; Leonard and Lucas, 2020). Particle trajectories were integrated using a fourth-order Runge–Kutta scheme, applied to surfacelayer velocities from the high-resolution hydrodynamic model. The velocity field was interpolated onto a uniform 2 m grid, with linear spatial and temporal interpolation between hourly model outputs and particle positions updated every second ( $\Delta t = 1$  s). Domain boundaries were treated with reflective conditions following Coulliette and Wiggins (2001); Beron-Vera et al. (2013). The FTLE field was computed as:

$$\sigma(x_0, t_0, \tau) = \frac{1}{|\tau|} \ln\left(\sqrt{\lambda_{\max}(\mathbf{C}(x_0, t_0, \tau))}\right),\tag{3}$$

where in Equation 3  $\lambda_{max}$  denotes the largest eigenvalue of the Cauchy–Green deformation tensor C, evaluated from the flow map gradient over the time interval  $\tau$ . High FTLE values correspond to regions of rapid particle separation (repelling LCS), while strongly negative FTLE values indicate particle convergence (attracting LCS).

While FTLE-based LCS analysis provides information on coherent transport structures, it does not directly quantify particle residence time, which is critical for understanding debris accumulation. Therefore, we complemented the LCS results with residence time and revisit probability diagnostics. To achieve this, we divided the domain into a uniform  $25 \times 25$  m grid and released one synthetic particle per cell per hour across full tidal cycles. Particle trajectories were integrated using a 1-second time step, with advection terminated upon exiting the model domain.

The total residence time in grid cell (i,j) was computed as:

$$T_{i,j} = \sum_{t=1}^{N_t} \sum_{p=1}^{N_p} \delta_{p,i,j}(t) \cdot \Delta t,$$
(4)

where  $\delta_{p,i,j}(t) = 1$  if particle *p* occupies cell (i, j) at time *t*, and  $\Delta t = 1$  s.

The mean residence time per cell using Equation 4 is then defined as:

$$\bar{T}_{i,j} = \frac{T_{i,j}}{V_{i,j}}, \quad \text{where} \quad V_{i,j} = \sum_{t=1}^{N_t} \sum_{p=1}^{N_p} \delta_{p,i,j}(t),$$
(5)

and  $V_{i,j}$  in Equation 5 denotes the total number of particle visits to cell (*i*,*j*).

Particle positions were updated according to:

$$x_{p,i,j}(t + \Delta t) = x_{p,i,j}(t) + u_{i,j}(t) \cdot \Delta t,$$
(6)

where  $x_{p,i,j}(t)$  is the particle position and  $u_{i,j}(t)$  is the interpolated velocity vector.

To further characterize spatial retention, we computed a revisit factor defined as the ratio of total particle visits, derived from Equations 5, 6, to the number of unique particles visiting each cell. This metric highlights zones of repeated re-entry and potential recirculation, offering additional insight into debris-trapping behavior within the domain.

#### 2.6 Ocean model validation

Model validation was carried out using observational data from multiple sources to assess the accuracy of the hydrodynamic simulations. This includes profiling stations from the Sundklakkstraumen system, at the southern and northern ends of the channel, and centrally located in the basin, as shown in Figure 1, which provided vertical profiles of temperature, salinity, and velocity, offering comprehensive spatial coverage of the study domain. Additional long-term and multi-depth velocity data (at 5 m and 15 m depths over four months from March to June 2023)



from Malnesfjord (14.593°E, 68.793°N), a nearby fjord with similar dynamic conditions, were used for a simplified multi-depth validation that aligns with methodologies employed in Norwegian fjord systems (Dalsøren et al., 2020; Kristensen and Gusdal, 2021).

Comparison between observed and simulated temperature and salinity profiles (Appendix C) demonstrated good agreement, despite a slight positive bias in both variables. This overestimation did not substantially affect transport predictions, given that the barotropic character of the system, rather than vertical stratification, dominates flow behavior. Recent studies emphasize that barotropic dominance is typical in fjords with strong tidal forcing (Cowton et al., 2015; Dalsøren et al., 2020), and resolving barotropic currents and sub-mesoscale features is essential for accurately modeling particle transport and retention in similar environments (Hecht and Hasumi, 2013; Fox-Kemper et al., 2011; McWilliams, 2016).

Velocity validation was the primary focus and showed high model fidelity. As illustrated in Figure 2, modeled current speeds at both 5 m and 15 m depths in CM1-CM4 displayed a strong correlation with observations. Linear regression lines for each depth closely followed the 1:1 relationship, with only minor deviations. The model underestimates the peak velocities (~ 10%) in surface layers (5 m), which mirrors challenges reported in Norwegian Coast (NorKyst) operational model validations, where resolution limits and parameterized friction effects require careful calibration (Kristensen and Gusdal, 2021). One possible improvement could involve adjusting the Manning coefficient, which influences bottom friction and has been shown in previous sensitivity analyses to impact velocity magnitudes (Xie et al., 2022). Despite this minor underestimation, the validation results confirm the model's robustness and reliability in simulating the hydrodynamic conditions of the Lofoten archipelago. The model successfully captured key velocity structures and spatial flow variations, providing a strong foundation for subsequent analyses of passive particle transport in the region. Similar model setups have also been validated against other regional observations, confirming their robustness (Børve et al., 2021, 2025).

## **3** Results and discussion

## 3.1 Flow dynamics

Figure 3 presents snapshots of the one-day maximum modeled flow speed at a depth of 1 meter from both the 3D (left panel) and 2D (right panel) simulations for the first field day, March 23<sup>rd</sup>. The flow fields exhibit strong similarities, emphasizing the dominance of tidally driven currents in the region. These currents form coherent, linear jets that extend from narrow straits into the adjacent basin an expected pattern given the region's dynamic tidal forcing (Børve



et al., 2021). The 3D simulation shows slightly higher surface-layer velocities compared to the 2D model, a difference attributed to its ability to resolve vertical structure and reduce the smoothing effects of depth-averaging. In contrast, the 2D model simplifies the velocity field by averaging over the water column, which can underestimate near-surface flow intensity.

Variance ellipses are widely used to represent the dominant direction and variability of horizontal current flow over time, with the major axis indicating the primary direction and magnitude of variability, and the minor axis reflecting cross-directional variability. Anisotropic (elongated) ellipses indicate strong directional flow, often aligned with topography (topographic steering and bathymetric alignment) or mean flow features, while isotropic (circular) ellipses indicate more uniform variability (Lumpkin and Johnson, 2013; Le Traon and Morrow, 2001; Elipot and Beal, 2015). In this study, ellipses were computed from a six-month 3D simulation to assess spatial coherence and the barotropic nature of the flow field. The results show that the major axes of the ellipses align closely with the geometry of the straits, confirming strong topographic control on flow direction. As further evidence, model diagnostics summarized in Table 1 indicate minimal vertical deviation in ellipse orientation across surface, bottom, and depth-averaged currents ( $\leq$  3.5%), supporting the conclusion that baroclinic contributions to velocity are small

(Kontogiannis and Bakas, 2020). However, during the summer months, stratification may enhance vertical shear and increase baroclinic effects (Lynge et al., 2010; Jing et al., 2025).

To quantify the contribution of the barotropic mode to the overall flow dynamics, we calculated the fraction of energy associated with the depth-independent mode at these specified locations (Ghaffari et al., 2013). The energy fraction, R, is defined as:

$$R = H \left\langle \bar{u}^2 \right\rangle / \left[ H \left\langle \bar{u}^2 \right\rangle + \left\langle \int_{\text{bott}}^{\text{surf}} (u')^2 dz \right\rangle \right], \tag{7}$$

where in Equation 7 *H* is the depth,  $\bar{u}$  and u' are the depth-averaged and depth-varying components of the flow field, respectively. The angle brackets indicate time-averaged values. The analysis revealed that approximately 70% of the total flow field variance across all selected positions is attributed to the barotropic mode, consistent with studies emphasizing tidal rectification in narrow channels (de Swart and Yuan, 2019; Zimmerman, 1980; Børve et al., 2021, 2025).

Storvika emerges as a site of particular interest due to its potential role as a transient collector and reservoir of floating marine debris (Haarr et al., 2024; Solbakken et al., 2022). Flow field analysis reveals that Storvika experiences markedly lower current velocities relative to more dynamic regions such as Gimsøystraumen. Within Storvika, peak velocities reach approximately 1 ms<sup>-1</sup> along the main channel adjacent to the

TABLE 1 Variance ellipse characteristics for surface, bottom, and depth-averaged currents at four locations.

Location	Surface (ms <sup>-1</sup> )	Bottom (ms <sup>-1</sup> )	Depth-avg (ms <sup>-1</sup> )	Avg. deviation (%)
CM1	1.20	1.12	1.15	3.5%
CM2	0.95	0.92	0.94	1.6%
CM3	0.78	0.74	0.76	2.6%
CM4	0.82	0.78	0.80	2.5%

southern shoreline, while the northern sector is characterized by substantially weaker flows, typically around 0.1 ms<sup>-1</sup>. These reduced velocities along the northern coast suggest the presence of a sheltered and shallow zone that may act as a temporary hotspot for marine debris accumulation if particles enter the bay.

Nevertheless, the overall energy levels in the Storvika basin are higher than those observed in nearby semi-enclosed bays such as Jenndalspollen and Gimsøymyrene, which may offer more suitable conditions for long-term retention. As such, while Storvika may intermittently function as a debris accumulation zone, resuspension and redistribution are likely, particularly under spring tidal conditions when time-mean transport intensifies by approximately 20% compared to neap tide.

#### 3.2 Drifter pathways

Figure 4 presents an overview of the trajectories of drifters released during both spring (left panels) and neap (right panels) tide phases, as observed in the field (top panels) and simulated using the 2D (middle panels) and 3D (lower panels) hydrodynamic models. These trajectories reveal clear contrasts between tidal phases, underscoring the dynamic interplay between tidal forcing and local bathymetry in shaping transport pathways in the Storvika–Sundklakkstraumen system.

During spring tide (March 23<sup>rd</sup>), the observed drifters exhibited a range of behaviors: some entered lateral boundary layers along Sundklakkstraumen's side walls and stranded; others looped within the Storvika basin near the tidal jet, suggesting the presence of local recirculation; and most were advected rapidly out of the channel along the deep central corridor. These drifters eventually bifurcated into northern and southern branches before reaching Årrstranda within the time frame of the field operation. These patterns reflect the dominant influence of the tidal jet and bathymetric steering during high-energy conditions.

In contrast, the neap tide deployment (April 14<sup>th</sup>) produced more cohesive trajectories. Most drifters exited Storvika following the main channel but returned after partial egress, indicating a reduction in tidal momentum and enhanced bathymetric influence. This recirculation within the basin, particularly along the northern shoreline, suggests that local topographic features modulate retention potential more strongly under low-energy conditions.

Idealized drifters released in both the 2D and 3D models replicated field release conditions and successfully captured these tidal contrasts. Simulated trajectories closely matched observations under both tidal regimes, reproducing looping, stranding, and bifurcation behaviors during spring tides, and re-entry into Storvika during neap tides. This agreement affirms the models' ability to represent key transport dynamics across contrasting hydrodynamic conditions. Root-mean-square endpoint displacement errors were approximately 65 meters during spring tides and increased to  $\sim$  100 meters under neap conditions, with maximum deviations ranging between 80 – 120 meters. The 3D model performed slightly better in weaker forcing regimes, more accurately capturing localized recirculation. Lateral trajectory deviations remained under 30 meters in spring and around 40 meters during neap conditions. Exit direction and timing were also well reproduced. These metrics align with benchmarks for high-resolution coastal drift modeling (Xie et al., 2022).

To further evaluate model performance across different hydrodynamic states, we applied the normalized cumulative separation distance (s) and corresponding skill score (ss) as formulated by Liu and Weisberg (2011). The metric s quantifies the time-integrated deviation between modeled and observed positions, normalized by the cumulative distance traveled by the observed drifter:

$$s = \frac{\sum_{i=1}^{N} |\mathbf{x}_{\text{mod}}(i) - \mathbf{x}_{\text{obs}}(i)|}{\sum_{i=1}^{N} |\mathbf{x}_{\text{obs}}(i+1) - \mathbf{x}_{\text{obs}}(i)|},$$
(8)

where  $x_{mod}(i)$  and  $x_{obs}(i)$  are the simulated and observed drifter positions at time step *i*, and *N* is the number of trajectory samples. This method accounts for both spatial and temporal evolution of the trajectory, making it particularly suitable for evaluating Lagrangian performance in coastal domains (Özgökmen et al., 2000; Barron et al., 2007; Willmott, 1981). The associated skill score using Equation 8 is computed as:

$$ss = 1 - \frac{s}{n},\tag{9}$$

where *n* is the tolerance threshold *s* value in Equation 9, above which (s > n) the model is considered to have no predictive skill. Here, we adopt n = 1.0, corresponding to a scenario where the cumulative separation equals the total trajectory length—a reasonable upper bound for skillful predictions in coastal drift modeling (Liu and Weisberg, 2011).

Separate calculations were performed for spring and neap tide episodes. During spring tide, the 2D and 3D models yielded normalized cumulative separation distances of s = 0.212 and s =0.198, resulting in skill scores of ss = 0.788 and ss = 0.802, respectively. Under neap tide conditions, the 2D and 3D models produced slightly lower *s* values of 0.181 and 0.152, corresponding to skill scores of *ss* = 0.819 and ss = 0.848. Although both model configurations exhibited marginally higher skill under neap tide conditions, this result should be interpreted cautiously. The success rate of usable drifter trajectories increased by approximately 40% during neap tide relative to spring, meaning that some of the spring drifters either grounded or ceased recording after partial recirculation. These interruptions likely reduced the cumulative trajectory lengths used in normalization, thereby influencing the magnitude of the separation metric. As such, the improved ss values may partially reflect these data differences rather than a fundamental improvement in model fidelity under low-energy conditions.

Overall model performance across both tidal phases yielded cumulative separation values of s = 0.196 and s = 0.167 for the 2D and 3D models, translating to skill scores of ss = 0.804 and ss = 0.833. These scores place both models in the "good" skill category according to Liu and Weisberg (2011), with the 3D model showing consistent advantages in resolving sub-basin recirculation and retention processes.



Field deployments further highlighted topographic interactions influencing particle fate. During spring tides, some drifters collided with submerged features but remained afloat, though often damaged, reducing their surface area. In neap tide deployments, weaker currents and shallower water levels caused drifters to ground, particularly along the northern margin of Storvika, requiring manual redeployment. These patterns indicate that floating plastics, especially those with low buoyancy or deformable geometries, are more likely to strand during lowenergy phases before potentially being remobilized. This behavior is consistent with documented accumulation mechanisms in similarly energetic coastal environments (Van Sebille et al., 2020; Browne et al., 2011; Zhang, 2017).

Although the overall trend was outward transport, several locations exhibited characteristics of temporary accumulation. Shallow and sheltered areas along the northern Storvika shoreline and the bifurcation zone in Sundklakkstraumen showed signs of intermittent recirculation and reduced flow, potentially acting as short-term retention hotspots. These regions are particularly sensitive to tidal dynamics and may serve as episodic sinks during neap conditions.

#### 3.3 Transport and retention zones

One of the main objectives of this study is to understand the flow field characteristics of the Storvika basin, which has been reported as a candidate region for deposition and retention of floating plastic items (Solbakken et al., 2022; Haarr et al., 2024). We focus on a subdomain encompassing Storvika and surrounding regions (illustrated in Figure 3, red dashed box), and given that reported floating plastic items are mainly located at the surface layer, we extract the surface layer of the 3D model for further analysis.

Understanding particle retention and transport dynamics in this system requires an integrated analysis of temporal variability, spatial energy distribution, and coherent transport structures. The strongly tidal environment alternates between periods of energetic flushing and conditions favoring localized retention, directly influencing the pathways and fate of floating debris.

Temporal variability was assessed by computing hourly changes in surface flow speed for March and April 2023. At each timestep, the maximum absolute velocity difference across the domain was recorded and compared to thresholds of 0.1, 0.5, and 1.0 ms<sup>-1</sup>. Results show that 96%, 85%, and 42% of these maxima exceeded the respective thresholds. The frequent occurrence of flow speeds surpassing 0.5 ms<sup>-1</sup> indicates persistent dynamic forcing, consistent with findings from tidal-stream energy sites where such velocities correlate with reduced turbulence intensity and stabilized power output (Thiringer et al., 2011). Large hourly changes exceeding 1.0 ms<sup>-1</sup> were observed less frequently and were most common during spring tides, aligning with findings from macrotidal estuaries where spring currents generate 30 - 50% higher turbulence kinetic energy compared to neap phases (Pieterse et al., 2015). This variability suggests that floating debris is subjected to strong, shifting forces that inhibit long-term retention under energetic conditions, while allowing for temporary entrapment during calmer neap periods.

The spatial distribution of mean kinetic energy (MKE) and flow pathways is presented in the upper panels of Figure 5, overlaid with streamlines and polygons marking low-energy and retention zones. The velocity field was decomposed into monthly mean and fluctuating components:

$$U = \bar{U} + U',\tag{10}$$

where U is the instantaneous velocity,  $\overline{U}$  the mean velocity, and U' the deviation from this mean. The residual current reflects net transport structures shaped by tidal asymmetry, bathymetric steering, and minor wind contributions (Thomson et al., 2012; Chamorro et al., 2013; Guerra et al., 2017).

MKE which is calculated using the mean velocity component from Equation 10, peaked at approximately 0.30 m<sup>2</sup> s<sup>-2</sup> during spring tides and decreased to 0.24 m<sup>2</sup> s<sup>-2</sup> during neap conditions, with maxima along constricted and deep channel sections. Recirculation zones near the northern and eastern basin boundaries displayed substantially lower MKE values, ranging from 0.02 to 0.04 m<sup>2</sup> s<sup>-2</sup>, nearly seven times lower than in primary flushing corridors. The energy contrast ratio between corridors and recirculation zones was 5.6 during spring and 4.9 during neap conditions, mirroring observations from the Alderney Race, where neap tides reduce kinetic energy gradients by 18 – 22% due to weaker hydraulic forcing (Thiébot et al., 2020). Furthermore, areas with MKE< 0.025 m<sup>2</sup> s<sup>-2</sup> (shown as blue polygons in Figure 5) expanded from 17% of the domain in spring to 28% in neap tides, indicating increased potential for debris retention.

The differences in energetics in the region between spring and neap tides provide a measure of circulation and mixing intensity, while the LCS analysis outlined in Section 2.5 quantifies how transport pathways respond to these energetic shifts. To capture short-term retention structures relevant to tidal modulation, the FTLE fields were computed using an integration window of  $\tau = 2$ day, which is a standard choice in coastal and tidal environments to resolve mesoscale flow variability and transient Lagrangian features (Serra et al., 2017; Haller, 2015; Lekien and Ross, 2010). Figure 5 presents the FTLE fields for March (spring tide) and April (neap tide) 2023. Positive FTLE values delineate repelling structures acting as dynamic barriers, while negative FTLE values highlight convergence zones where floating material accumulates. In March, repelling LCSs dominated along the main channel and boundaries, with strong transport pathways facilitating efficient export. Nevertheless, localized attracting features (FTLE values below  $-1.0 \text{ day}^{-1}$ ) appeared along the western boundary and lower strait, forming transient retention pockets with particle residence times of 1.5-2.2 hours, consistent with retention times reported for similar tidal environments (Leonard and Lucas, 2020).

During neap tides in April, convergence zones became more extensive, especially in the central basin and eastern boundary, with FTLE minima reaching approximately  $-2.0 \text{ day}^{-1}$ . Particle residence times within these structures increased to 4 hours, and the spatial extent of strong attracting LCS regions expanded by around 40% compared to March. This corresponded with a flushout time increase from 10 to 15 hours and a 38% increase in the Retention Efficiency Index (REI), from 0.42 to 0.58. These results indicate that weaker tidal forcing substantially enhances both the spatial and temporal scales of retention, in agreement with prior observations in barotropic archipelago systems (Børve et al., 2021). The eastern basin, particularly between latitudes  $68.274^{\circ}\text{N} - 68.278^{\circ}$  N and longitudes  $14.15^{\circ}\text{E} - 14.16^{\circ}\text{E}$ , exhibited moderate FTLE gradients (0.5–1.5 day<sup>-1</sup>), suggesting more gradual fluid stretching and mixing. Fine-scale convergence filaments along the



candidate retention zones with weak vortex circulation. Bottom panels present FTLE fields showing repelling (red) and attracting (blue) structures.

northeastern margin, revealed by LCS analysis but not evident in Eulerian fields or residence metrics, highlight additional retention complexity likely driven by localized recirculation patterns (Haarr et al., 2024).

Transport efficiency was computed to quantify the balance between downstream flushing and local recirculation strength, defined as:

$$TE = \frac{\bar{U}_c}{\bar{U}_r},\tag{11}$$

where  $\bar{U}_c$  is the spatially averaged velocity magnitude in primary flushing pathways and  $\bar{U}_r$  is the average tangential velocity in retention vortices. Higher TE values, in Equation 11, indicate stronger downstream transport relative to retention. TE ranged from 2.6 during neap conditions to 4.2 under spring tides, representing a ~ 62% increase in transport efficiency with stronger tidal forcing. This pattern confirms that energetic tidal conditions enhance flushing, while weaker tides promote retention, consistent with the findings of Gao et al. (2023) and prior studies highlighting alternating debris transport patterns controlled by tidal inequality (Schreyers et al., 2024; Sawan et al., 2025; Carvalho et al., 2025).

## 3.4 Residence time

While kinetic energy and streamline patterns offer qualitative insight into the distribution of energetic versus quiescent flow regions, quantifying particle retention requires a direct Lagrangian approach. To characterize spatial retention variability in Storevika, we computed residence time and revisit probability fields as outlined in Section 2.5 for March (spring tide) and April (neap tide) 2023 using particle-tracking experiments over the Storvika–Sundklakkstraumen subdomain.



The maps illustrate key movement metrics for March and April 2023, including average residual time per box (left) and revisitation probability (right). Warmer colors indicate higher values, highlighting areas with prolonged retention and frequent revisits. The inset maps show normalized unique visitor probability, emphasizing spatial variation in movement patterns.

Figure 6 shows the spatial distribution of mean residence time (left) and revisit probability (right). During March's spring tide, residence times remained low basin-wide, averaging between 10 - 13.5 min. In contrast, April's neap tides increased both the magnitude and spatial extent of residence time. The interior basin reached over 15 mins, and median values rose by nearly 40%, consistent with broader LCS convergence zones and longer flush-out times.

The small inset maps further resolve retention features. Highest retention was found in three distinct hotspots under neap forcing: the northeastern Storvika shoreline (near  $68.276^{\circ}$ N,  $14.163^{\circ}$ E), the central basin ( $68.273^{\circ}$ N,  $14.157^{\circ}$ E), and the sheltered entrance to Jenndalspollen ( $68.272^{\circ}$ N,  $14.147^{\circ}$ E). These areas maintained residence times exceeding 15 min and revisit probabilities greater than 0.8. Ranked by relative retention intensity, the northeastern Storvika region exhibited the highest accumulation (over 18 min and revisit probability > 0.9), followed by the central basin (approximately 16.5 min and revisit ~ 0.85), and the entrance to Jenndalspollen (around 16 min and revisit ~ 0.82). Collectively, these zones covered about 22–25% of the domain during neap tides, in contrast to only 11–13% during spring tides. Their location correlated strongly with low-MKE pockets and attracting LCS filaments (Figure 5), suggesting coherent control by bathymetric constraints and tidally modulated forcing.

In March, revisits were concentrated near the western shoreline but remained limited in spatial coverage and persistence. The shift of recirculation and retention structures from west to east under weaker tidal amplitude reflects a redistribution of accumulation potential, in line with tidal rectification theory (Børve et al., 2021). The total particle-time spent within the domain, normalized by maximum simulation duration, increases from 0.42 to 0.58 between spring and neap tides. This increase mirrors convergence zone expansion and confirms that tidally modulated energy gradients and local topography drive systematic retention shifts in this fjordic system (Leonard and Lucas, 2020; Gao et al., 2023; Carvalho et al., 2025).

# 3.5 Integrated performance and hotspot metrics

To synthesize the system-scale behavior under varying tidal regimes, we combined Lagrangian diagnostics, model performance metrics, and spatial retention analysis. This integrated assessment links model accuracy with observed debris retention patterns and reveals how neap and spring tides drive contrasting accumulation dynamics within the domain.

Model skill metrics corroborate these findings. Based on normalized cumulative separation distance, the 2D and 3D models yielded overall skill scores of ss = 0.804 and ss = 0.833, respectively, placing both in the "good" performance category (Liu and Weisberg, 2011). Skill varied by tidal phase: under spring tide, the 2D and 3D models achieved ss = 0.788 and 0.802, while under neap tide, scores improved to 0.819 and 0.848. Although the improvement is modest, deployment of fewer drifters and the higher retrieval success during neap tide (an increase of up to 40%) may have contributed to better skill score estimates by increasing trajectory lengths and reducing early terminations. Endpoint displacement errors remained within 65 – 100 meters, and trajectory accuracies exceeded 87% in all cases, confirming the model's high fidelity in representing observed pathways.

Model simulations reproduced these dynamics with high accuracy. MKE peaked near 0.30 m<sup>2</sup> s<sup>-2</sup> during spring tide and declined to 0.24 m<sup>2</sup> s<sup>-2</sup> during neap tide. Zones of low MKE (< 0.025 m<sup>2</sup> s<sup>-2</sup>) expanded by more than 60%, particularly near basin margins, and corresponded to convergence zones in streamline and particle tracking results. FTLE maps revealed extensive attracting LCS during neap tides, with minimum FTLE values reaching -2.0 day<sup>-1</sup> and a 40% increase in attracting area. Concurrently, median residence time increased by 40%, maximum revisit probability rose from 0.6 to 0.9, and domain-wide retention efficiency improved from 0.42 to 0.58, consistent with prior Lagrangian studies on tidal retention (Leonard and Lucas, 2020; Gao et al., 2023; Sawan et al., 2025; Carvalho et al., 2025).

These system-scale metrics are summarized in Table 2. Neap tides were associated with broader convergence zones, elevated retention, and longer particle persistence. Transport efficiency decreased from 4.2 to 2.6, and the energy contrast between flushing corridors and recirculating zones declined by 12.5%, indicating weaker energetic segregation of the basin.

To identify key accumulation areas, we integrated Eulerian (MKE, streamlines) and Lagrangian (residence time, revisit probability, FTLE) diagnostics with drifter trajectories. During neap tide, three hotspots were consistently observed (red zones, Figure 6). The central-northern basin (near  $68.2765^\circ$ N,  $14.155^\circ$ E) emerged as the most prominent retention zone, exhibiting > 16.5 min residence times, revisit probabilities > 0.85, and strongly attracting FTLE structures. The northeastern corner ( $68.2778^\circ$ N,  $14.1615^\circ$ E) showed secondary retention, with frequent reentrainment, while the southeastern boundary ( $68.2725^\circ$ N,  $14.161^\circ$ E) exhibited intermittent stagnation. Collectively, these zones accounted for over 40% of total residence time despite covering only ~ 20% of the basin area.

TABLE 2 Summary of key transport and retention metrics for spring (March) and neap (April) tide conditions in Storvika and Sundklakkstraumen.

Metric	Spring tide (March)	Neap tide (April)	Relative change (%)
Peak residence time (min)	~13.3	~16.7	+25
Median residence time (min)	~8.3	~11.7	+40
Max revisitation probability	0.60	0.90	+50
Retention efficiency	0.42	0.58	+38
Flush-out time (hours)	10	15	+50
Attracting LCS area (relative)	Baseline	+40%	+40
Transport efficiency	4.2	2.6	-38
Energy contrast ratio	5.6	4.9	-12.5

Flush-out time indicates when 90% of surface particles exit the domain.

These spatial patterns are quantitatively visualized in Figure 7, which compares residence time, revisit probability, and LCS attracting area contributions across zones and tidal regimes. Under neap tide, central north Storvika contributed 25–30% to key metrics, while northeast and southeast zones contributed 8–20%. In contrast, spring tide contributions from all three zones dropped significantly, down to 10% or less, with >74% of all metrics dominated by the rest of the basin, confirming that no persistent accumulation occurred under strong tidal forcing. Under spring tide, only one minor and transient hotspot (red zone, Figure 6) was identified along the western-central boundary of Storvika (68.2735° N, 14.146°E), where looping drifter trajectories and low-FTLE convergence coincided with slightly elevated residence times (10–11.5 min). However, this zone was small, weakly retentive, and short-lived, with retention contributions<

## 3.6 Applicability of the diagnostic approach

The multi-diagnostic approach presented here integrates observational validation, high-resolution hydrodynamic modeling, and Lagrangian diagnostics to quantify floating debris dynamics and retention under varying tidal conditions. The results align with previous reports on tidal asymmetry and plastic accumulation in high-latitude fjordic environments (Solbakken et al., 2022; Haarr et al., 2024; Børve et al., 2021), confirming that tidal modulation is a dominant control on short-term debris entrapment in complex coastal systems.

While this study focused on a sheltered fjord with minimal wind and wave influence, the same approach could be adapted to more



exposed or stratified coastal systems by incorporating additional physical forcings such as wind drag, Stokes drift, and shoreline interaction schemes. For instance, Ghaffari et al. (2020) demonstrated that Stokes drift can drive transport at magnitudes comparable to moderate winds in semienclosed basins. Similarly, recent findings in the Lofoten archipelago indicate that Stokes parameterizations, particularly those accounting for crossing windsea and swell, can significantly reduce residence time near the coast (Espenes et al., 2024).

For broader application, several variables are critical, including accurate bathymetry, representative tidal forcing, and careful selection of model dimensionality (2D vs. 3D) based on the degree of baroclinicity. For the present study area, the depthaveraged 2D model proved computationally efficient and suitable for real-time operational contexts such as search and rescue (SAR), oil spill response, or aquaculture risk forecasting (Liu and Weisberg, 2011; Lebreton and Andrady, 2019). However, this substitution must be evaluated on a case-by-case basis. In fjord systems with strong stratification and significant baroclinic variability, such as Nesnafjord in northern Norway (Ghaffari et al., 2025), full 3D modeling remains essential to resolve vertical shear and associated transport processes. Additionally, in more exposed environments, the inclusion of wind and wave-induced processes becomes essential to realistically capture surface transport dynamics. Access to drifter data or equivalent observational benchmarks can further improve model calibration and transferability.

Nonetheless, certain limitations in the present setup should be noted. Wind forcing, Stokes drift, and wave effects were excluded due to the sheltered nature of the study site, which may limit direct applicability to more dynamic or open systems (Dobler et al., 2019). Reflective boundary conditions simplified shoreline interactions, potentially under-representing beaching and strandline retention processes (Hernandez et al., 2024, 2025). Likewise, while freshwater inflow was represented using climatological discharge, real-time variability, though likely minor in Lofoten, could be more consequential in river-dominated settings. Incorporating shoreline permeability and wave-driven resuspension would further improve realism in future simulations.

# 4 Conclusion

This study combined targeted field observations with highresolution hydrodynamic modeling to examine the transport and retention of floating marine debris in Storvika and Sundklakkstraumen, a tidally energetic fjord system in the Lofoten archipelago. Using GPS-tracked drifters and both 2D and 3D hydrodynamic simulations, we assessed how tidal modulation governs surface transport dynamics, convergence structures, and short-term retention behavior.

Drifter deployments during spring (March  $23^{rd}$ ) and neap (April  $14^{th}$ ) tides revealed pronounced differences in surface

transport. Spring tides generated strong barotropic currents that efficiently flushed particles through central channels, while neap tides favored localized recirculation and accumulation, particularly along the basin's eastern and northern margins. Model diagnostics supported these observations, showing that neap conditions coincided with expanded retention zones, elevated residence times, and enhanced convergence as indicated by attracting Lagrangian Coherent Structures. The results confirm that tidal modulation is a dominant control on short-term debris entrapment in complex coastal systems.

The modeling results demonstrated the utility of both 2D and 3D configurations for debris transport analysis in a tidal fjord system. The 3D model resolved vertical shear and fine-scale convergence zones, whereas the depth-averaged 2D model performed well under barotropic conditions and proved computationally efficient for potential real-time applications.

In summary, this study presents a validated multi-diagnostic approach for quantifying floating debris retention in a tidally dynamic coastal system. By integrating Eulerian and Lagrangian diagnostics with empirical and simulated drifter data, the approach reveals how tidal modulation and flow structure govern the spatial and temporal dynamics of debris accumulation. Its strength lies in combining observational validation, high-resolution hydrodynamics, and multi-metric diagnostics to assess retention behavior across tidal regimes. As such, it provides a solid foundation for marine litter assessments, aquaculture planning, and operational coastal forecasting applications aimed at enhancing environmental resilience and pollution mitigation.

## Data availability statement

The original contributions presented in the study are included in the article/Supplementary Material, further inquiries can be directed to the corresponding author/s.

## **Ethics statement**

Written informed consent was obtained from the individual(s) for the publication of any identifiable images or data included in this article.

## Author contributions

PG: Data curation, Project administration, Formal analysis, Conceptualization, Visualization, Validation, Methodology, Writing – original draft, Software, Writing – review & editing, Funding acquisition, Investigation, Supervision, Resources. HE: Methodology, Writing – original draft, Investigation, Data curation, Visualization, Writing – review & editing, Formal analysis. EB: Writing – review & editing. SH: Writing – review & editing. ØL: Validation, Writing – review & editing. JR: Writing – review & editing. RP: Writing – review & editing. VSS: Writing – review & editing, Funding acquisition, Project administration. MLH: Writing – review & editing, Project administration, Funding acquisition.

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# **Conflict of interest**

Authors JR, RP, VSS, and MLH were employed by SaltLofoten. The remaining authors declare that the research was conducted in the absence of any commercial or financial relationships that could be construed as a potential conflict of interest.

## **Generative AI statement**

The author(s) declare that no Generative AI was used in the creation of this manuscript.

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# Supplementary Material

The Supplementary Material for this article can be found online at: https://www.frontiersin.org/articles/10.3389/fmars.2025.1612395/ full#supplementary-material

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