



Corrigendum: Foot Placement Characteristics and Plantar Pressure Distribution Patterns during Stepping on Ground in Neonates

F. Sylos-Labini^{1,2}, S. Magnani³, G. Cappellini^{1,2}, V. La Scaleia^{1,2}, A. Fabiano⁴, S. Picone⁴, P. Paolillo⁴, A. Di Paolo^{5,6}, F. Lacquaniti^{1,2,6} and Y. Ivanenko^{2*}

¹ Center of Space BioMedicine, University of Rome Tor Vergata, Rome, Italy, ² Neuromotor Physiology Laboratory, Fondazione Santa Lucia (IRCCS), Rome, Italy, ³ Department of Computer, Control and Management Engineering, Sapienza University of Rome, Rome, Italy, ⁴ Neonatology and Neonatal Intensive Care Unit, Casilino Hospital, Rome, Italy, ⁵ Neonatology and Neonatal Intensive Care Unit, Ospedale San Giovanni, Rome, Italy, ⁶ Department of Systems Medicine, University of Rome Tor Vergata, Rome, Italy

Keywords: neonates, stepping pattern, limb loading, foot pressures, kinematics, EMG activity, early development, human locomotion

A corrigendum on

Foot Placement Characteristics and Plantar Pressure Distribution Patterns during Stepping on Ground in Neonates

by Sylos-Labini, F., Magnani, S., Cappellini, G., La Scaleia, V., Fabiano, A., Picone, S., et al. (2017). *Front. Physiol.* 8:784. doi: 10.3389/fphys.2017.00784

OPEN ACCESS

Edited and reviewed by:

Leonardo Alexandre Peyré-Tartaruga,
Federal University of Rio Grande do
Sul (UFRGS), Brazil

*Correspondence:

Y. Ivanenko
y.ivanenko@hsantalucia.it

Specialty section:

This article was submitted to
Integrative Physiology,
a section of the journal
Frontiers in Physiology

Received: 31 October 2017

Accepted: 15 November 2017

Published: 27 November 2017

Citation:

Sylos-Labini F, Magnani S,
Cappellini G, La Scaleia V, Fabiano A,
Picone S, Paolillo P, Di Paolo A,
Lacquaniti F and Ivanenko Y (2017)
Corrigendum: Foot Placement
Characteristics and Plantar Pressure
Distribution Patterns during Stepping
on Ground in Neonates.
Front. Physiol. 8:973.
doi: 10.3389/fphys.2017.00973

In the original article, we neglected to include the specific section “**Acknowledgments**” in the article. We would like to add to the article:

ACKNOWLEDGMENTS

We thank Marika Cicchese, Nadia Dominici, Carlo Giannini, Vito Mondì and Tiziana Silei for help with some of the experiments.

In the original article, we neglected to include the funder (**Lazio Region**), grant (**INNOVA.1 FILAS - RU 2014_1033 - RIABILITA**). We ask you to add this missing funding to the Funding section:

“This work was supported by the Italian Ministry of Health (IRCCS Ricerca corrente), Italian Space Agency (contract n. I/006/06/0), Italian University Ministry (PRIN grant 2015HFWRY_002), Lazio Region (INNOVA.1 FILAS - RU 2014_1033 - RIABILITA), and Horizon 2020 Robotics Program (ICT-23-2014 under Grant Agreement 644727-CogIMon).”

The authors apologize for these errors and state that this does not change the scientific conclusions of the article in any way.

Conflict of Interest Statement: The authors declare that the research was conducted in the absence of any commercial or financial relationships that could be construed as a potential conflict of interest.

Copyright © 2017 Sylos-Labini, Magnani, Cappellini, La Scaleia, Fabiano, Picone, Paolillo, Di Paolo, Lacquaniti and Ivanenko. This is an open-access article distributed under the terms of the Creative Commons Attribution License (CC BY). The use, distribution or reproduction in other forums is permitted, provided the original author(s) or licensor are credited and that the original publication in this journal is cited, in accordance with accepted academic practice. No use, distribution or reproduction is permitted which does not comply with these terms.