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Chaotic and fractal maps in higher-order derivative dynamical systems

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Hamiltonian maps are considered a class of dynamical systems that hold meticulous properties used to model a large number of complex dynamical systems. When time flows in dynamical systems with two-dimensional degrees of freedom, the trajectories in phase space can be analyzed within bidimensional surfaces known as Poincaré sections. The Chirikov–Taylor standard map for two canonical dynamical variables (momentum and coordinate) is the most renewed map characterized by a family of area-preserving maps with a single parameter that controls the degree of chaos. In this study, a generalization of the standard map for two different problems is presented and discussed. The first problem deals with the higher-order derivative Hamiltonian system (up to the fourth order) since the fourth-order characteristic provides the possibility of chaotic behavior at all scales including nanoscales where high-order derivatives take place in nanosystems. The second problem concerns the time-dependent δ -kicked rotor in fractal dimensions characterized by a time-dependent potential due to its important implications in quantum chaos. This study shows that higher-order derivative maps and fractal dimensional δ -kicked rotor maps apparently exhibit a large number of chaotic orbits and fractal patterns, including the spiral fractal patterns comparable to the Julia set. Moreover, these problems are characterized by additional parameters which can be used to control chaos. Some of these parameters lead to chaos, and others lead to fractal patterns.

KEYWORDS

standard map, δ -kicked rotor, higher-order derivative Hamiltonians, fractal dimensions, chaos

Introduction

Classical mechanics is successfully described based on the Lagrangian and Hamiltonian formalisms, which fulfill the locality basic property. The trajectory of any body and its associated derivatives depend on a single point. The most significant results of both formalisms, including Noether's theorem for dynamical systems with an infinite number of degrees of freedom, are well-known in the literature [1]. A classical local dynamical system consists of a set of possible local states described by one or a set of second-order differential equations. A basic account of these equations can be obtained by means of

the discrete time framework modeled through maps, e.g., the kicked-rotor problem, which plays an important role in dynamical systems. These discrete maps alternate a system of differential equations and are practical in computational modeling of complex dynamical systems [2, 3]. In case of higher-order differential equations, e.g., the fourth-order differential equations, they offer the possibility of chaotic behavior in contrast to second-order autonomous differential equations, principally since such systems do not have an adequate amount of degrees of freedom. Hence, one naturally expects that n th-order differential equations will offer a rich variety of patterns and chaotic structures than the second-order differential equations. In general, any system described by a second-order Lagrangian leads to a fourth-order Lagrangian [4–8]. A supplementary advance in the theory of differential equations both facilitates applications and offers new insights in applied mathematics. The penultimate motive for this study is to understand the causal structure of higher-order differential equations, in particular of fourth-order equations, to study their associated standard map, and finally to understand the impacts of fractal dimensions on them. The reason to consider fractal dimensions in this study is based on the fact that fractals are a type of dynamic system generated by recursion. They depend on initial conditions and generate a kind of non-periodic orbits. Fractals, therefore, belong to chaotic dynamical systems. Let us stress that not all chaotic systems are fractals, e.g., stochastic dynamical systems. In phase space, a chaotic orbit traces out a fractal dimensional strange attractor, i.e., strange attractors exhibit the fractal structure [9]. Substantial attention is given, in this study, to two main types of problems, which generalize the basic standard map, known as the Chirikov–Taylor standard map [2]. These problems are expressed as follows:

1. The problem of the fourth-order differential equation is expressed as follows:

$$-\gamma u^{(4)}(x) + \beta u''(x) + K \sin u(x) = 0, \quad (1)$$

where $u = u(x)$ is a function of the space x and $\beta \in \mathbb{R}^+$ and $\gamma \in \mathbb{R}^+$ are assumed to be small parameters. We will prove that the limit of the problem will lead to the “kicked rotor” problem in higher-order derivative theory. Higher-order dynamical systems play a pertinent role in theoretical physics, applied mathematics, and numerical analysis. This problem is of particular importance since it may have motivating implications in the understanding of the kicked-rotor problem, formed by periodically pulsing on the optical higher-order standing waves [10, 11].

2. The problem of “time-dependent δ -kicked rotor” formulated in fractal dimensions. We are interested on fractal calculus concepts introduced in [12, 13], where the derivatives of two given functions are given by $f(x)$ and $g(t)$, which are expressed as $d^\alpha f(x)/dx^\alpha = (x^{1-\alpha}/\alpha)(df(x)/dx)$, $\alpha > 0$ and $d^\beta g(t)/dt^\beta = (t^{1-\beta}/\beta)(dg(t)/dt)$, $\beta > 0$, respectively. Here, α and β are their associated fractal dimensions. It is obvious that the fractal length measure x and the fractal time

measure t are scaled according to the laws x^α and t^β . This approach has motivating implications in various fields of sciences and engineering and at different lengths and time scales [14–20]. These fractal derivatives are considered a non-Newtonian simplification of the derivative defined in fractal medium or topology. Self-similarity and scale invariance are two important concepts in physics and any complex dynamical systems governed by Lagrangian and Hamiltonian mechanics laws. In general, the notion of non-integer fractal dimension has been spread over all fields of sciences since Mandelbrot introduced the notion of fractals or self-similar sets [21]. It is notable that fractal calculus is of practical importance in various fields of physics since it is considered, to some extent, trouble-free, helpful, and algorithmic [22]. It is also used in the theory of differential equations to study stability problems [23–25] besides its relevance in stochastic differential equations [26, 27] and transforms approaches such as the Laplace, Fourier, and Sumudu fractal transforms [28, 29]. The relevance of fractal calculus in sciences is well-appreciated based on a large number of outcomes obtained by researchers [30–47]. In the literature, there are various types of fractal derivatives where various inequalities have been obtained, and new classes of differential equations have been derived and analyzed accordingly [34, 48–57]. However, He’s fractal derivative is an extension of Leibniz’s derivative for discontinuous fractal media and is less tricky in mathematical analysis, but with relevance in various fields of sciences, as mentioned previously, including geometric analysis [58], attachment oscillator arising from nanotechnology [59], variational study of the time–space fractal Bogoyavlenskii equation [59], non-linear vibrations [60], and fractal nano/micromechanical system [61].

The purpose of this paper is to study the whole dynamical behavior of maps generated by these problems. We investigate the chaotic and complex behavior of standard maps by selecting various control parameters. From a practical point of view, we show that in addition to the usual stochastic parameter, there are additional parameters in each model, which can be used as chaos control parameters.

Before elaborating our analysis, two points deserve to be elucidated:

1. The investigation of higher-order derivative Hamiltonian systems (up to the fourth-order) is relevant as it offers insights into chaotic behavior across multiple scales, including the nanoscale. This shows potential to enhance our understanding of physical systems like micro-electromechanical systems (MEMS), where high-order derivatives play a crucial role. For example, in MEMS devices, the mechanical behavior at small scales can be highly non-linear and may exhibit chaotic dynamics that could be better understood through the study of such higher-order systems [62–69].

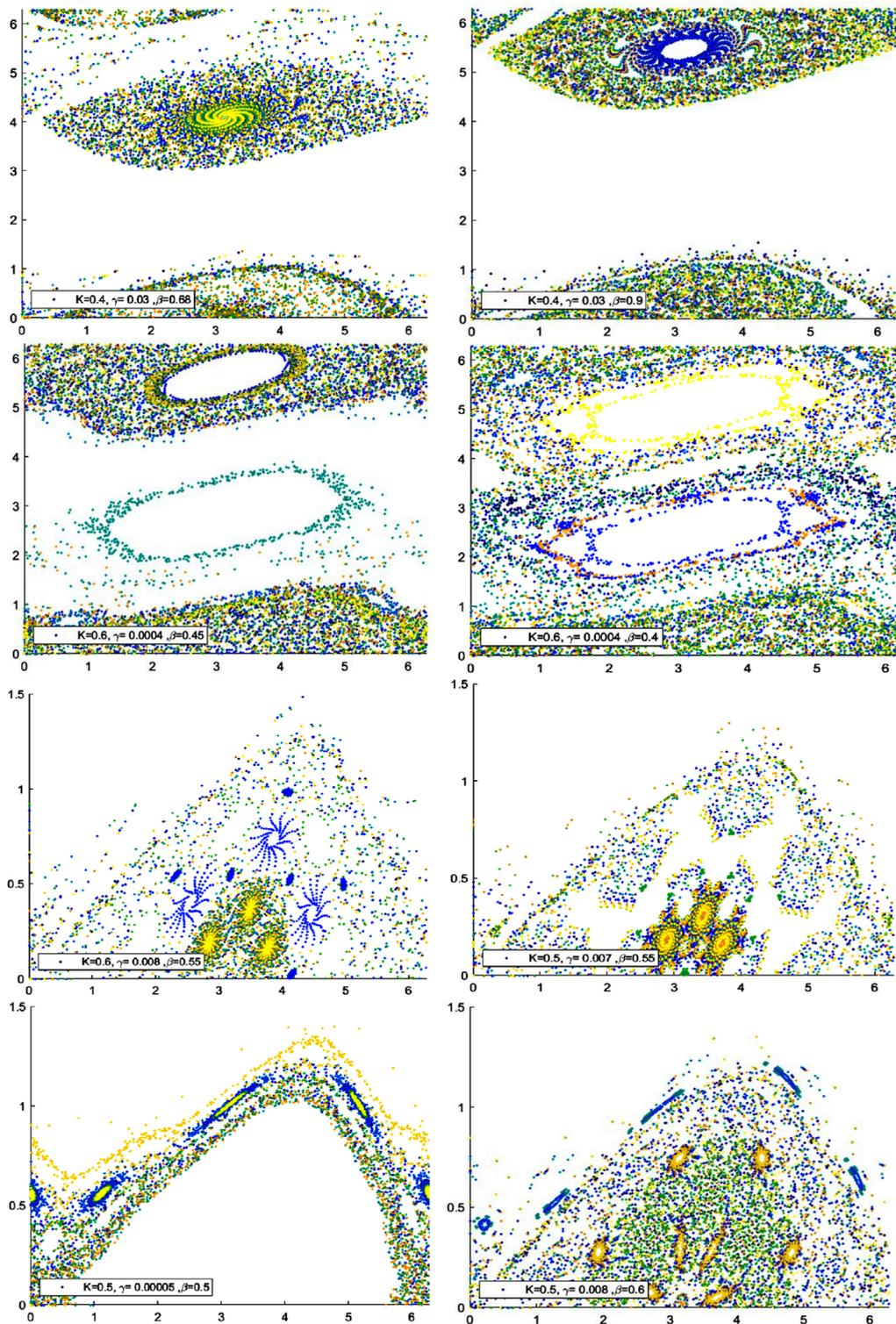
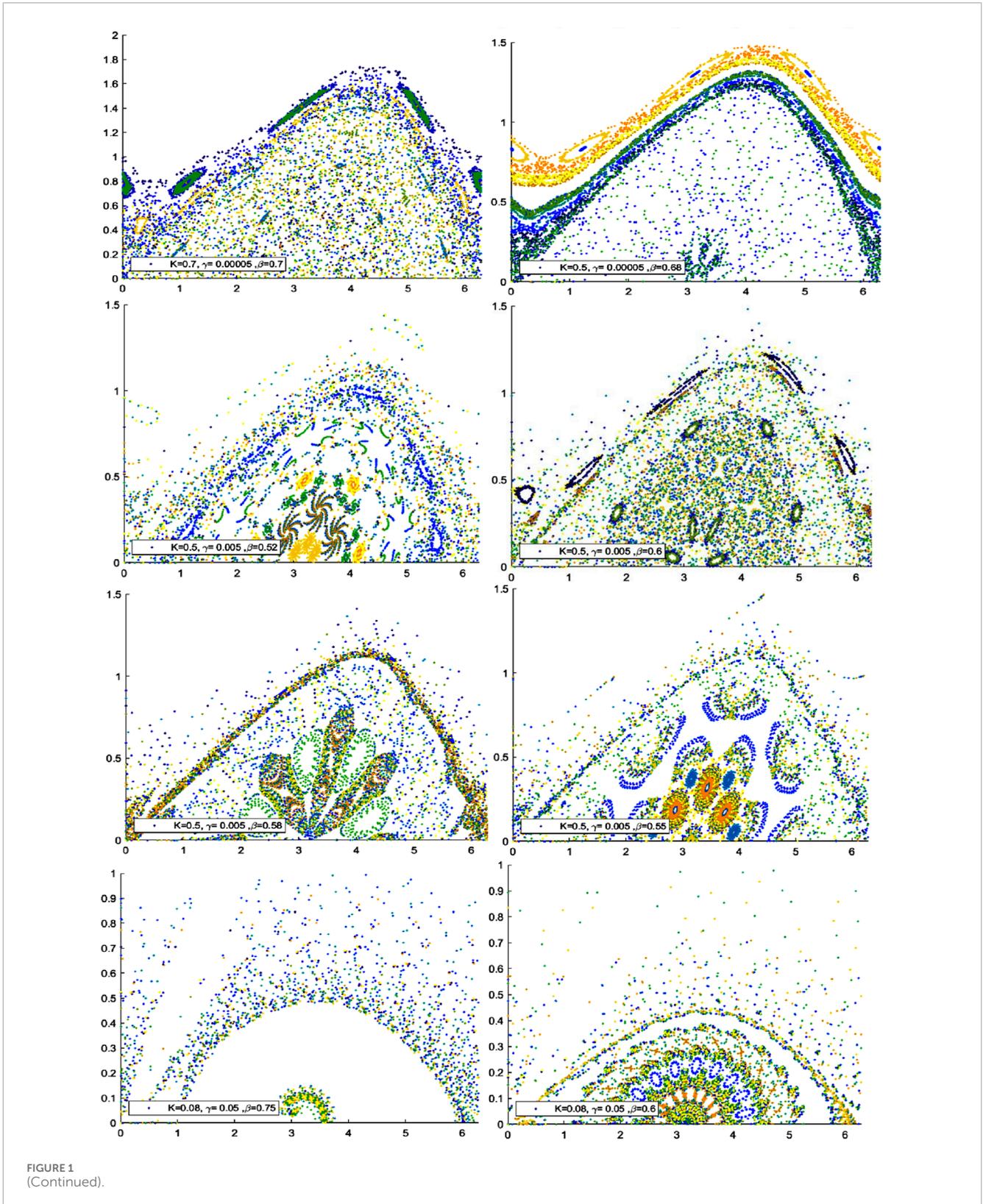


FIGURE 1 (Continued).

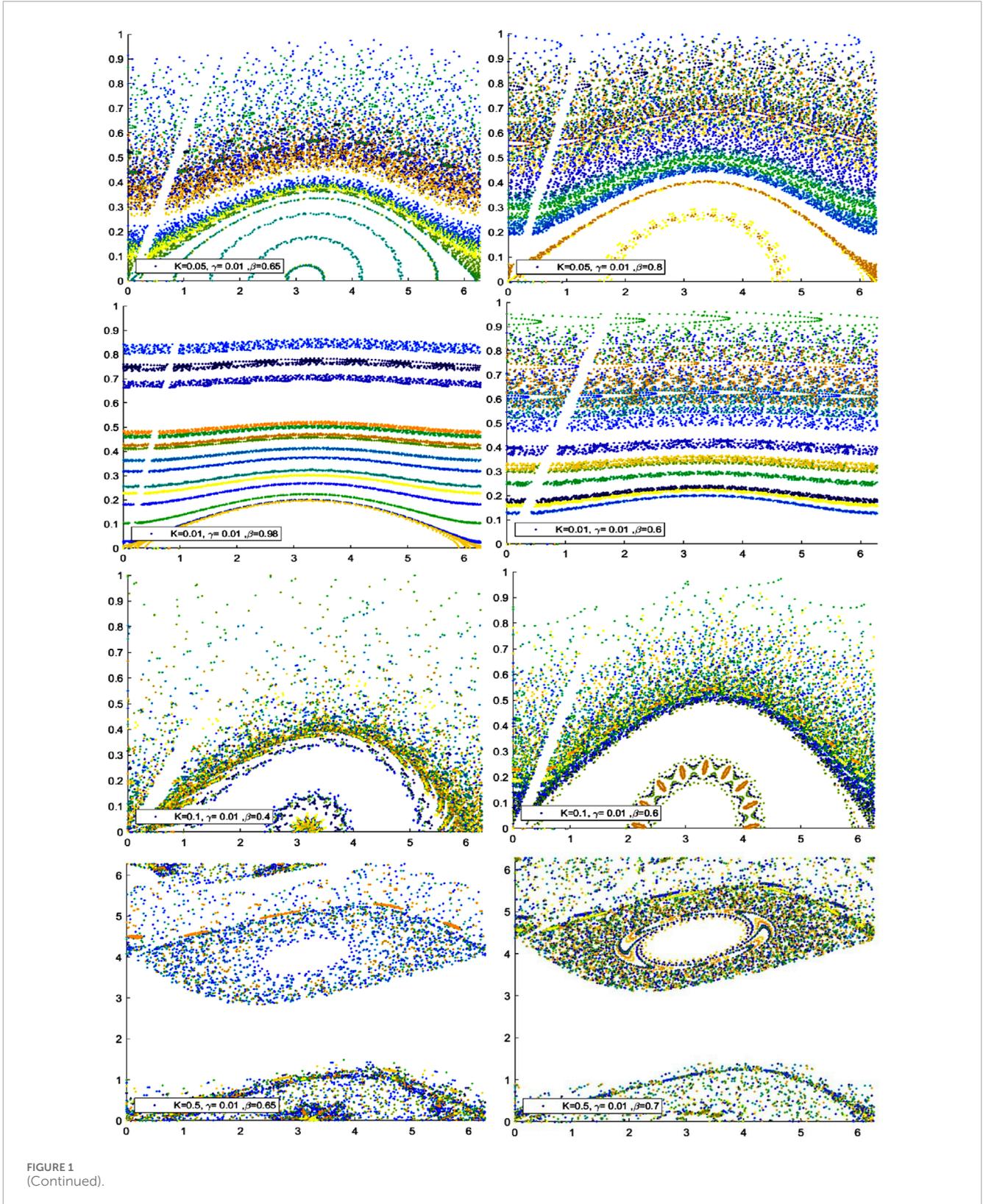
2. In our approach, we used the two-scale fractal development: in fact, the two-scale dimension is of great importance to describe any physical property of a complex system. It is used to evaluate

the degree of complexity of a given discontinuous pattern between two neighboring dissimilar scales of observation [70]. It is considered an alternative definition of fractal



dimension. It is notable that physical laws are scale-dependent, and dissimilar outcomes may be obtained at different scales. The two-scale theory is practical since it treats any physical

or dynamical problem with two different scales applied respectively for continuous and porous structures media: the conventional classic calculus can be successfully applied for



the large scale, whereas for the smaller scale, the effect of the porous structure on the physical properties of the system can be effortlessly explained and, hence, reveal a number

of hidden properties beyond the classical assumption. The validation of this new methodology has been proved using qualitative and quantitative/numerical techniques [70–80].

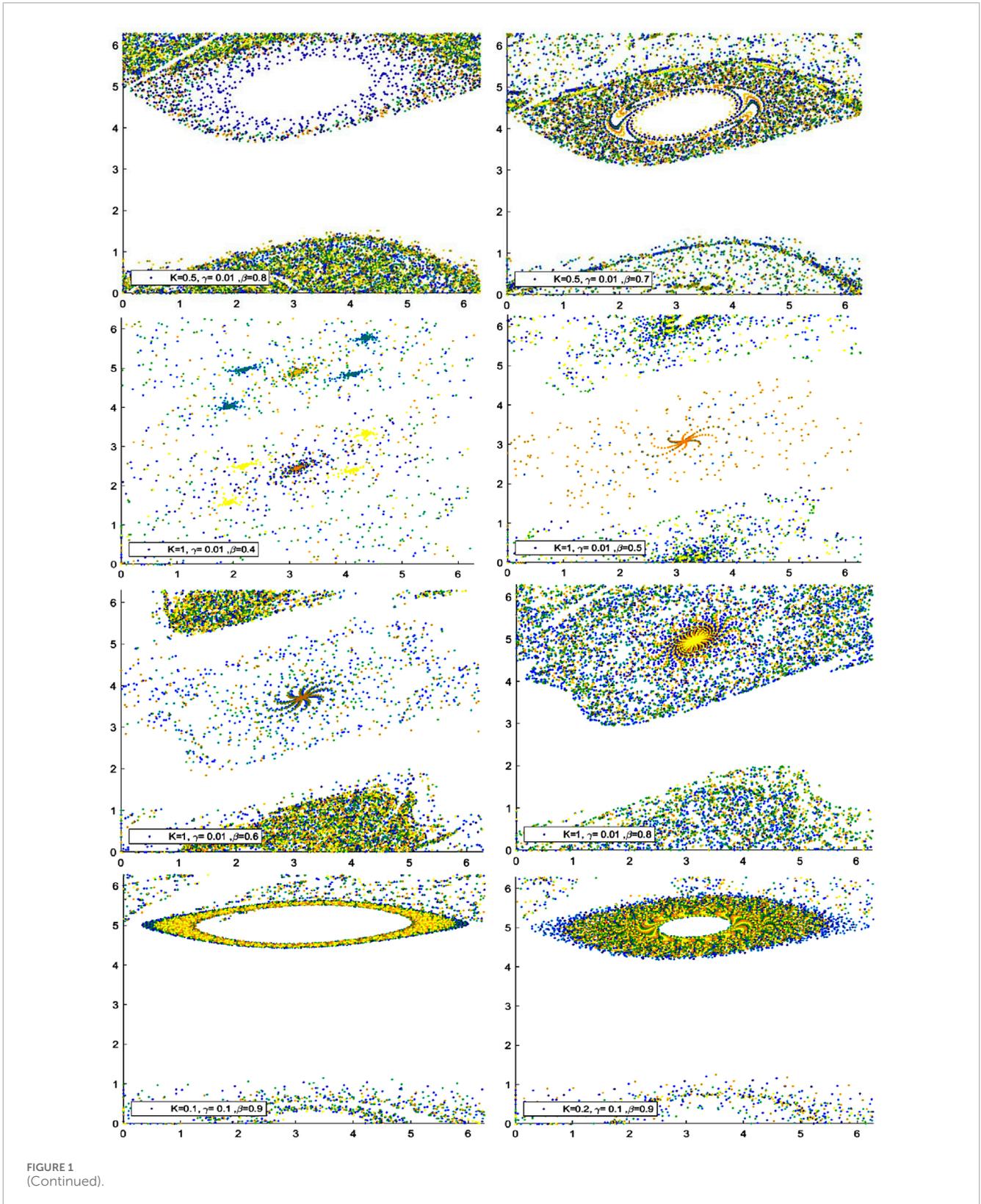
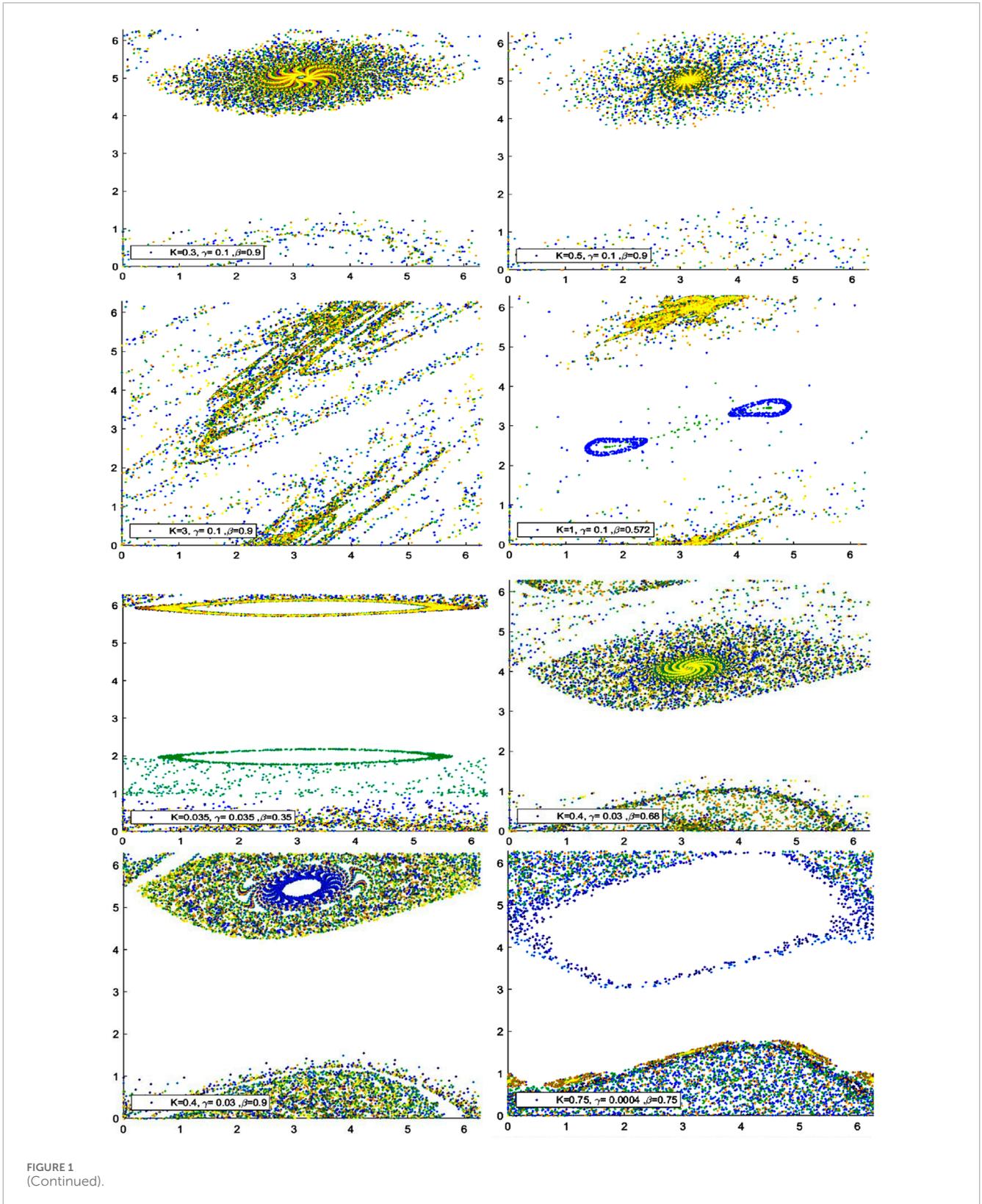


FIGURE 1 (Continued).

Therefore, it is motivating to consider, in this study, two-scale dimensions since they reveal a number of hidden properties and features not found within the conventional formalism.

Problem 1: To start, we introduce the Hamiltonian of Equation 1, which is written as

$$H(u, v, p_u, p_v) = \frac{1}{2\gamma} p_v^2 + v p_u - \frac{\beta}{2} v^2 + \sin u,$$



where $v = u'$, $p_u = \beta u' - \gamma u'''$, and $p_v = \gamma u''$ [5]. The associated Hamilton's equations of motion are $v = u' = \partial H / \partial p_u$, $v' = \partial H / \partial p_v$, $p'_u = -\partial H / \partial u$, and $p'_v = -\partial H / \partial v$. To construct a map, we introduce

a small number $\epsilon \ll 1$ such that

$$u_{n+1} = u(x_{n+1}) = \lim_{\epsilon \rightarrow 0^+} u(x(n+1) - \epsilon), \quad (2)$$

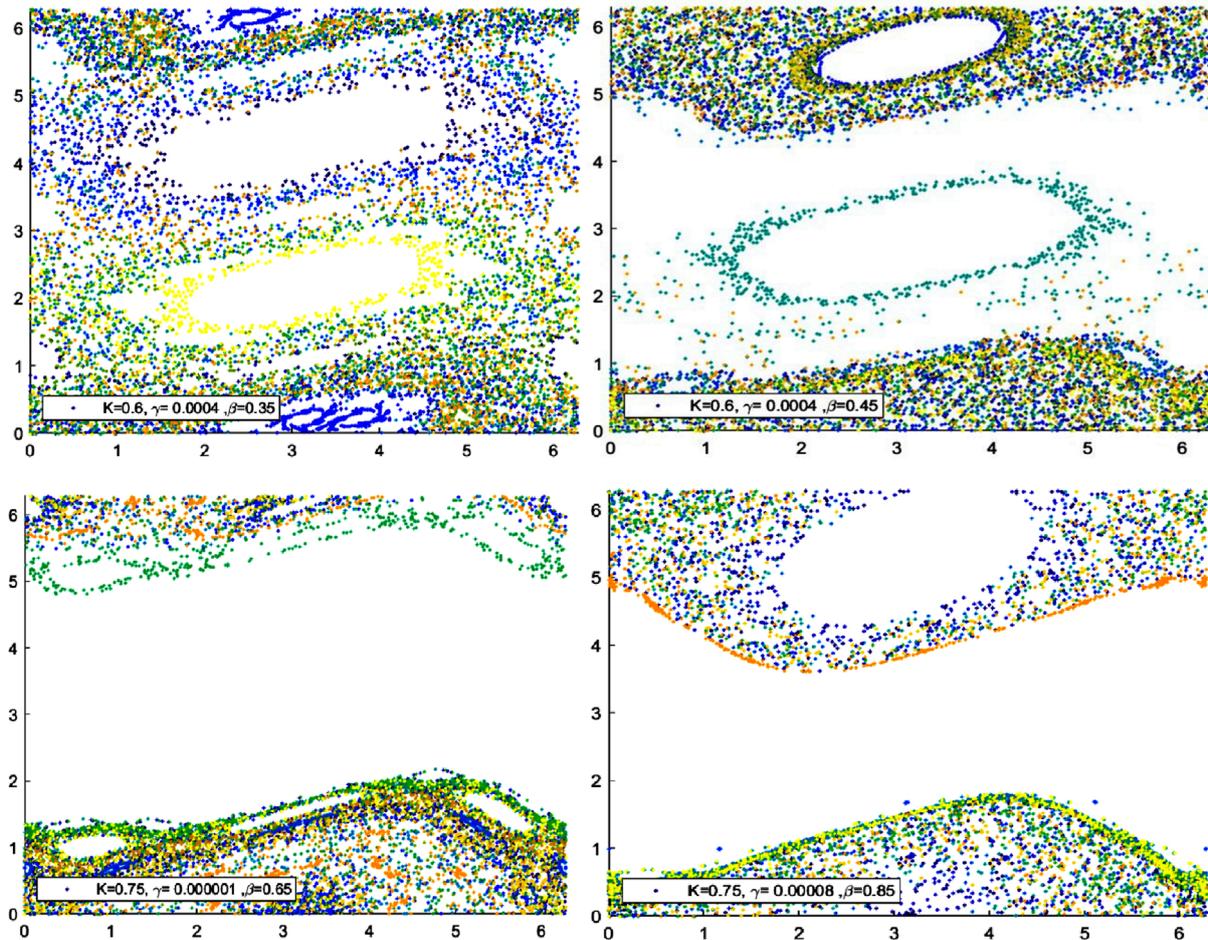


FIGURE 1 (Continued). Particle orbits of the modified standard map for the different stochastic parameter K and parameters β and γ .

$$v_{n+1} = v(x_{n+1}) = \lim_{\epsilon \rightarrow 0^+} v(x(n+1) - \epsilon), \tag{3}$$

$$u p_{n+1} = u p(x_{n+1}) \equiv p(x_{n+1}) = \lim_{\epsilon \rightarrow 0^+} p(x(n+1) - \epsilon), \tag{4}$$

$$v p_{n+1} = v p(x_{n+1}) \equiv P(x_{n+1}) = \lim_{\epsilon \rightarrow 0^+} P(x(n+1) - \epsilon), \tag{5}$$

where $x_{n+1} = (n+1)x$. Integrating the Hamilton's equation yields

$$p_{n+1} = p_n + K \sin u_n, \tag{6}$$

$$u_{n+1} = u_n + p_{n+1}, \tag{7}$$

$$P_{n+1} - P_n = -P_{n+1} + \beta(u_{n+1} - u_n), \tag{8}$$

$$\gamma(v_{n+1} - v_n) = P_{n+1} = \gamma(u_{n+1} - 2u_n + u_{n-1}), \tag{9}$$

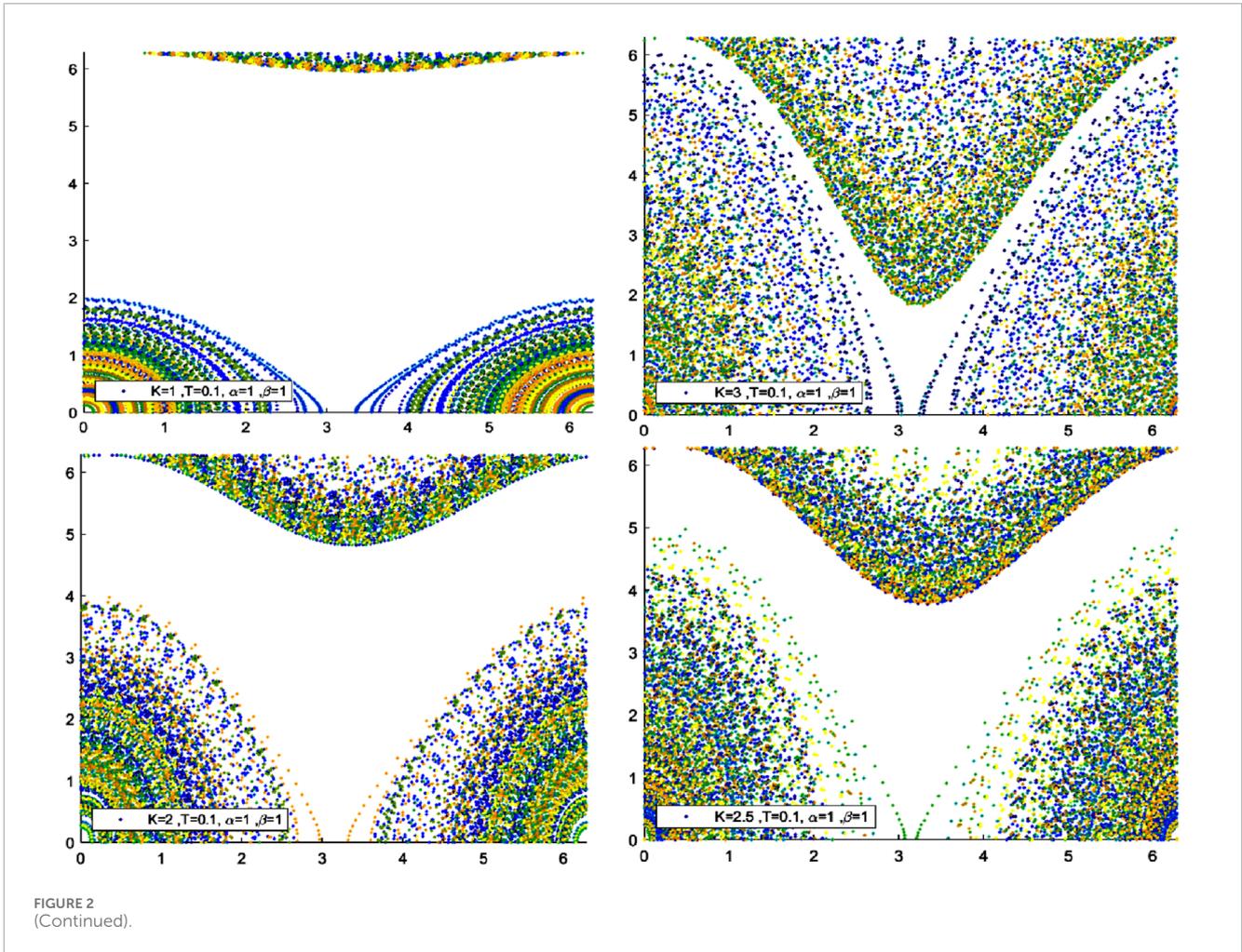
which, after arrangement, also yields the modified standard map:

$$p_{n+1} = \beta(u_{n+1} - u_n) - \gamma(u_{n+1} - 3u_n + 3u_{n-1} - u_{n-2}), \tag{10}$$

$$p_{n+1} = p_n + K \sin u_n. \tag{11}$$

For $\beta = 1$ and $\gamma = 0$, Equations 2–9 reduce Equations 10, 11 to the Chirikov–Taylor standard map. In order to examine the typical features of the dynamics determined by the modified standard map, let us start our analysis with the results of the numerical observations of the particle motions in the phase space. We plot in Figure 1 accordingly, by running a program in MATLAB, the following figures (Poincaré sections) for different numerical values of the parameters β and γ .

We observe the emergence of a family of patterns, including fractals and chaotic patterns. Decreasing K suppresses the deterministic diffusion significantly and may lead to chaotic maps. Decreasing both K and γ also suppresses the formation of islands around islands. There is a classic evidence of stickiness in these plots and transition to chaos (chaotic sea) in some. Orbits are subject to consecutive traps, filling regions more densely than others. In some cases, we observe the Kolmogorov–Arnold–Moser (KAM) secondary islands corresponding to a certain resonance. We recall that the KAM theorem states that for non-integrable



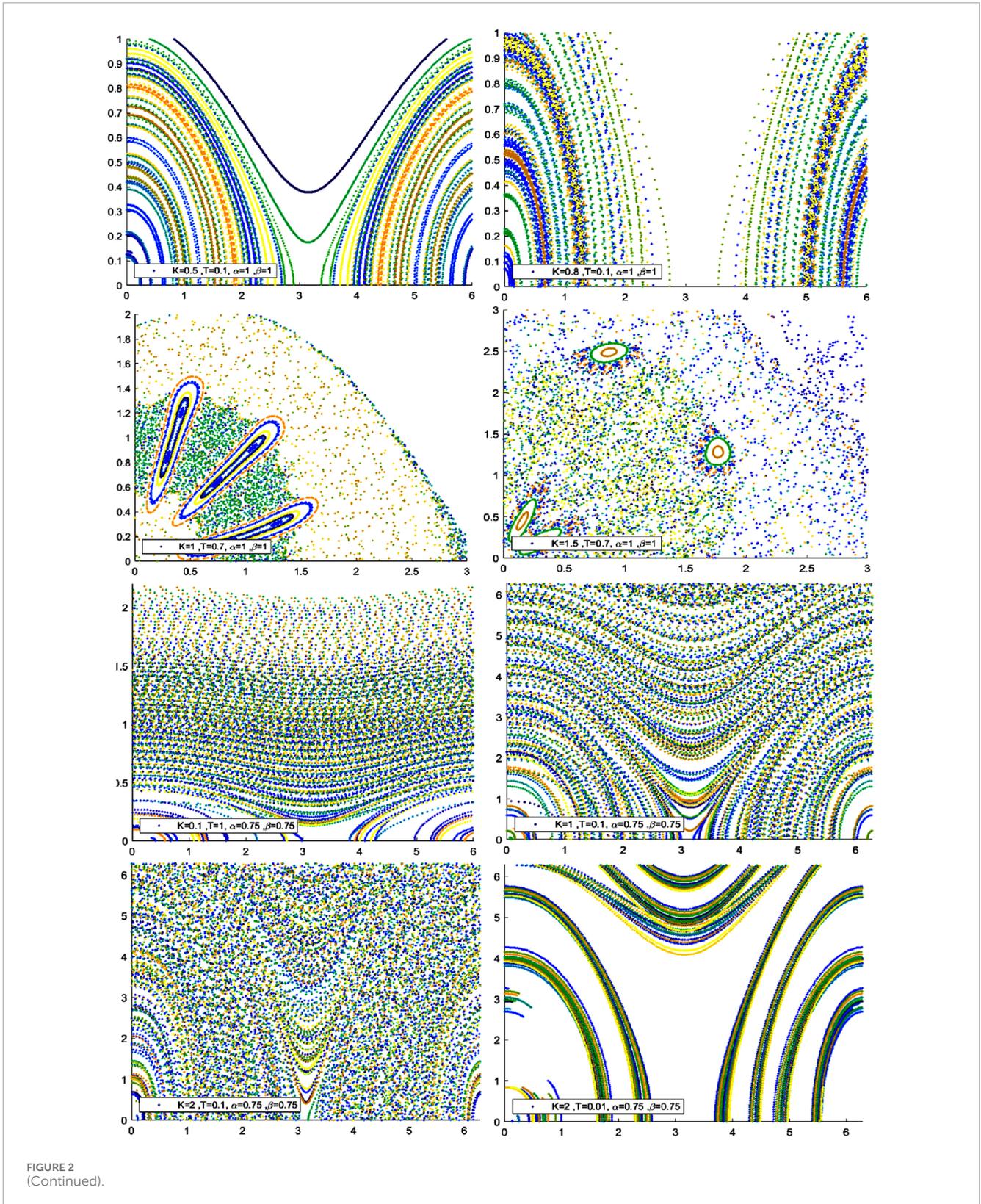
Hamiltonian systems, only non-destroyed orbits have quasiperiodic irrational winding numbers. We also observe islands in the chaotic sea, while islands of certain resonance are inside the corresponding last KAM curve. Small islands also emerge for certain values of K , besides unstable and stable orbits. There is an emergence of chaotic orbits depending on the values of the system parameters. For lower values of K , the size of the central island is reduced and is limited by a number of unstable periodic orbits. For some values of K which are close to unity, there is emergence of spiral fractal patterns comparable to the Julia set [81, 82]. An arbitrary small variation in the parameters causes radical changes in the patterns. We recall that, in general, the standard map has an attractive property; it has a fractal behavior. Further consecutive amplifications would confirm the fractal-like structure of this model. Chaotic regions with various chaoticities are also observed, besides the chaotic chains whose chaoticities are weaker than other chaotic seas. These maps exhibit chaotic and fractal behaviors separately or together in the available phase space as the control parameters change. The breakdown of the ergodicity of this map may lead to a deformation of the statistical mechanical framework [83]. In fact, non-linear dynamical systems exhibit fractal structures in

the phase space, and they are very sensitive to initial conditions [84]. This problem, however, has received less attention, for higher-order derivative theories. In this problem, we proved that fractal structures arise in fourth-order derivative theories, although the geometrization of Hamiltonian formalisms was developed for autonomous and non-autonomous mechanical systems [85–87].

Problem 2: We are concerned with the classical global momentum transport in the kicked rotor governed by the time-dependent Hamiltonian (time-dependent δ -kicked rotor):

$$H(x, p, t) = \frac{p^2}{2} + KTV(x, t) \sum_{n=-\infty}^{n=+\infty} \delta(t - n), \tag{12}$$

where K is the amplitude of the pulse, T is the period of oscillations, p is the momentum, $V(x, t)$ is a time-dependent potential, and δ is the Dirac delta-function. Equation 12 is subject to the initial conditions $x(0) = x_0$ and $\dot{x}(0) = p(0) = p_0$ [1–3]. When K is adequately large, no KAM invariant circles



bound the motion. The presence of the Dirac function is suitable since the equations of motion can be reduced to a simple discrete Chirikov–Taylor standard map. It is notable that during

the kick, the potential term dominates the kinetic term, the potential is zero between kicks, and the motion is that of a free rotor. One can, therefore, integrate easily the equations

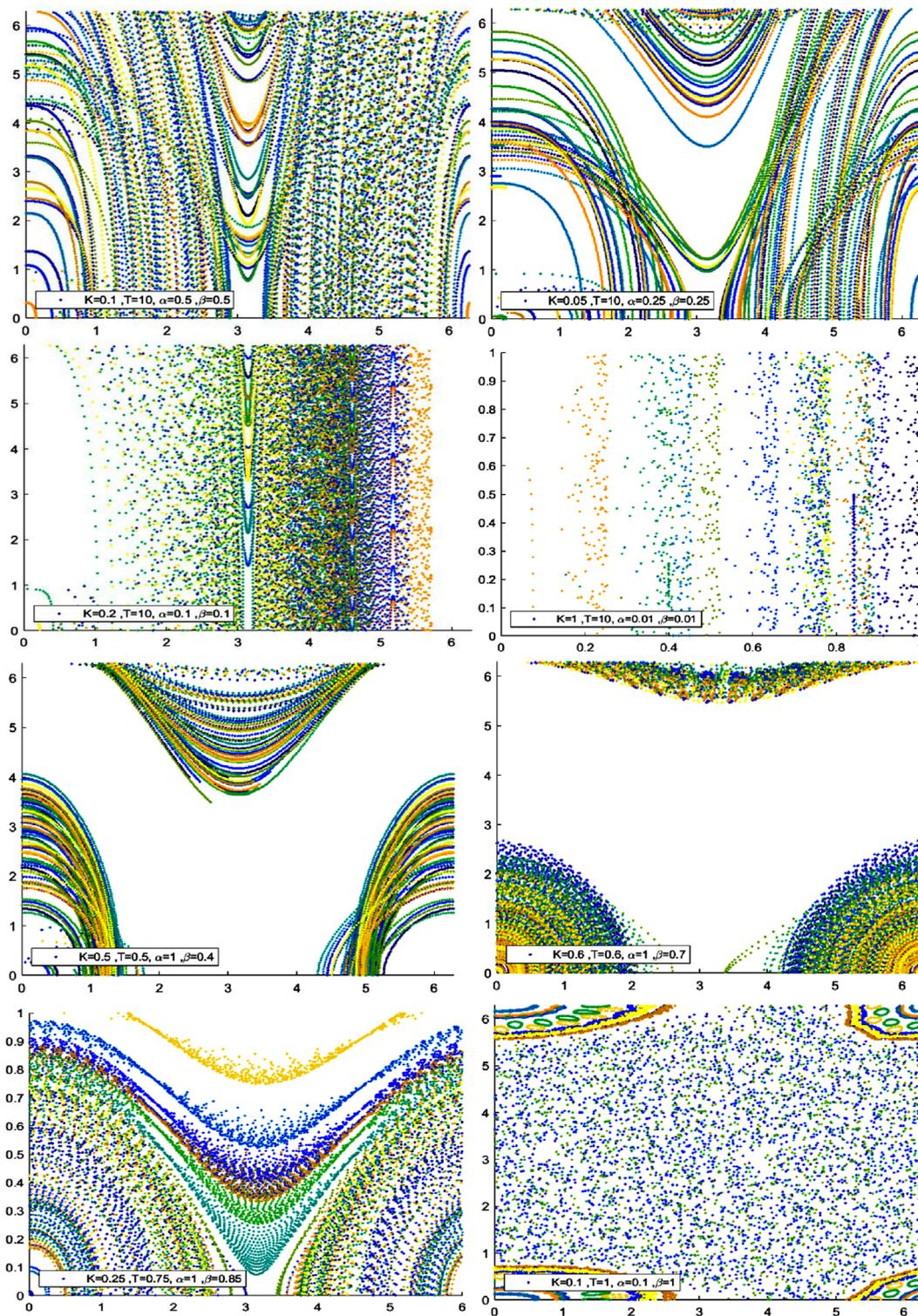


FIGURE 2 (Continued).

of motion over one temporal period of the Hamiltonian [2, 3, 88, 89]. However, in our approach, we considered a time-dependent potential due to their motivating implications in

controlling quantum chaos [90–95]. In this study, we consider $V(x, t) = t^\eta \cos x$, with η being a real parameter. In fact, periodic time-dependent Hamiltonian systems are said to be of n and

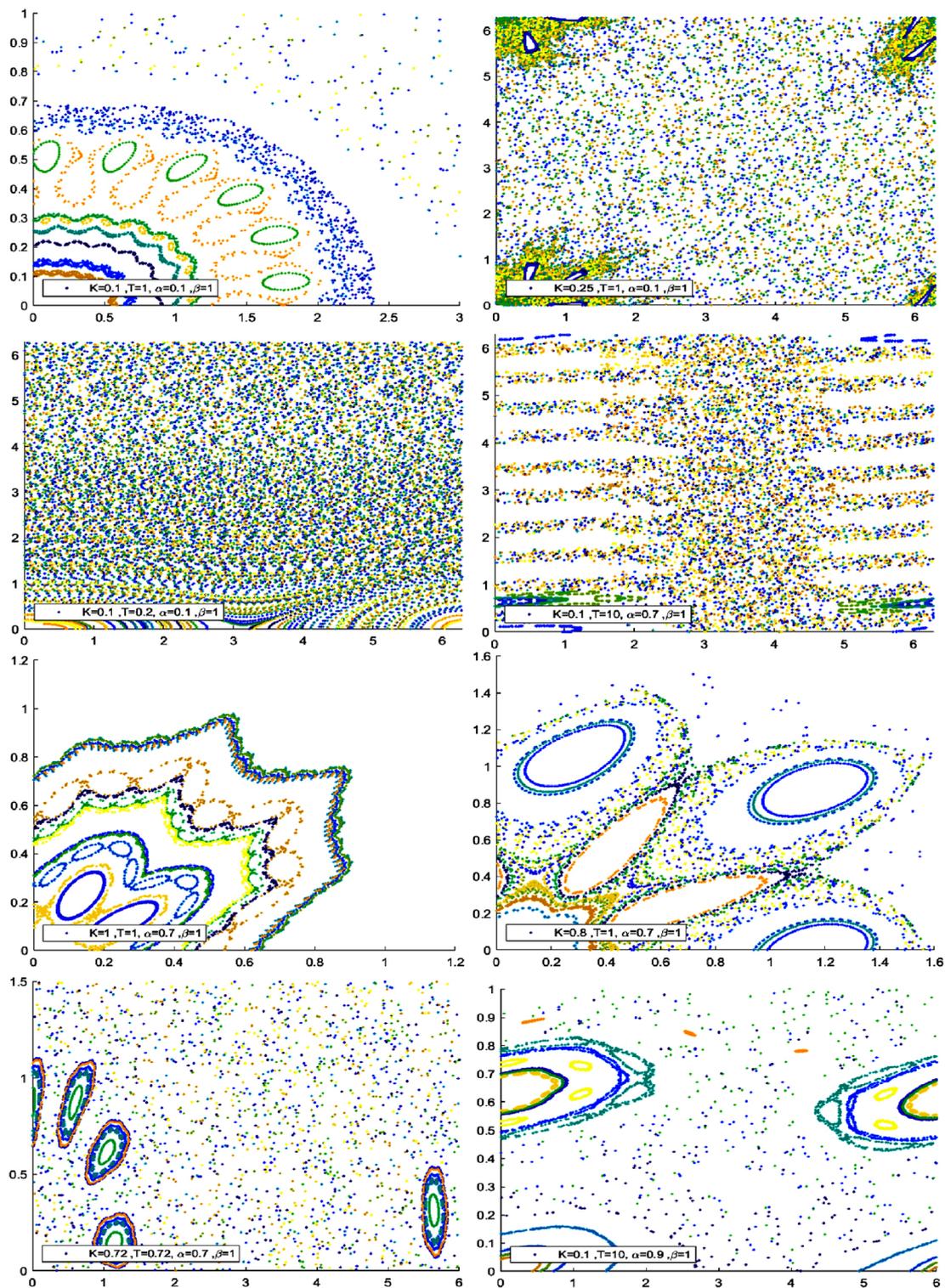
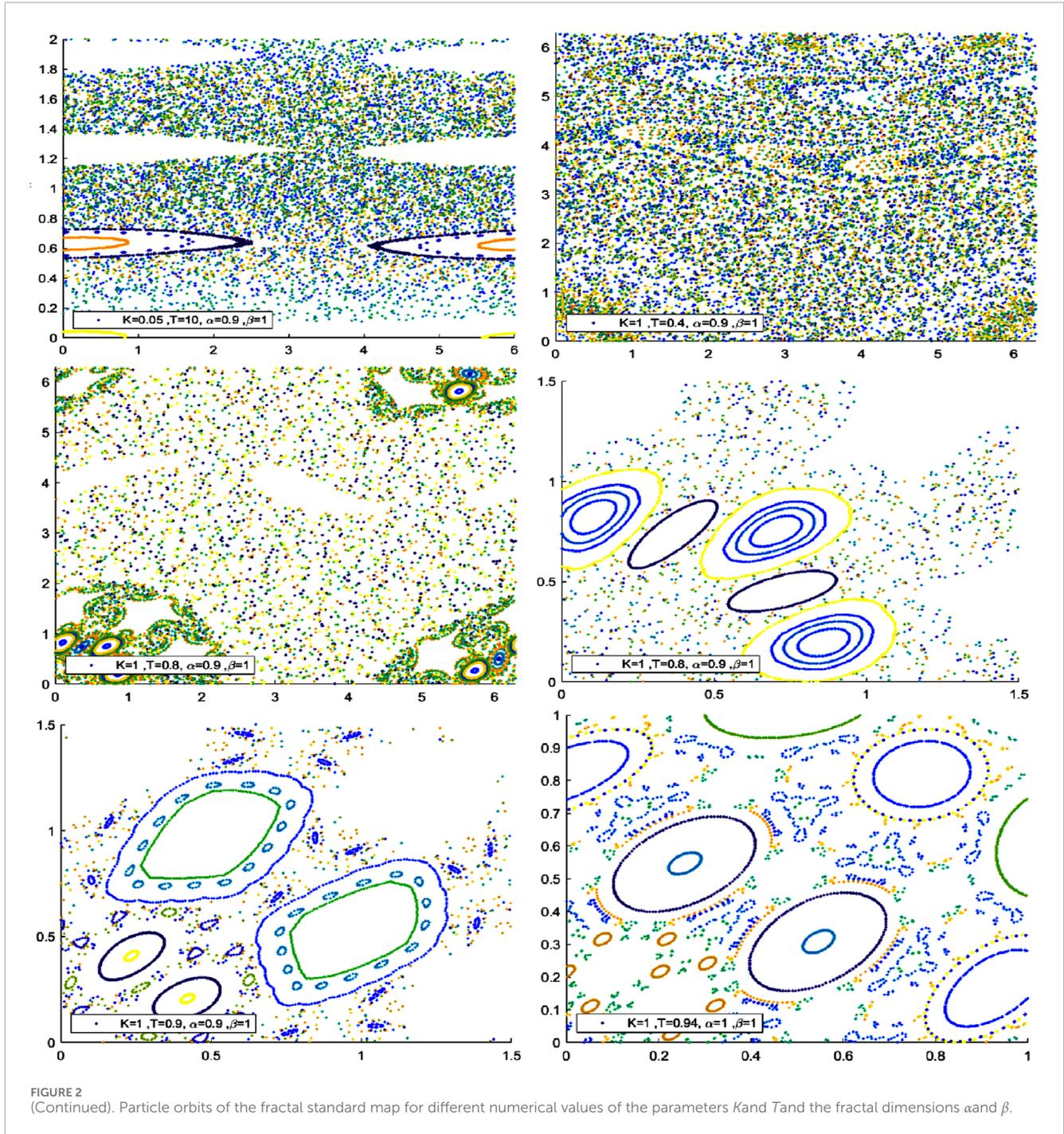


FIGURE 2 (Continued).

half degrees of freedom, and one way to study them is the stroboscopic map, which is a special case of a Poincaré map for driven systems [96]. It is considered in quantum-kicked top [97, 98]. Hamilton's equations of motion in fractal dimensions are

given by

$$\frac{1}{\beta} t^{1-\beta} \frac{dp}{dt} = -\frac{1}{\alpha} x^{1-\alpha} \frac{\partial H}{\partial x} = -\frac{1}{\alpha} x^{1-\alpha} t^\eta K T \sin x \sum_{n=-\infty}^{\infty} \delta(t-nT), \quad (13)$$



$$\frac{1}{\beta} t^{1-\beta} \frac{\partial x}{\partial t} = p. \tag{14}$$

The special case where $\eta = 1 - \beta$ is motivating since it does not lead to divergent series when performing the integration of Equation 13. To construct a map in fractal dimensions before the n^{th} -kick, we again introduce a small number $\varepsilon \ll 1$ such that

$$x_{n+1} = x(t_{n+1}) = \lim_{\varepsilon \rightarrow 0^+} x(T(n+1) - \varepsilon) \tag{15}$$

and

$$p_{n+1} = p(t_{n+1}) = \lim_{\varepsilon \rightarrow 0^+} p(T(n+1) - \varepsilon). \tag{16}$$

Here, $t_{n+1} = (n + 1)T$. Accordingly, we integrate Equations 13, 14 using Equations 15, 16 as follows:

$$\int_{t_n - \varepsilon}^{t_{n+1} - \varepsilon} \frac{\partial p}{\partial t} dt = \frac{KT\beta}{\alpha} x^{1-\alpha} \sin x \int_{t_n - \varepsilon}^{t_{n+1} - \varepsilon} t^{\beta-1+\eta} \sum_{n=1}^{\infty} \delta(t-nT) dt, \tag{17}$$

$$\int_{t_n - \varepsilon}^{t_{n+1} - \varepsilon} \frac{\partial x}{\partial t} dt = \beta \int_{t_n - \varepsilon}^{t_{n+1} - \varepsilon} t^{\beta-1} p dt. \tag{18}$$

Equations 17, 18 yield, in particular for $\eta = 1 - \beta$:

$$p_{n+1} = p_n - \frac{KT\beta}{\alpha} x_n^{1-\alpha} \sin x_n \equiv p_n + F_\alpha(x_n). \tag{19}$$

$$x_{n+1} = x_n + \beta(nT)^{\beta-1} T p_{n+1} \equiv x_n + G_\beta(p_{n+1}). \tag{20}$$

Observe that when $\alpha = \beta = 1$, Equations 19, 20 are reduced to the Chirikov–Taylor standard map. In addition, FSM differs from the fractional standard map obtained in [87, 88]. The stability of the fixed points is determined from the residue of the tangent map:

$$\begin{pmatrix} \Delta p_{n+1} \\ \Delta x_{n+1} \end{pmatrix} = \Delta M \begin{pmatrix} \Delta p_n \\ \Delta x_n \end{pmatrix}, \tag{21}$$

where

$$\Delta M = \begin{pmatrix} 1 & \frac{\partial F_\alpha(x_n)}{\partial x_n} \\ \frac{\partial G_\beta(p_{n+1})}{\partial p_n} & 1 + \frac{\partial F_\alpha(x_n)}{\partial x_n} \frac{\partial G_\beta(p_{n+1})}{\partial p_n} \end{pmatrix} \tag{22}$$

is the tangent map [39]. The stability of the system arises (using Equations 21, 22) if the residue given by

$$R = \frac{1}{2} - \frac{1}{4} \text{Tr}(\Delta M) = -\frac{1}{4} \frac{\partial F_\alpha(x_n)}{\partial x_n} \frac{\partial G_\beta(p_{n+1})}{\partial p_n} \tag{23}$$

is constrained by $0 < R < 1$, which yields at the fixed point $x_m = 2\pi m, m \in \mathbb{Z}, 0 < K < 4\alpha(2\pi m)^{1-\alpha}/T\beta$, and stability occurs, phase-space trajectories lie on invariant curves, and the variation in momentum based on Equation 23 is restricted. We examine particle motions in the phase space by plotting in Figure 2 the Poincaré sections, where the orbits may have different behaviors depending on the values of the parameters K and T and the fractal dimensions α and β .

We observe that all the parameters play an important role in the formation of islands around islands and that low fractal dimensions suppress the deterministic diffusion and lead to chaotic maps. KAM secondary islands corresponding to a certain resonance emerge in some particular cases. Trajectories demonstrate island chains connected with an assortment of elliptic periodic orbits. For small K and spatial fractal dimension α , chaotic behavior dominates larger phase space areas, i.e., a large area of the phase space is occupied by a single chaotic sea due to the large amount of non-integrability of the system. The fundamental reason for this behavior is related to destroying the stability islands. This leads to a decrease in the non-integrability of the fractal dynamical system. An increase in K and fractal dimensions shows regions of chaotic behavior rising around stable and unstable manifolds, besides the emergence of fractal patterns. These orbits are characterized by a dense collection of points with no obvious order. These chaotic orbits can have positive Lyapunov exponents but free from any kind of fractal structure. The stabilization of these orbits may be achieved in some particular cases due to the presence of parameters that may help control the chaotic behavior. There is a critical value of K and fractal dimensions from which the chaotic regions are no longer separated. For fractal dimensions close to unity, a central island with a chain of smaller islands around it is revealed, comparable to its larger-scale version. Additional successive amplifications would prove the fractal structure. It is notable that this fractal map

verifies the twist condition $\partial x_{n+1}/\partial p_n \neq 0$, which is the analog of the non-degeneracy condition from Hamiltonian systems for KAM’s theorem applicability to the map [99, 100].

To conclude, we have constructed maps for two different dynamical problems: the first one describes higher-order derivative dynamical systems, and the second one, the time-dependent δ -kicked rotor in fractal dimensions. The first problem is characterized, for particular values of K , by the emergence of spiral fractal patterns comparable to the Julia set, besides the emergence in some cases of strange chaotic orbits which are thickly interfaced with regular regions. On the contrary, the second problem, which is dominated by fractal dimensions, reveals the emergence of invariant curves, islands, and fractal and chaotic trajectories. The transition to chaos is shown by varying control parameters. Some of these parameters lead to chaos, and others lead to fractal patterns. The range of convergence and stability can be made to increase considerably. The difference between the fractal time-dependent δ -kicked rotor and the conventional one with the integer derivative is the emergence of various quasiperiodic and periodic windows, intermittency, and chaotic structures, which depend on the numerical values of fractal dimensions. The dynamic system displays a rich assortment of non-linear behaviors as fractal dimensions are varied. We observe the occurrence of chaotic regions exhibiting fractal features (islands around islands) in regions confined between the other types of trajectories. In several cases, KAM secondary islands corresponding to a certain resonance emerge. The second problem is, therefore, very sensitive to fractal dimensions. These new standard maps might be used to achieve better results to study quantum chaos. This work addresses challenges in incorporating Hamiltonian systems with higher-order derivatives and fractal derivatives into the analysis of complex systems that go beyond the standard map. It offers new tools and models to enhance our understanding of how higher-order dynamics and fractal patterns affect complex systems by providing additional accurate representations than traditional models. It will be of interest to apply these models to relativistic systems governed by higher-order derivatives and dissipation, and to time-dependent quantum Hamiltonian systems. In fact, the relativistic generalization of the Chirikov–Taylor standard map is based on various aspects, e.g., acceleration of the particle in an electric field [98, 100], dynamics of particles in magnetic relativistic field [101–103], and acceleration of charged particles in the electric field of an electromagnetic wave packet subject to temperature effects [104]. The emergence of chaos and fractal structures in relativistic systems is also considered motivating since these will support physicists and mathematicians to better understand several hidden properties arising in quantum and high energetic Hamiltonian chaos, besides their relevance in ergodic theory [105–107]. Additionally, it will be of interest to study the frequency property of Equation 1 using the one-step frequency formulation for non-linear oscillators introduced in [108], with an emphasis on odd non-linearity. Based on the outcomes of [108], we believe that this approach will offer several additional insights into the dynamics described by Equation 1, mainly related to the variations and effects of the frequency characteristics of the system for different parameter values and their correlations with chaotic and fractal behaviors. Work in these directions will be the aim of our future study.

Data availability statement

The raw data supporting the conclusions of this article will be made available by the authors, without undue reservation.

Author contributions

RE-N: conceptualization, investigation, methodology, software, and writing—original draft. WA: resources, validation, and writing—review and editing.

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