



A Simple Elastoplastic Damage Constitutive Model of Porous Rock Materials

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Traditional macroscopic phenomenon constitutive model is not easy to describe in the non-linear mechanical properties of porous rock materials, since the effect of porosity does not incorporate into the strength criterion. This paper presents a simple elastoplastic damage constitutive model of porous rock material based on micromechanical theory. To consider the heterogeneities of the studied porous rock, a simplified representative volume element is introduced, and it is assumed that it is made up of randomly distributed spherical pores embedded in a solid matrix obeying Drucker-Prager yield function. Thus, a homogenized plastic criterion considering the effect of porosity is introduced to describe the macroscopic plastic mechanical properties of porous rock materials. In this model, the non-associated flow rule and isotropic strain hardening law are used, and then the degradation of elastic and plastic properties is employed by adopting a damage criterion. This criterion is related to the evolution of equivalent plastic strain. In order to verify the accuracy of the model, the corresponding numerical program was used to realize the micro-macro constitutive model, and the results were compared with the triaxial compression test results of sandstone under different confining pressures. It is observed that the numerical simulation results are in great agreement with the experimental data, indicating that the proposed model is able to predict the main mechanical behavior of porous sandstone.

Keywords: elastoplastic damage constitutive model, porous rock, non-associate flow rule, numerical analysis, damage

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INTRODUCTION

As a complex geological material, the rock mass contains various primary microstructures, including pores, cracks, inclusions, etc. The initiation and expansion of microdefects in rock mass reflect the degree of mechanical deterioration [1]. The deformation of inner pores or voids exhibits a great influence on the effective strength and mechanical behaviors on such materials, which lead to the complex plastic deformation, tension-compression asymmetry [2–5], brittle-ductile transition, and so on. In order to present the non-linear behaviors of porous medium and reflect the effects of the voids on the strength related to its plastic deformation, a number of previous investigations [6–8] have been proposed, which are based on the theory of kinematical limit analysis and provides the theoretical determination or numerical assessment of macroscopic yield criteria for porous materials. The present works are first to establish an appropriate effective plastic yield criterion for a porous

medium. Then, an analytical effective plastic yield function is obtained by the second homogenization step. Finally, consider the effects of mineral grains to determine the macroscopic plastic behavior of porous materials.

However, most of the above theories do not consider the influence of porosity inside rock on the evolution of damage. Several previous studies have shown that the growth of internal microdefects and the local stress concentration are two main factors, leading to the damage evolution in rocks under the external loading [9–12]. Further, the construction in geotechnical engineering often changes the stress state of rock mass, aggravating the damage evolution around the excavation section [13–16]. Hence, the damage modeling remains an ongoing interest in investigating the mechanical behavior of rock-like materials. On one hand, thanks to the rapid development of various kinds of rock testing techniques, considerable experimental studies have been conducted for understanding the underlying mechanism of damage evolution in rocks [17, 18]. On the other hand, the rock damage model research also has remarkable development. So far, many researchers have established numerous rock damage constitutive models based on different theoretical frameworks from various perspectives [19–21].

At the same time, as a natural porous material, rock has many pores at different scales. The development mechanism of plasticity and damage is bound to be related to the development and evolution of porosity. For this purpose, the present study is aiming to develop a micro-mechanics based constitutive model for plastic deformation and damage evolution in sandstone containing two populations of pores and mineral based on the plasticity theory and the irreversible thermodynamic framework [22, 23]. This work will put effort into developing a simple elastoplastic damage coupled constitutive model of porous rocks considering the effect of porosity and damage degradation.

THE ELASTOPLASTIC DAMAGE CONSTITUTIVE MODEL OF SANDSTONE

According to the experimental data of triaxial compression and irreversible thermodynamic theory [21], a elastoplastic constitutive model describing the damage of sandstone under drainage conditions is established, which can reflect the mechanical behavior of the sandstone with different seepage conditions in the stress field.

Porous Media Model

Based on the theory of porous media mechanics, the non-linear mechanical response of sandstone is described by using the plastic yield equation considering porosity. At the same time, the damage evolution criterion was established based on the existing damage theory, and independent damage variables were introduced into the plastic yield function to describe the damage evolution of rock in the process of deformation and failure, so as to determine the coupling relationship between plastic deformation and damage development. This model can

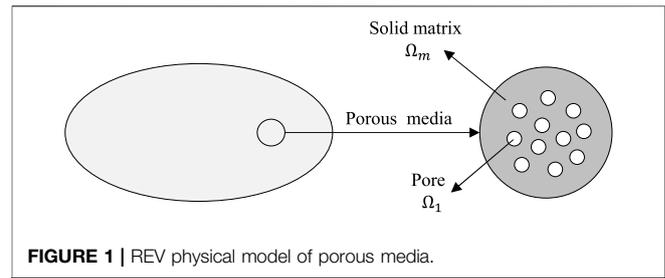


FIGURE 1 | REV physical model of porous media.

simulate both pre-peak strengthening and post-peak softening behaviors at the same time. The physical model of porous media is shown in **Figure 1**.

As is shown in **Figure 1**, the porous media is considered made up of isotropic solid matrix and random pore at microscale. The volumes of solid matrix and of the void are noted as Ω_m and Ω_1 , respectively. The volume of the whole porous media is obtained as $\Omega = \Omega_m + \Omega_1$. Based on the above statement, unit porosity can be calculated by the following formula:

$$f = \frac{\Omega_1}{\Omega} = \frac{\Omega_1}{\Omega_m + \Omega_1} < 1, \quad (1)$$

Compared with metal materials, the pressure sensitivity and volumetric deformation are two crucial characteristics of rock materials. In order to consider these aspects, here we assumed that the solid matrix is made up of elastoplastic material subjected to Drucker-Prager yield criterion.

$$F(\boldsymbol{\sigma}) = \boldsymbol{\sigma}_d + T(\boldsymbol{\sigma}_m - h) \leq 0, \quad (2)$$

Based on the assumption of small deformation, in the field of traditional plastic mechanics, the total strain increment of rock can be decomposed into elastic strain (increment) and plastic strain (increment):

$$\boldsymbol{\varepsilon}_{ij} = \boldsymbol{\varepsilon}_{ij}^e + \boldsymbol{\varepsilon}_{ij}^p, \quad D_{ij} = D_{ij}^e + D_{ij}^p, \quad (3)$$

Referring to the previous research theory of porous media [6–8], the effective volume modulus and shear modulus of intact and non-destructive rock materials are expressed as follows:

$$\kappa_0^{hom} = \frac{4(1-f)\kappa_s\mu_s}{4\mu_s + 3f\kappa_s}, \quad \mu_0^{hom} = \frac{(1-f)\mu_s}{1 + 6f\frac{\kappa_s + 2\mu_s}{9\kappa_s + 8\mu_s}}, \quad (4)$$

where the parameters κ_s , μ_s , and f represent the elastic bulk modulus, shear modulus of solid matrix, and porosity, respectively, in which κ_s and μ_s can be derived by the elastic modulus E_s and Poisson ν_s of solid phase.

Concerning the assumption of material isotropy and damage extension isotropy, the scalar ω is used to represent the damage variable. Therefore, the effective bulk modulus and shear modulus of damaged rock material can be expressed as:

$$\kappa(\omega) = \kappa_0^{hom}(1 - \omega), \quad \mu(\omega) = \mu_0^{hom}(1 - \omega), \quad (5)$$

As a result, the macroscopic elastic stress-strain relation of the rock in the incremental form writes [24]:

$$d\boldsymbol{\Sigma} = \mathbf{C}_w : (\mathbf{D} - \mathbf{D}^p) + \frac{\partial \mathbf{C}_w}{\partial \omega} : (\boldsymbol{\varepsilon} - \boldsymbol{\varepsilon}^p) d\omega, \quad (6)$$

where \mathbf{C}_w denotes damage stiffness matrix, \mathbf{D} and \mathbf{D}^p represent total strain increment and plastic strain increment, respectively. $\boldsymbol{\varepsilon}$ and $\boldsymbol{\varepsilon}^p$ are the total strain and plastic strain. The total elastic strain tensor is given by $\boldsymbol{\varepsilon}^e = \boldsymbol{\varepsilon} - \boldsymbol{\varepsilon}^p$.

Plastic Model

In general, the M-C yield criterion and D-P yield criterion are used for the yield function. Based on the above experimental results of triaxial compression, the yield surfaces of sandstone under seepage conditions are close to non-linear characteristic of elliptical surface, thus the typical porous plastic criterion proposed by Ref. [25] is used to describe the mechanical response of sandstone in the study. The plastic yield surface equation is defined as:

$$\Phi(\boldsymbol{\Sigma}, f, T, \omega) = \frac{1+2f/3}{T^2} \Sigma_d^2 + \left(\frac{3f}{2T^2} - 1 \right) \Sigma_m^2 + 2h(1-f)\Sigma_m - (1-f)^2 h^2, \quad (7)$$

where Σ_d, Σ_m is the generalized shear stress and mean stress of rock on macro scale respectively.

$$\Sigma_d = \sqrt{\boldsymbol{\Sigma}' : \boldsymbol{\Sigma}'} \quad \Sigma_m = \frac{\Sigma_{11} + \Sigma_{22} + \Sigma_{33}}{3}, \quad (8)$$

T is the plastic hardening function, which reflects the pre-peak strengthening and post-peak softening behavior of sandstone [26]. Based on the thermodynamic framework and the work of [27], the plastic thermodynamic potential of sandstone Γ_p can be obtained as:

$$\Gamma_p = (1-\omega) \left[T_m \gamma_p - (T_m - T_0) b_1 \ln \frac{b_1 + \gamma_p}{b_1} \right], \quad (9)$$

Thus the expression of hardening function T is derived as:

$$T = T(\gamma_p, \omega) = \frac{\partial \Gamma_p}{\partial \gamma_p} = (1-\omega) \left[T_0 + (T_m - T_0) \frac{\gamma_p}{b_1 + \gamma_p} \right], \quad (10)$$

where T_0 and T_m are two parameters related to the position of the initial plastic yield surface and the final plastic yield surface for the rock. b_1 represents the controlling parameter of hardening rate for the rock. The influencing factors of the hardening function include plastic shear strain γ_p of solid matrix and damage variables ω , indicating that hardening function T increases with increasing plastic shear strain γ_p , but decreases with the increasing damage variable ω , indicating the characteristics of increased plastic deformation and post-peak softening for the rock.

In addition, the non-associated plastic potential function G is used to describe the characteristics of rock from compression to expansion, which is defined as follows [25]:

$$G = G(\boldsymbol{\Sigma}, f, t) = \frac{1+2f/3}{Tt} \Sigma_d^2 + \left(\frac{3f}{2Tt} - 1 \right) \Sigma_m^2 + 2h(1-f)\Sigma_m, \quad (11)$$

where t is plastic hardening function related to damage variable and plastic shear strain of rock and can be given by:

$$t = t(\gamma_p, \omega) = (1-\omega) \left(t_0 + (t_m - t_0) \frac{\gamma_p}{b_2 + \gamma_p} \right), \quad (12)$$

where t_0 and t_m are two parameters related to the position of the initial plastic potential function and the final plastic potential function for the rock. b_2 represents the controlling parameter of hardening rate for the rock. In addition, the plastic strain rate of sandstone \mathbf{D}^p is calculated based on the non-associated flow rule as follows:

$$\mathbf{D}^p = d\lambda_p \frac{\partial G}{\partial \boldsymbol{\Sigma}}, \quad (13)$$

where $\dot{\lambda}$ is the plastic multiplier, and it is used to verify the following loading-unloading condition:

$$\begin{cases} d\lambda_p = 0 & \text{if } \Phi < 0 \text{ or if } \Phi = 0 \text{ and } \dot{\Phi} < 0 \\ d\lambda_p \geq 0 & \text{if } \Phi = 0 \text{ and } \dot{\Phi} = 0 \end{cases}, \quad (14)$$

Assuming that the change of pore volume on the microscopic scale only depends on pore plastic compression and expansion, and ignore the influence of new pore nucleation, according to function Eq. 1, we can get that:

$$df = d \left(\frac{\Omega_1}{\Omega} \right) = \frac{d\Omega_1}{\Omega} - \frac{\Omega_1}{\Omega} \frac{d\Omega}{\Omega} = (1-f) \left(\frac{d\Omega}{\Omega} - \frac{d\Omega_m}{\Omega_m} \right), \quad (15)$$

Where $\frac{d\Omega}{\Omega}$ is the mean macroscopic volumetric strain rate $tr\mathbf{D}^p$, $\frac{d\Omega_m}{\Omega_m}$ is the volume strain rate of solid matrix $tr\dot{\boldsymbol{\varepsilon}}$. Based on the assumption that solid matrix obeying Drucker-Prager yield function and non-associated flow rule, the potential is given by $\phi(\boldsymbol{\sigma}) = \sigma_d + t\sigma_m$, thus the mesoscopic strain rate can be written as follows:

$$\dot{\boldsymbol{\varepsilon}} = d\Lambda \frac{\partial \phi}{\partial \boldsymbol{\sigma}}, \quad \dot{\boldsymbol{\varepsilon}}' = d\Lambda \frac{\boldsymbol{\sigma}'}{\sigma_d}, \quad \dot{\varepsilon}_m = \frac{1}{3} t d\Lambda, \quad (16)$$

where $\dot{\boldsymbol{\varepsilon}}'$ is the deviatoric strain rate tensor with $\dot{\boldsymbol{\varepsilon}} = \dot{\boldsymbol{\varepsilon}}' + \dot{\varepsilon}_m \boldsymbol{\delta}$. $d\Lambda$ is the plastic multiplier of the solid matrix. Therefore, the equivalent plastic strain rate $\dot{\gamma}^p$ can be calculated as:

$$\dot{\gamma}^p = \sqrt{\dot{\boldsymbol{\varepsilon}}' : \dot{\boldsymbol{\varepsilon}}'} = d\Lambda, \quad (17)$$

According to the energy-based equivalence condition provided by Ref. [28], the following relation between plastic strain rate of porous medium material and equivalent plastic strain rate of solid matrix can be derived as presented in [29]:

$$\dot{\gamma}^p = \frac{\boldsymbol{\Sigma} : \mathbf{D}^p}{(1-f) \left(Th + (t-T) \frac{\Sigma_m}{1-f} \right)}, \quad (18)$$

With the relations (Eqs 16, 17) and $tr\boldsymbol{\varepsilon} = t\dot{\gamma}^p$ in hand, the variation of porosity in Eq. 15 can be expressed as:

$$df = (1-f) (tr\mathbf{D}^p - t\dot{\gamma}^p), \quad (19)$$

Damage Evolution Criterion

In accordance with the thermodynamic theory, the effect of the damage driving force related to the free energy release rate in the elastic stage on the damage of rock change its internal structure. The internal cracks of the sandstone specimen are mostly closed based on conventional triaxial compression. Therefore, the damage of the sandstone is primarily caused by plastic shear, while the damage caused by the elastic deformation is very small. According to the previous study [21] and ignoring the effect of elasticity, the damage driving force Y_d can be obtained as follows:

$$Y_d = -\frac{\partial \Gamma_p}{\partial \omega} = T_m \gamma_p - (T_m - T_0) b_1 \ln \frac{b_1 + \gamma_p}{b_1}, \quad (20)$$

In addition, the damage evolution criterion of the rock is introduced by the Mazars' research [30], and the damage evolution function f_d can be defined as:

$$f_d = \omega_c \text{th}(B_d Y_d) - \omega \leq 0, \quad (21)$$

where ω_c is the maximum threshold of damage variable and B_d is a parameter related to the rate of damage evolution.

Plastic Damage Constitutive Relations

The plastic flow and damage evolution of sandstone are coupled processes under loading conditions [27]. To reflect the effect of pore water pressure on mechanical behavior of rock, the plasticity multiplier λ^p and damage multiplier λ^d can be determined by coupling plastic flow and damage evolution, which can obtain the consistency conditions of plastic deformation and damage variable for rock material as follows:

$$\begin{cases} \dot{\Phi}(\Sigma, f, T, \omega) = \frac{\partial \Phi}{\partial \Sigma} : d\Sigma + \frac{\partial \Phi}{\partial f} df + \frac{\partial \Phi}{\partial T} \frac{\partial T}{\partial \gamma^p} d\gamma^p + \frac{\partial \Phi}{\partial \omega} d\omega = 0 \\ \dot{f}_d(Y_d, \omega) = \frac{\partial f_d}{\partial Y_d} dY_d + \frac{\partial f_d}{\partial \omega} d\omega = 0 \end{cases}, \quad (22)$$

In addition, based on the plastic flow rule, the increment of plastic deformation and damage variable are defined as:

$$\begin{cases} d\epsilon_p = d\lambda_p \frac{\partial G}{\partial \Sigma} \\ d\omega = d\lambda_d \frac{\partial f_d}{\partial Y_d} \end{cases}, \quad (23)$$

According to Eqs. 6, 7, 10–13, 18–21, the plastic multiplier and the damage evolution multiplier are obtained:

$$\begin{cases} d\lambda_d = (T_m + (T_m - T_0) b_1 / b_1 + \gamma_p) \Sigma : \frac{\partial G}{\partial \Sigma} / (1 - f) \left(Th + (t - T) \frac{\Sigma_m}{1 - f} \right) d\lambda_p \\ d\lambda_p = \frac{\partial \Phi}{\partial \Sigma} : C_w : D \frac{\partial \Phi}{\partial \Sigma} : C_w : \frac{\partial G}{\partial \Sigma} - \frac{\partial \Phi}{\partial f} (1 - f) \left(\frac{\partial G}{\partial \Sigma_m} - tB \right) - \frac{\partial \Phi}{\partial T} \frac{\partial T}{\partial \gamma^p} B - \left(\frac{\partial C_w}{\partial \omega} : \epsilon^e - \frac{\partial \Phi}{\partial T} \frac{\partial T}{\partial \omega} \right) AB \end{cases}, \quad (24)$$

The parameter A and B is written as follows:

$$A = T_m + (T_m - T_0) \frac{b_1}{b_1 + \gamma_p}, \quad B = \frac{\Sigma : \partial G / \partial \Sigma}{(1 - f) \left(Th + (t - T) \frac{\Sigma_m}{1 - f} \right)}, \quad (25)$$

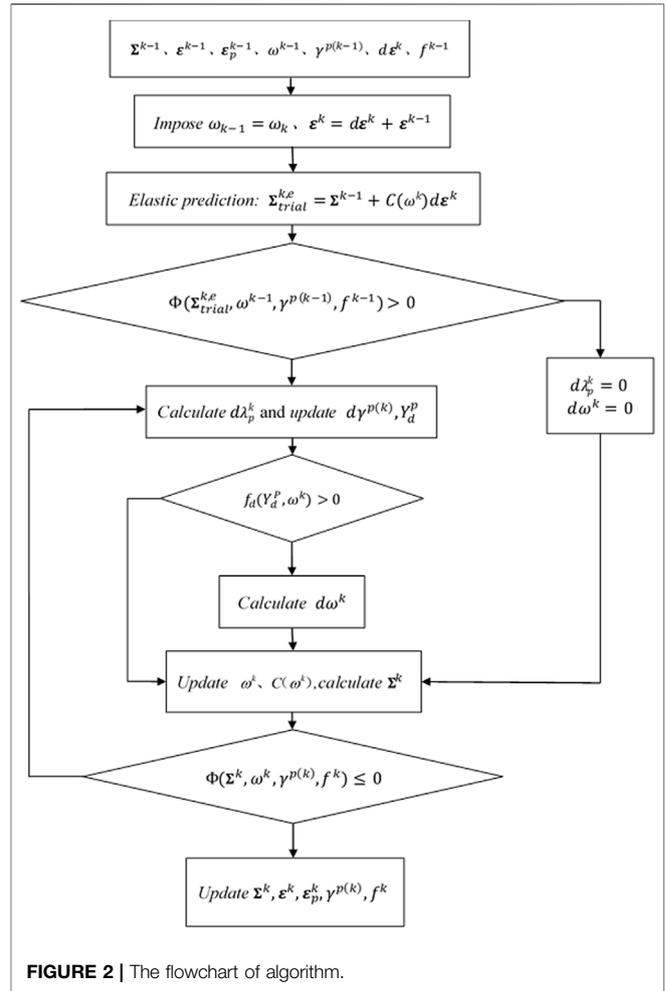


FIGURE 2 | The flowchart of algorithm.

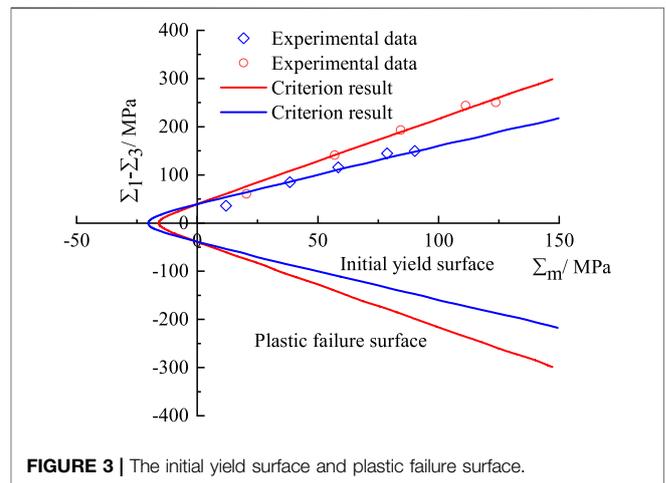


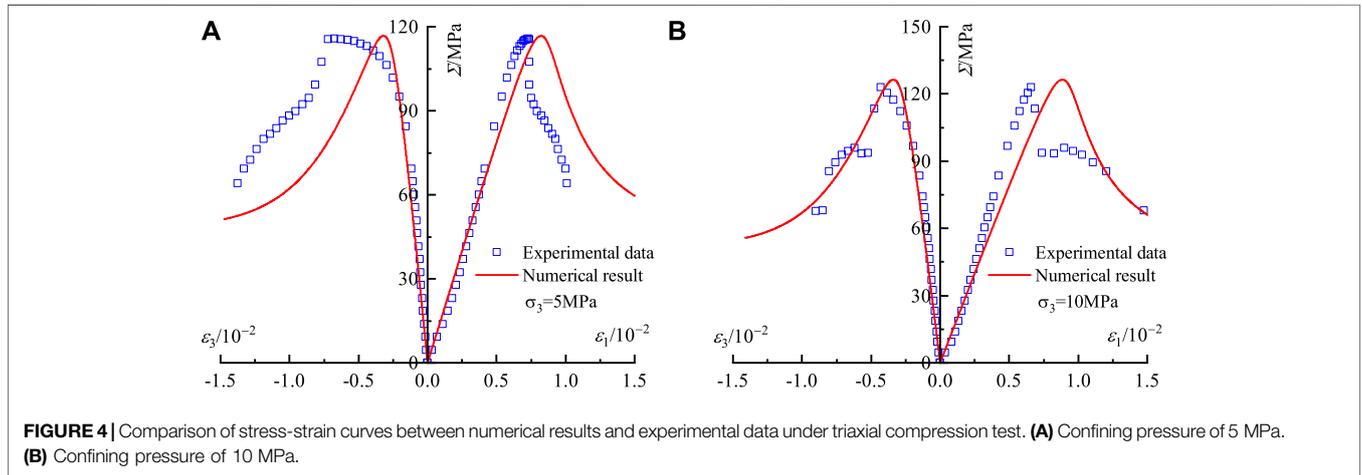
FIGURE 3 | The initial yield surface and plastic failure surface.

MODEL VERIFICATION AND NUMERICAL SIMULATION

In this model, we divided the whole loading process into a limit number of steps. It is assumed that the parameters of the $k-1$ step

TABLE 1 | Parameters of the fitted model.

E_s/GPa	ν_s	T_0	T_m	b_1	t_0	t_m	b_2	f	h/MPa	w_c	B_d
22.5	0.35	0.54	1.2	0.0001	0.5	1.0	0.00005	0.17	60	0.5	70



loading variables including $\Sigma^{k-1}, \epsilon^{k-1}, \epsilon_p^{k-1}, \omega^{k-1}, \gamma^{p(k-1)}, d\epsilon^k, f^{k-1}$ are known, and the parameters of the k step loading variables including $\Sigma^k, \epsilon^k, \epsilon_p^k, \omega^k, \gamma^{p(k)}, f^k$ are calculated according to the displacement loading method. The flowchart of this algorithm is shown in **Figure 2**.

The detailed process of calculation can be divided into the following steps:

- (1) Suppose $d\omega^k = 0$ and $\epsilon^k = \epsilon^{k-1} + d\epsilon^k$; perform elastic prediction $\Sigma_{trial}^{k,e} = \Sigma^{k-1} + C(\omega^{k-1})d\epsilon^k$, where $C(\omega^{k-1})$ is the damage stiffness matrix.
- (2) If $\Phi(\Sigma_{trial}^{k,e}, \omega^{k-1}, \gamma^{p(k-1)}, f^{k-1}) > 0$, namely, the stress is outside the yield surface, which should be amend. According to **Eq. 24**, the plastic multiplier $d\lambda_p$ is calculated, then $d\gamma^{p(k)}$ is updated; otherwise, Σ^k, ϵ^k are directly updated.

- (3) Based on the updated $\gamma^{p(k)}$ and **Eq. 20**, the damage driving force Y_d is calculated, then brought into **Eq. 21** for damage judgment. If $f_d(Y_d, \omega^k) > 0$, $d\omega^k$ is calculated according to **Eq. 23**, then the damage variable ω^k is updated, otherwise, $\omega^k = \omega^{k-1}$.
- (4) Damage stiffness matrix $C(\omega^k)$ is updated based on ω^k . In addition, the updated variables are brought into thermodynamic potential to obtain the stress Σ^k .
- (5) If $\Phi(\Sigma^k, \omega^k, \gamma^{p(k)}, f^k) \leq 0$, namely, the stress tensor is in the plastic yield plane after plastic damage was corrected. Get the parameters of the k step loading variables, including $\Sigma^k, \epsilon^k, \epsilon_p^k, \omega^k, \gamma^{p(k)}, f^k$. Otherwise, go to **Eqs. 2–4** until the new stress is within the plastic yield plane.

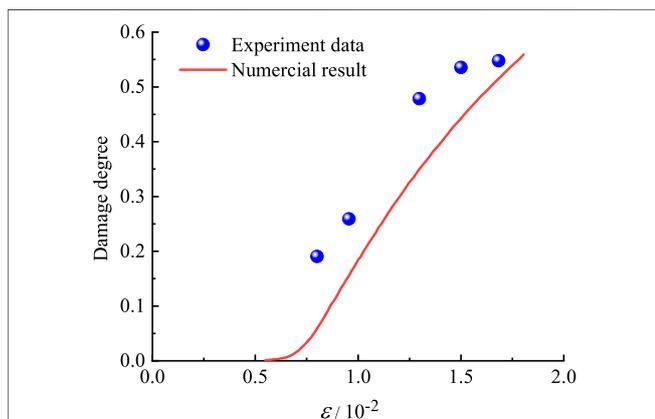


FIGURE 5 | Comparison of damage evolution curve between numerical results and experimental data.

First, according to the previous studies [7, 29], basic parameters of the sandstone, such as the elastic modulus E_s , Poisson’s ratio ν_s of solid matrix can be determined by the conventional triaxial test based on inverse calculation of **Eq. 4**. Porosity parameters f can be determined by saturation test. In addition, the plastic parameters h, T_m and T_0 can be calculated by the least square method and the initial plastic yield surface, respectively. The initial yield surface and plastic failure surface are shown in **Figure 3**. The evolution law of plastic deformation ϵ^p can be obtained through loading and unloading tests, and then **Eqs. 7, 11** are fitted to determine parameters b_1 and b_2 respectively. The damage variable threshold ω_c and the control parameter B_d can be obtained by experimental data and the inversion of **Eq. 20**, respectively. In this paper, the experimental mechanical parameters used in the numerical simulation are listed in **Table 1**.

Figure 4 shows the experimental stress-strain curves of sandstone and the corresponding numerical results. As can be seen from **Figure 4**, it is obvious that the experimental data and

numerical results are very close before the peak stress, which shows that the non-linear transition from brittleness to plasticity for the sandstone can be well fitted with increasing the strain.

In order to further verify the rationality of the damage evolution model, a comparative analysis was made between the damage evolution value and the test results under the condition of 10 MPa confining pressure (Figure 5), in which the damage evolution test data were calculated by the acoustic emission method. As shown in Figure 5, damage development is very limited in the initial loading stage. With the increase of deviatorial stress, mechanical damage gradually develops and eventually leads to rock failure.

CONCLUSION

In this paper, an elastoplastic damage constitutive model for sandstone considering the influence of rock pores is constructed based on the previous research results and the knowledge framework of irreversible thermodynamics. In this proposed model, the plastic flow and damage evolution of sandstone are coupled and combine with non-associative plastic potential function to capture its elastoplastic behaviors.

In order to verify its prediction ability of porous rocks damage evolution, the numerical simulations of this model have been plotted and compared with experimental data of triaxial compression tests on sandstone. A good agreement between the numerical and experimental results has been observed,

indicating that the proposed model is able to describe the main features of porous sandstone.

DATA AVAILABILITY STATEMENT

The original contributions presented in the study are included in the article/Supplementary Material, further inquiries can be directed to the corresponding author.

AUTHOR CONTRIBUTIONS

CC: Conceptualization, Methodology, Software, Investigation, Formal Analysis, Writing—Original Draft; CY: Conceptualization, Resources, Supervision, Writing—Review and Editing.

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