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Reconstructing hyper-spectral downwelling irradiance from multi-spectral measurements

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Checking the radiometric calibration of satellite hyper-spectral sensors such as the PACE Ocean Color Instrument (OCI) while they operate in orbit and evaluating remote sensing reflectance, the basic variable from which a variety of optical and biogeochemical ocean properties can be derived, requires measuring upwelling radiance just above the surface (L_w) and downwelling planar irradiance reaching the surface (E_s). For this, the current HyperNav systems measure L_w at about 2 nm spectral resolution in the ultraviolet to near infrared, but E_s in only four 10 nm wide spectral bands centered on 412, 489, 555, and 705 nm. In this study, the E_s data acquired in these spectral bands in clear sky conditions are used to reconstruct via a multi-linear regression model the hyper-spectral E_s signal at 0.5 nm resolution from 315 to 900 nm, the OCI spectral range, allowing an estimate of E_s at the HyperNav, OCI, and other sensors' resolutions. After correction of gaseous absorption and normalization by the top-of-atmosphere incident solar flux, the atmospheric diffuse transmittance is expressed as a linear combination of E_s measured in those 4 spectral bands. Based on simulations for Sun zenith angles from 0 to 75° and a wide range of (i.e., expected) atmospheric, surface, and water conditions, the E_s spectrum is reconstructed with a bias of less than 0.4% in magnitude and an RMS error (RMSE) ranging from 0% to 2.5%, depending on wavelength. The largest errors occur in spectral regions with strong gaseous absorption. In the presence of typical noise on E_s measurements and uncertainties on the ancillary variables, the bias and RMSE become -2.5% and 7.0%, respectively. Using a General Additive Model with coefficients depending on Sun zenith angle and aerosol optical thickness at 550 nm improves statistical performance in the absence of noise, especially in the ultraviolet, but provides similar performance on noisy data, indicating more sensitivity to noise. Adding spectral bands in the ultraviolet, e.g., centered on 325, 340, and 380 nm, yields marginally more accurate results in the ultraviolet, due to uncertainties in the gaseous transmittance. Comparisons between the measured and reconstructed E_s spectra acquired by the MOBY spectroradiometer show agreement within predicted uncertainties, i.e., biases less than 2% in magnitude and RMS differences less than 5%. Reconstruction can also be achieved accurately with other sets of spectral bands and extended to cloudy conditions since cloud optical properties, like aerosol properties, tend to vary regularly with wavelength. These results indicate that it is sufficient, for many

scientific applications involving hyper-spectral E_s , to measure E_s in a few coarse spectral bands in the ultraviolet to near infrared and reconstruct the hyperspectral signal using the proposed multivariate linear modeling.

KEYWORDS

HyperNav, downwelling planar irradiance, multivariate regression, generalized additive model, ocean Color, MOBY, PACE

1 Introduction

Water-leaving radiance (L_w) and remote sensing reflectance (R_{rs} , or the ratio of L_w and downwelling planar irradiance reaching the air-water interface E_s), $R_{rs} = L_w/E_s$, are basic aquatic optical variables from which properties of the water body can be retrieved for a variety of scientific and societal applications (e.g., IOCCG, 2008; Frouin et al., 2019). System Vicarious Calibration (SVC), an important procedure to ensure that satellite L_w estimates meet requirements for biogeochemistry (Evans and Gordon, 1994; Gordon, 1997; IOCCG, 2013), necessitates measuring L_w accurately at the time of satellite overpass (Franz et al., 2007; Zibordi et al., 2015). Inversion schemes to retrieve inherent optical properties (IOPs) and biogeochemical characteristics of the water body require R_{rs} (or similar normalized L_w variables) as input (e.g., Werdell et al. (2018)). Measurements of R_{rs} are therefore essential to develop algorithms for inferring those properties/characteristics, and to evaluate their retrieval. Diverse instrumentation, installed on fixed platforms or deployed from ships, has been used to measure L_w and E_s (therefore R_{rs}) spectrally, and deployment/measurement protocols defined to provide best data quality with associated uncertainties (e.g., Mueller et al. (2003); Ruddick et al. (2019a) for L_w ; Ruddick et al. (2019b) for E_s).

For the upcoming PACE mission, which will carry into polar orbit the Ocean Color Instrument (OCI), the HyperNav spectroradiometer/float system (Barnard et al., 2024, this issue) was designed to measure L_w at about 2 nm resolution (full width at half maximum) from 250 to 900 nm. The system is also equipped with a commercial (SeaBird, Inc.) cosine sensor that measures E_s in 4 spectral bands about 10 nm wide centered on 412, 489, 555, and 705 nm. The E_s measurements do not allow direct normalization of L_w into R_{rs} over the entire spectral range and at the spectral resolution of the L_w measurements, but this is highly desirable for evaluating the PACE OCI hyper-spectral R_{rs} retrievals at 5 nm resolution. Accurate reconstruction of the E_s spectrum from measurements in a few coarse spectral bands is possible, however, because the solar irradiance reaching the surface is strongly correlated spectrally, even though gaseous absorption only modulates specific regions of the solar spectrum, which requires proper treatment.

In the following, a methodology is presented and evaluated to reconstruct E_s at 0.5 nm resolution from 315 to 900 nm (the OCI spectral range) in clear sky conditions from E_s measurements in 10 nm bands centered on 412, 489, 555, and 705 nm. The methodology is based on multi-linear regression and includes uncertainty estimation via Monte Carlo propagation (Section 2). Simulations for expected (realistic) atmospheric, surface, and aquatic conditions and Sun zenith angles are described in Section

3. Performance is evaluated theoretically in the absence and presence of noise in Section 4, as well as the merits of an additive varying coefficient model with aerosol optical thickness and Sun zenith angle as auxiliary variables. The methodology is checked experimentally on E_s spectral measurements collected at and near the MOBY site in Section 5. The applicability to other sets of spectral bands, and the advantage and drawback of including additional bands in the ultraviolet, is discussed in Section 6, as well as the ability to reproduce accurately E_s at the HyperNav and OCI spectral resolutions. The study is summarized in Section 7, with conclusions on the accuracy of the reconstruction and the possible extension to cloudy conditions since cloud properties, like aerosol properties, tend to vary smoothly with wavelength, and recommendations, in view of the applications, on the need for hyper-spectral E_s sensors instead of multi-band sensors.

2 Methodology

In clear atmosphere, the downwelling planar solar irradiance reaching ocean surface, E_s , can be modeled accurately as in Eq. 1 (e.g., Tanré et al., 1979):

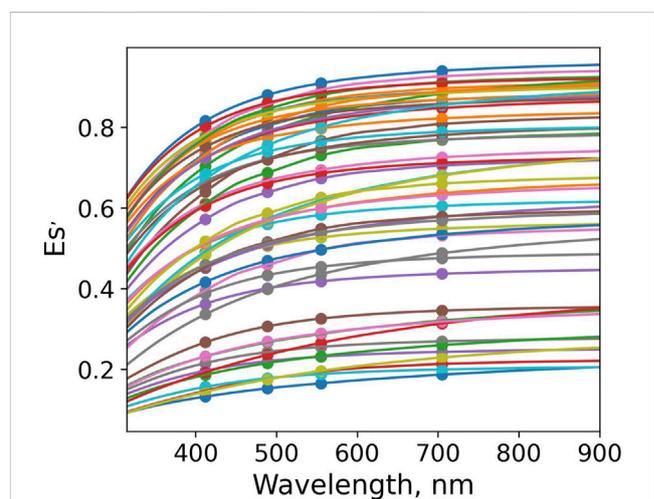


FIGURE 1
Es' of the 50 cases simulated using ARTDECO with parameters randomly selected, i.e., different aerosol models (maritime clean, continental, urban, desert), aerosol optical thickness at 550 nm from 0 to 0.8, aerosol scale height from 0.5 to 5 km, relative humidity from 60% to 90%, ozone amount from 250 to 450 Dobson, water vapor from 0.1 to 7 g cm⁻², surface pressure from 1,000 to 1,025 mb, solar zenith angle from 0° to 75°, wind speed from 5 to 15 m s⁻¹, and chlorophyll concentration from 0.3 to 30 mg m⁻³. Dots represent the Es' values at 412, 489, 555, and 705 nm.

$$E_s = E_0 \cos(\theta_s) T_g T_a / (1 - S_a A) \quad (1)$$

where E_0 is the extraterrestrial (top-of-atmosphere, TOA) solar irradiance corrected for Earth Sun distance, θ_s is the solar zenith angle, T_g and T_a denote the downward gaseous transmittance and total (direct plus diffuse) atmospheric transmittance, respectively, S_a is the spherical albedo of the atmosphere, and A is the surface albedo.

The hypothesis that it is feasible to reconstruct E_s at hyper-spectral resolution using measurements at only a few bands is based on the fact that E_s after the correction of gaseous absorption and normalization using the extraterrestrial solar irradiance, i.e., $E'_s = E_s / (E_0 T_g)$, essentially becomes $T_a \cos(\theta_s) / (1 - S_a A)$, which varies smoothly with wavelength (Figure 1). However, even though E'_s does not exhibit an irregular spectral dependence, its reconstruction via interpolation/extrapolation of measurements in a few bands may not be sufficiently accurate (see Section 4). Therefore, we tested two different models:

1. Multivariate linear model with constant coefficients (Eq. 2).

$$E'_s(\lambda) = a_0 + \sum_i a_i E'_s(\lambda_i) \quad (2)$$

where a_0 is a constant, λ represents wavelength, $E'_s(\lambda_i)$ and a_i are the E'_s and the corresponding linear coefficients at λ_i , the center wavelengths i of the 412, 489, 555, and 705 nm bands.

2. Generalized additive model (GAM; Hastie and Tibshirani, 1993) with coefficients as functions of geometric and/or geophysical parameters (Eq. 3).

$$E'_s(\lambda) = f_0(p_1, p_2, \dots, p_n) + \sum_i f_i(p_1, p_2, \dots, p_n) E'_s(\lambda_i) \quad (3)$$

where p_1, p_2, \dots, p_n represent the various geometric and/or geophysical parameters to be used, and f are functions of these variables. The parameters p are selected based on analysis of the data. The f functions constitute the free parameters of the model and will be estimated from the data. The shapes of f are largely unspecified in the fitting procedure, while the resulting number of degrees of freedom are controlled to avoid overfitting. This is achieved via penalized smoothing splines.

Once E'_s is retrieved, E_s can be derived from E'_s since E_0 is known and T_g can be accurately estimated (see Section 4). Uncertainties of the two methods are quantified by introducing noise to the input E_s at the four wavelengths, together with assigning noise to T_g , which will then be propagated to estimate the uncertainties in reconstructed E_s using the Monte-Carlo method (e.g., JCGM, 2008; Bialek et al., 2020). This requires the probability distribution functions for the input components in the model equation (content of gaseous absorbers in the multilinear model with constant coefficients and, additionally, the auxiliary variables in the additive varying coefficient model), from which many random realizations are selected in the calculation of the output, providing the uncertainty of the output value.

The reconstruction of E_s described above is accomplished with respect to the extraterrestrial solar spectrum E_0 used in the radiative transfer (RT) model. One has to be aware of this in calibration/validation activities and make sure that the same E_0 is used. Using a

different E_0 , however, does not require re-determining the coefficients of the E'_s model (Eq. 2).

3 Simulations

Radiative transfer simulations were performed from 315 to 900 nm at 0.5 nm resolution with the Atmospheric Radiative Transfer Database for Earth Climate Observation (ARTDECO) code (Dubuisson et al., 2016) for a variety of geometric and geophysical conditions. The ARTDECO radiative transfer model accounts for scattering and absorption by air molecules, aerosols, and cloud droplets, and interactions between scattering and absorption. The radiative transfer equation is solved using the discrete ordinate method. The atmosphere is assumed plane-parallel and positioned above a wavy air-sea interface. In the code, the high-resolution extraterrestrial solar spectrum is from Chance and Kurucz (2010), mean Earth-Sun distance is used, and gaseous absorption is accounted for by applying the correlated-k technique (Lacis and Oinas, 1991) with appropriate k-distribution coefficients. The optical properties of aerosols and clouds are selected from the Optical Properties of Aerosols and Clouds (OPAC) database (Hess et al., 1998). The vertical distribution of the scatterers and absorbers can be specified. The bidirectional reflectance of the wavy interface is modeled based on Fresnel equations and the Cox-Munk wind-dependent wave slope probability density distribution. The diffuse water reflectance (Case 1 waters only) is assumed Lambertian and modeled as a function of chlorophyll concentration according to Morel and Maritorena (2001). This model, limited to the visible, was extended to 300 nm using Hydrolight (Hedley and Mobley, 2019) inherent optical properties. The water body is considered black at wavelengths longer than 700 nm. This treatment is sufficient because the impact of photons leaving the water that are backscattered by the atmosphere to the surface is relatively small.

The total downwelling solar irradiance arriving at the ocean surface E_s was simulated from 315 to 900 nm with a 0.5 nm resolution for a clear atmosphere (i.e., no clouds). The corresponding extraterrestrial solar irradiance E_0 was also output in the simulations. In the code, the AFGL US standard atmosphere profile (Anderson et al., 1986) was used and adapted to the input concentrations of gases, i.e., ozone, water vapor, and oxygen. Note that by explicitly varying the oxygen amount the absorption from other gases including CH_4 , CO_2 , and N_2O was considered since the molar fraction of these gases are fixed with respect to oxygen in the ARTDECO code. Since absorption from NO_2 was not modeled in ARTDECO, transmittance of NO_2 was estimated based on Schneider et al. (1987) and applied to the simulated E_s . In this study, the following three different datasets were generated.

1. Dataset for calibrating the models for E_s reconstruction, referred as the calibration dataset.

In this dataset, four different aerosol models from the OPAC database were considered, i.e., maritime clean, continental clean, urban, and desert, including both absorbing and non-absorbing aerosols. The computations were conducted for total aerosol optical thickness values (AOT550) ranging from 0 to 0.8 at 550 nm. The

aerosol concentration was set to decrease with altitude according to an exponential law with a typical scale height (SH) from 0.5 to 5 km. The relative humidity (RH) in the atmosphere was set to randomly vary from 60% to 90%. The amount of ozone (U_{o3}) and water vapor (U_{h2o}) were from 250 to 450 Dobson and from 0.1 to 7 g cm⁻², respectively. The oxygen amount is defined using surface pressure (PS), which was varied from 1,000 to 1,025 mb. Simulations were carried out for Sun zenith angles (SZAs) ranging from 0° to 75° (view zenith and relative azimuth were fixed as 0° and 90°, since they do not affect E_s). The wind speed (U) was set to vary from 5 to 15 m s⁻¹. The optical properties of the diffuse boundary marine reflectance were specified for chlorophyll concentration (Chl) varying from 0.03 to 30 mg m⁻³. A total of 10,000 simulations were performed, with aerosol types, aerosol optical thickness, scale height, humidity, ozone, surface pressure, water vapor, Sun zenith angle, wind speed, chlorophyll concentration randomly varied in the ranges described above. For each simulation with gaseous absorption, the case of no gaseous absorption was also generated to obtain E_{s0} , i.e., E_s after correction of gaseous absorption ($E_s = E_{s0} T_g$).

2. Dataset for developing the Look-Up Table (LUT) of T_g , referred as the LUT dataset.

In this dataset, the ranges of different geometric and geophysical parameters are the same as those in the calibration dataset. What is different is that the input amount of ozone, water vapor and oxygen as well as Sun zenith angles were set to be discrete values as below.

- SZA (degree): 0, 10, 20, 30, 40, 50, 60, 65, 70, and 75
- U_{o3} (Dobson): 250, 300, 350, 400, 450
- U_{h2o} (g cm⁻²): 0.1, 0.2, 0.3, 0.4, 0.5, 0.6, 0.7, 0.8, 0.9, 1, 2, 3, 4, 5, 6, 7
- PS (mb): 1,000, 1,005, 1,010, 1,015, 1,020, 1,025

Both simulations with and without gaseous absorption were made. The aerosol properties and surface conditions have a small impact on T_g , except in strong water vapor absorption bands, where the coupling between aerosol scattering and water vapor absorption becomes effective, but such bands occur above 900 nm. Therefore these parameters were fixed for each simulation, i.e., AOT550 = 0.1, RH = 90%, SH = 2 km, maritime aerosol, U = 5 m/s, and Chl = 0.1 mg/m³. The LUT has four axes, i.e., Sun zenith angle, ozone and water vapor amounts, and pressure.

3. Dataset for validating the models for E_s reconstruction, referred as the validation dataset.

Instead of using the four different OPAC aerosols, this dataset uses mixed aerosols, i.e., all aerosol species were mixed up for each simulation. The aerosol species include black carbon (OPAC urban), dust (OPAC Desert), organic carbon (OPAC continental), and sea salt (OPAC maritime). Global hourly MERRA-2 reanalysis data (Gelaro et al., 2017) for the entire year 2006 were acquired to extract the optical thickness corresponding to each aerosol species, which were then randomly selected (covering global ocean) and input to ARTDECO. Other parameters were set in the same predefined

ranges as in the calibration dataset but with totally different values. There are 10,000 simulations with gaseous absorption and another 10,000 without gaseous absorption. Noise was also added to this dataset to evaluate the sensitivity of the models to noise, of which the details are described in Section 4.

For the calibration and validation datasets, the E_s and E_{s0} simulations at 0.5 nm resolution were further processed into the values in the 412, 488, 555, and 705 nm bands by using the average within ±5 nm of the center wavelengths (the exact spectral response of the bands was unknown).

4 Theoretical results

The LUT developed in Section 3 was used to estimate T_g for the 10,000 cases in the calibration dataset and another 10,000 cases in the validation dataset using the prescribed solar zenith angle, ozone, amount, surface pressure, and water vapor amount as input and linearly interpolating within the LUT. Figure 2 shows that the LUT method produces accurate estimation of T_g , with the bias ranging from -0.6% to 0.3% and from -2.5% to 0.4% and RMS error (RMSE) within 2.5% and within 3%, for the calibration and validation dataset, respectively. The bias and RMSE for the calibration and validation dataset are different because the input parameters to the LUT are not exactly the same. Remember that -2.5% bias is equivalent a bias of -0.004, which is very small. As expected, degradation of accuracy is found at the wavelengths with gaseous absorption, for example, the ultra-violet (UV) and 500–700 nm with ozone absorption, ~688 nm and ~760 nm with strong oxygen absorption, and near-infrared with water vapor absorption, while at the wavelengths almost without gaseous absorption the bias and RMS error are close to 0. This is with the assumption that the amount of ozone, surface pressure, and water vapor are perfectly known. In practice, noise in these quantities will introduce uncertainties in the estimated T_g and the impact on the E_s reconstruction is investigated, as described in the text below.

E'_s at 0.5 nm resolution from 315 nm to 900 nm can be accurately reconstructed using the values at 412, 489, 555, and 705 nm using multivariate linear regression (Figure 3). The a_0 and a_i coefficients in Eq. 2, are irregular spectrally (Figure 4), an indication that simple interpolation/extrapolation would not capture spectral E'_s variability as well as the multilinear model. Bias is 0 for all the wavelengths, which is not surprising because the model is supposed to be unbiased. The RMSE is less than 0.1% starting from 400 nm and increases to 0.6% in the UV wavelengths. The relatively high error in the UV is probably due to the fact that the input four wavelengths are from 400 to 700 nm, which may fail to properly capture some of the spectral characteristics at the UV. The E_s spectra were computed using E_0 and the estimated T_g . The bias, ranging from -0.2% to 0.4%, and RMSE, from 0% to 2.5%, are basically the total of T_g and E'_s errors, although some compensation occurs so that the values are slightly lower.

The prescribed E'_s was further modeled as a function of all other variables, including the estimated E'_s ($E'_{s,est}$), SZA, AOT550, SH, aerosol model (A), Chl, U, RH, and PS, following the procedure of Bisson et al. (2021) using a Bayesian approach to multivariate

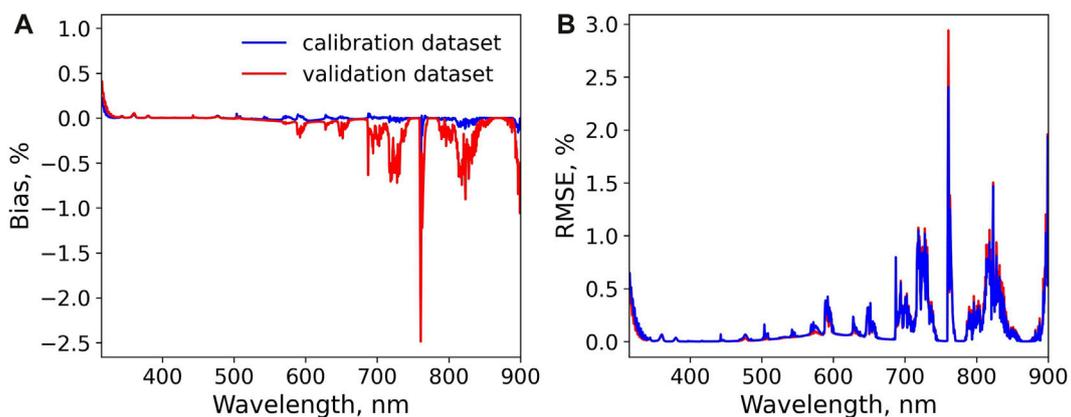


FIGURE 2 Percent bias (A) and RMSE (B) of T_g estimation using the calibration (blue) and validation (red) dataset.

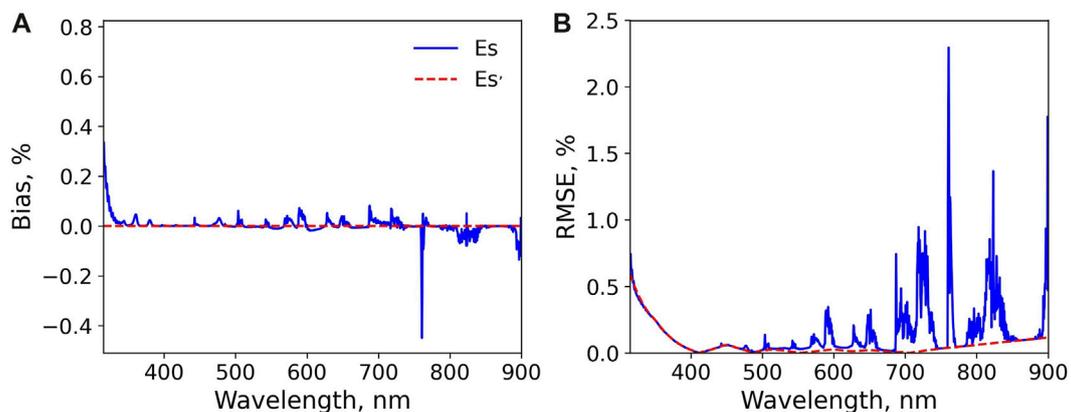


FIGURE 3 Percent bias (A) and RMSE (B) of E_s' (red dashed) and E_s (blue solid) estimation using the calibration dataset and multivariate linear regression.

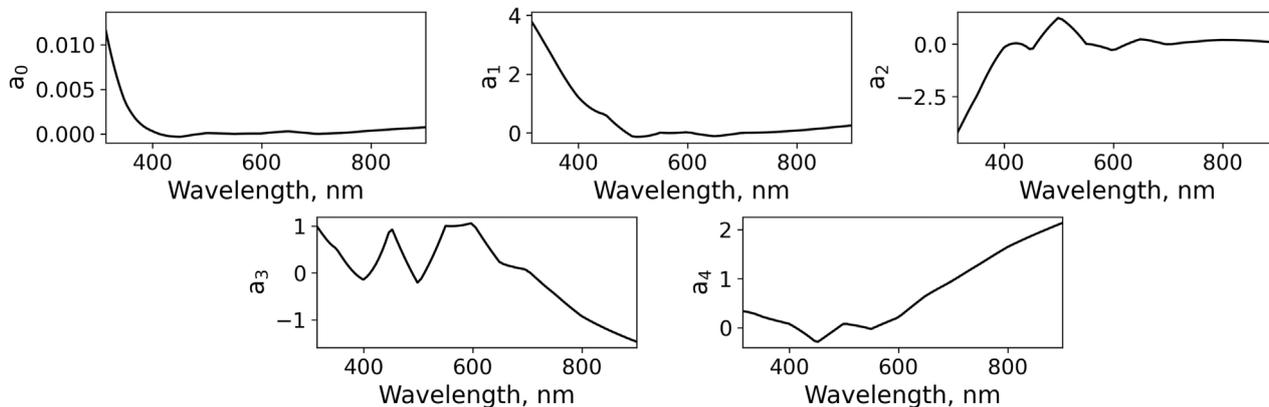
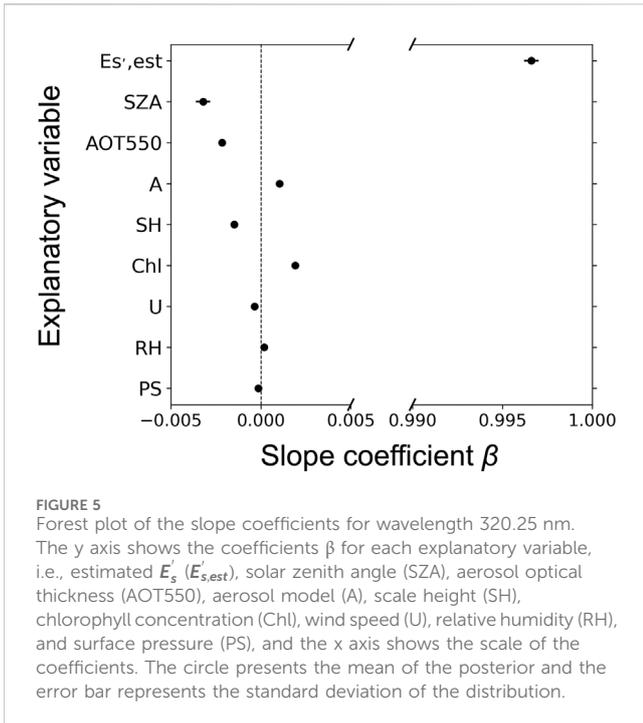


FIGURE 4 Coefficients of the multilinear model (see Eq. 2).



regression analysis. U_{o3} and U_{h2o} were not included because E'_s is the quantity after gaseous absorption. The regression model is assumed to follow a normal distribution with the mean μ modeled as in Eq. 4

$$\mu = \beta_0 E'_{s,est} + \beta_1 SZA + \beta_2 AOT550 + \beta_3 SH + \beta_4 A + \beta_5 Chl + \beta_6 U + \beta_7 RH + \beta_8 PS + \alpha \tag{4}$$

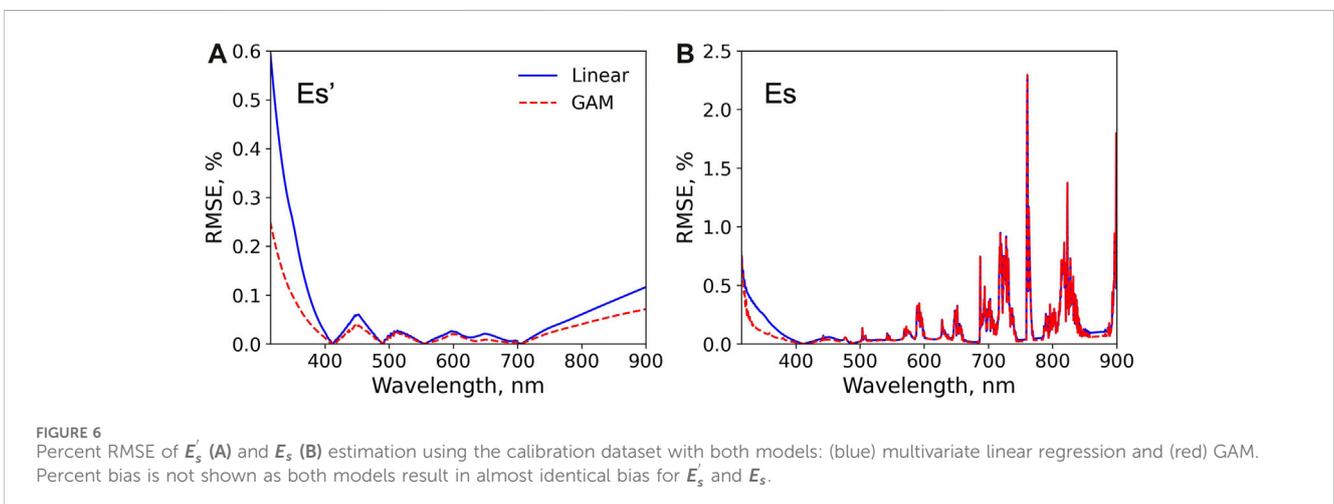
Each variable was standardized by subtracting the mean and dividing by the standard deviation to shift the distribution to have a mean of zero and a standard deviation of one. By doing so, the intercept bias α essentially becomes zero and the slope coefficients β_i illustrate a one-to-one correspondence between the dependent and independent variables. In the model, the prior distribution of β_i is assumed weakly

informative, with mean of zero and a standard deviation of 100. For example, at 320.25 nm, the slope coefficient β_0 is very close to 1, i.e., ~ 0.997 (Figure 5), indicating strong correspondence between E'_s and $E'_{s,est}$. The β for other variables all deviate from 0, although the deviations are small, indicating their contribution to residual errors. Based on the magnitude of the β values, the three variables with the highest absolute values are SZA, AOT550, and Chl. Large percent errors are typically found to be associated with small E'_s , which is not easy to model accurately. When SZA is large, it means longer travelling path and more interactions of the light with aerosols and molecules in the atmosphere. The larger AOT550, the more aerosol scattering and absorption, depending on the aerosol types. Both variables lead to small E'_s and may explain their relatively large contributions in the residual errors. The variations in chlorophyll concentration affect the ocean surface albedo. In the UV, when chlorophyll concentration is small, the ocean surface albedo becomes relatively large and the spherical albedo of the atmosphere is increased, hence the surface impact introduced by the term $1/(1 - S_a A)$ may cause perturbations in E'_s and inaccuracy in the modeling.

The variables SZA, AOT550, aerosol type, SH, Chl, U, RH, and PS were then tested in the GAM model. These variables were introduced one by one and only those that brought in significant model improvement were selected, i.e., SZA and AOT550 in this study. The GAM model therefore becomes Eq. 5:

$$E'_s(\lambda) = f_0(SZA, AOT550) + \sum_i f_i(SZA, AOT550) E'_s(\lambda_i) \tag{5}$$

With the coefficients as a function of SZA and AOT550 instead of assumed constant, the accuracy of E'_s reconstruction is improved (Figure 6). The bias is not discussed here because both models are unbiased. The change of percent RMSE with wavelength shows a pattern similar to that obtained using multivariate linear regression, i.e., the closer the wavelength is to one of the input four bands the smaller the RMSE. Overall, the magnitude is lower for GAM as opposed to the linear model, especially in the wavelengths shorter than 400 nm and those longer than 700 nm. For example, the error drops from 0.6% to 0.2% in the UV and from 0.1% to 0.06% at 900 nm. An even stronger decrease of RMSE in the UV and from 850 to 900 nm is observed for the E_s reconstruction when using GAM. The terms of the five components (i.e., the functions $f_0, f_1, f_2,$



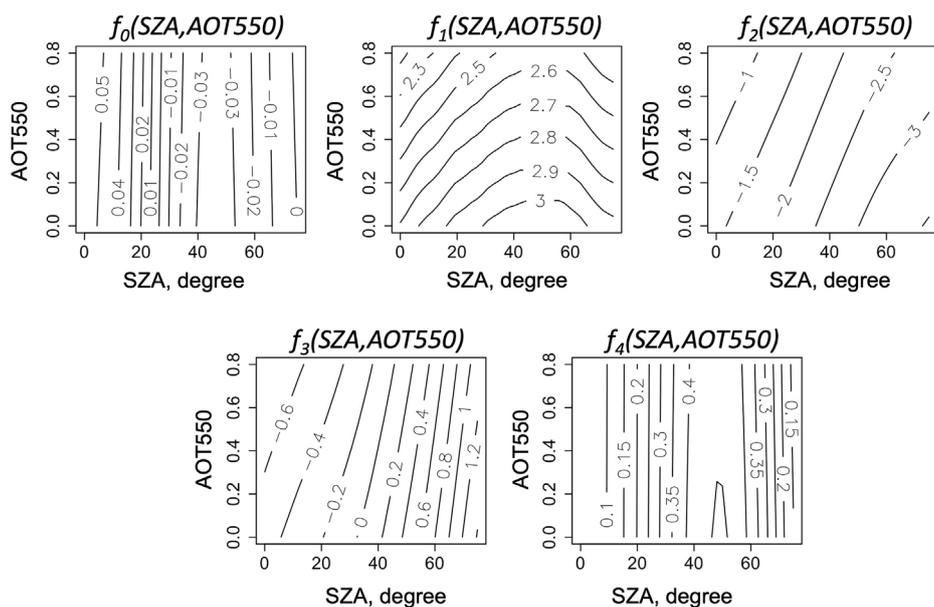


FIGURE 7
The five component smooth functions (f_0 , f_1 , f_2 , f_3 , and f_4) of the GAM model fitted on the calibration data at 320.25 nm.

f_3 and f_4) of the GAM model at 320.25 nm and 410.25 nm are displayed in Figures 7, 8, respectively. It is thus clear that the intercept as well as the coefficients for E'_s at the four wavelengths are not constant and the contours show how the values of f_i change with SZA and AOT550. The gradients of the component smooth functions f_i at 410.25 nm are much smaller than those at 310.25 nm, which is expected as the residual errors in E'_s attributed to SZA and AOT550 are more pronounced in the UV. At 320.25 nm the gradient of each f_i changes with SZA, while the impact AOT550 is more obvious on f_1 , f_2 , and f_3 and becomes less important for f_0 and f_4 . This is the same with 410.25 nm, i.e., the changes in f_i with respect to AOT550 decrease with wavelength, probably due to that aerosol scattering is stronger at shorter than longer wavelengths. Although the impact of AOT550 may be small and negligible depending on the smooth functions and the wavelength, AOT550 is kept in the GAM model so that we do not need to optimize the model for each wavelength, which is out of the scope of this study.

Performance of both models in reconstructing E'_s and E_s with the validation dataset are very similar to those with the calibration dataset (Figure 9). For E'_s reconstruction, the percent bias is from -0.15% to 0.03% for the multivariate linear model and from -0.01% to 0.02% for the GAM model, and the percent RMSE from 0% to 0.55% and from 0% to 0.15% , respectively. The bias and RMSE of E_s are higher than those with the calibration dataset (Figure 2), from -2.5% to -0.5% and from 0% to 3% , respectively, mainly attributed to the errors in T_g estimation (Figure 2). Figure 10 shows that simply using interpolation/extrapolation to reconstruct the hyperspectral E'_s from only four values typically yield much larger errors when compared to the multivariate linear model and GAM, especially in the ultraviolet wavelengths and at high Sun zenith angles.

In practice the *in-situ* measurements may be biased due to instrument calibration uncertainty and other uncertainties, (e.g., data

processing). It is important to check the *in-situ* dataset against radiative transfer calculations before performing the spectral reconstruction, which can be accomplished by comparing measurements and modeled values in ideal conditions, i.e., very clear atmosphere with low aerosol content. Assuming such check has been performed and environmental uncertainty is negligible, the remaining noise, i.e., which defines the E_s calibration uncertainty, is about $\pm 1\%$, according to Bialek et al. (2020) for an ideal case with no bias.

This noise was added to E_s in the validation dataset based on Eq.6 displayed below,

$$E_{s, \text{noisy}} = E_s (1 + e) \quad (6)$$

where e is a gaussian distributed variable with standard deviation of 0.01. Note that there are other sources of uncertainty in the E_s , such as that caused by converting the 0.5 nm simulated E_s to multispectral values, but here only the calibration error e is considered. In addition, noise was added to U_o3, U_h2o, and PS, i.e., ± 10 Dobson, $\pm 20\%$, and ± 5 mb, respectively, to account for the uncertainty in the MERRA-2 data. No uncertainty in E_o and in the radiative transfer modeling was considered. The Monte Carlo approach described in JCGM (2008) was used to quantify the final uncertainties in the reconstructed E_s . A total of 100 hyperspectral E_s were reconstructed with random realizations of noise specified above and the bias and RMSE were calculated against the prescribed values.

When using the multivariate linear model on the noisy data, the percent bias and RMSE in E'_s could reach 0.3% and about 2.0% , respectively (Figure 11), which generally increase in the UV and near infrared and decrease (i.e., less than 0.1% and 0.5% , respectively) in the visible. The errors in E_s are larger, with the largest bias and RMSE being -2.5% and 7.0% respectively. Relatively large errors are typically found in the spectral region of the gaseous absorption bands and at UV wavelengths. The GAM model produces very similar level of

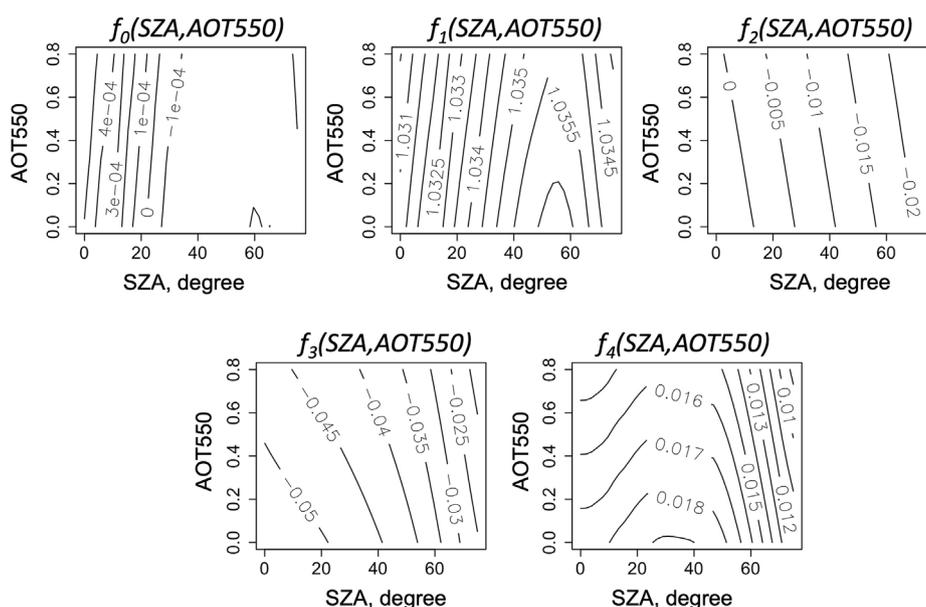


FIGURE 8
Same as Figure 7, but for 410.25 nm.

bias and RMSE in the E'_s estimation. Considering that the GAM model is more accurate than the multivariate linear model, especially in the UV, as well as that the uncertainty of GAM estimated E'_s was calculated assuming AOT550 is perfectly known, the results suggest that the GAM model is slightly more sensitive to noise, as the bias and RMSE between the two models become closer after introducing noise. In fact, the bias and RMSE for E_s are very similar for both models and much larger than those for E'_s , indicating the large impact from the noise in T_g .

5 Evaluation against *in situ* measurements

The performance of E_s reconstruction when applied to *in-situ* measurements was evaluated. Only the multivariate linear model was used since it is sufficiently accurate and slightly less sensitive to noise. In this study, two different *in-situ* datasets were used. The first one is the MOBY dataset, which has been collected off Lanai, Hawaii since 1997 (Clark et al., 1997; Clark et al., 2002) and used for vicarious calibration of many NASA, NOAA, and international satellite programs. MOBY is a spar buoy tethered to a slack-line moored buoy and has 3 underwater arms fixed at approximately 1, 5, and 9 m to take measurements of upwelling radiance and downwelling irradiance. Above-water downwelling irradiance is also measured using the E_s sensor mounted on top of the buoy, which is about 2.5 m above the surface float. For more details see Clark et al., 1997; Clark et al., 2002. The MOBY E_s data is hyperspectral and sampled every 0.8 nm from 344 nm to 750 nm, with the spectral resolution of approximately 0.9 nm for the blue

(<620 nm) and 1.2 nm for the red (>620 nm). The data is publicly available at https://www.star.nesdis.noaa.gov/socd/moby/filtered_spec/. October 2016 reprocessing was applied. Note that the E_s data below 380 nm is affected by stray light in the spectrometer (Feinholz et al., 2009). Only the data flagged as good were used in this study and there are a total of 7,036 data files available. In each data file, three columns of E_s are provided, to match the measurements taken at the three underwater arms. The three E_s values are very similar since they were taken in a short time period and only E_s corresponding to the times of measurements by the middle arm were used. These MOBY data were checked against ARTDECO simulations made using MERRA-2 data corresponding to the MOBY observation time and a minor wavelength shift, i.e., 0.3 nm toward short wavelengths, was noticed. Since the MOBY data are very close to the ARTDECO simulations (i.e., within uncertainties in the modeling), no bias adjustment was made, but the wavelength shift was corrected for each measurement.

Figure 12 displays one example of the reconstructed MOBY E_s on 27 May 2017. The measured and reconstructed E_s are in very good agreement with the relative percent difference mostly within 10% over the entire wavelength range and less than 5% above 450 nm. The reconstruction at the UV wavelengths is noisier, attributed to the model noise and the stray light issue of the MOBY E_s sensor. The relative error is also higher in the gaseous absorption bands. Uncertainties of the reconstructed E_s were calculated by introducing the typical uncertainties in MOBY E_s , i.e., approximately $\pm 1.5\%$ for the laboratory and $\pm 3.0\%$ for the field (Voss et al., 2015), ± 10 Dobson for U_o3, $\pm 20\%$ for U_h2o, ± 5 mb for PS, as well as the model noise shown in Figure 3 (blue line, right panel). After that, 100 random realizations were generated, and the final uncertainty, i.e., the

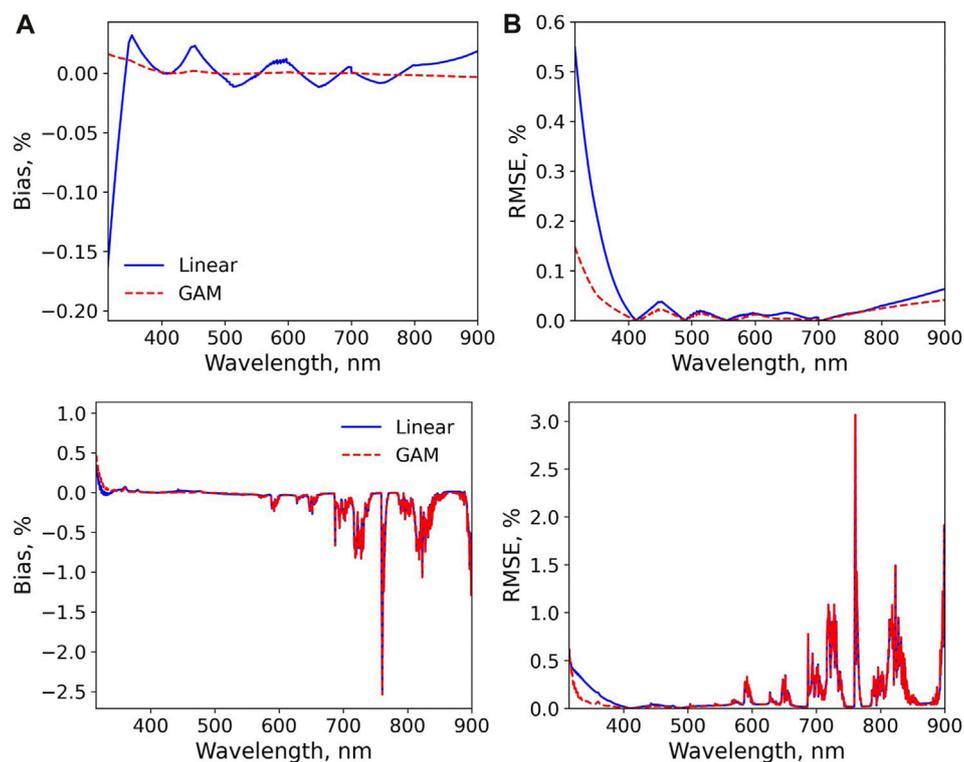


FIGURE 9 Percent bias and RMSE in the reconstructed of E'_s (A) and E_s (B) using the multivariate linear model (blue) and GAM (red) with the validation data set.

standard deviation of E_s with noise, was calculated using all realizations. The measured values are generally within the uncertainties of the reconstructed E_s (Figure 13). For all the 7,036 cases, the reconstructed E_s are in very good agreement with the measured values, with the bias less than 2% and RMSE less than 5% (Figure 14). The bias and RMSE at wavelengths affected by gaseous absorption are larger. For example, at 688 nm and 720 nm, corresponding to oxygen and water vapor absorption, the corresponding bias and RMSE are 2.2% and 3.6%, and -4.2% and 6.3%, respectively. Such uncertainties are higher than those obtained using the theoretical data (Figure 11, bottom panel), which may be due to noise that are not accounted for when evaluating the model performance using the theoretical data.

The second E_s dataset used for evaluation was acquired with a Sea-Bird Scientific HyperOCR radiometer from June 10 to 16 June 2021 within sight of the MOBY buoy in Hawaii ($20^\circ 49' 54.582''$ N, $157^\circ 11' 19.062''$ W). The measurements were made from the top of a 30 feet fishing vessel with an unobstructed view of the sky between 10:00 and 14:00 local time. The HyperOCR radiometer was calibrated by Sea-Bird Scientific with an FEL lamp pre and post deployment. The HyperOCR E_s ranges from 349 to 801 nm and is sampled every 3 nm, with a spectral resolution of 10 nm. Only the data collected during clear sky conditions were used, which resulted in only one measurement on 16 June 2021. A check with ARTDECO code corresponding to the field observation time and conditions (obtained from MERRA-2 data) suggested that the HyperOCR E_s

values are biased, with the difference up to about $20 \mu\text{W}/\text{cm}^2/\text{nm}$ (Figure 15). After adjusting the E_s at the four wavelengths to the simulated values, the reconstruction was performed, with the uncertainties quantified in the same way as for the MOBY data. The measured values are mostly outside the uncertainty of the reconstructed E_s , confirming the possible bias existing in the measurements. The relative errors between the reconstructed and simulated E_s using the 4 spectral bands are within 5% from 380 to 800 nm and go up to $\sim 9\%$ at 350 nm. It is within expectation that the relative differences between the reconstructed and measured 10-nm resolved HyperOCR E_s are lower than those with MOBY data, which has approximately 1 nm resolution.

6 Discussion

As demonstrated in the previous sections, both the multivariate linear and GAM models are capable of accurately reconstructing E_s at 0.5 nm from four 10 nm wide spectral bands centered on 412, 489, 555, and 705 nm. The multivariate linear model is straightforward, easy to interpret, and well suited for the problem in this study, i.e., E_s , after normalization of the incoming TOA solar irradiance and correction of gaseous absorption, exhibits a smooth wavelength-dependent behavior. Conversely, the GAM model is more sophisticated and has advantages in complex nonlinear relationships. By varying the coefficients as

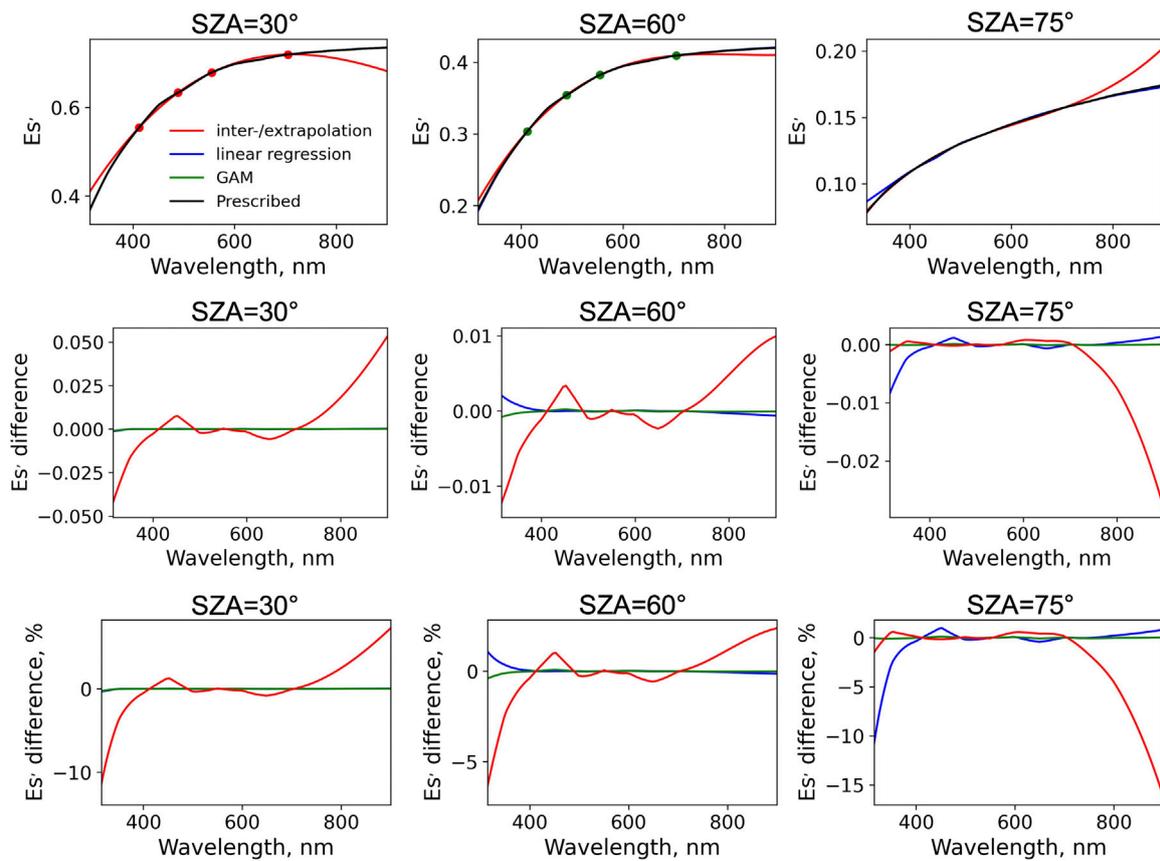


FIGURE 10 Comparison of the reconstructed E'_s using interpolation/extrapolation, multivariate linear model, and GAM for three cases in the calibration dataset with solar zenith angle (SZA) of 30°, 60°, and 75°. E'_s difference is defined as the prescribed minus the reconstructed value.

functions of SZA and AOT550 in the GAM, the accuracy in reconstructing E_s is slightly improved. This is consistent with the analysis of the correspondence between E'_s and different variables (Figure 5). This analysis suggests that only small residual errors exist between the E'_s and $E'_{s,est}$, which indicates that the relation between the E'_s to be reconstructed and the E'_s at the four 10-nm bands is almost linear, and such residual errors can be explained by parameters including SZA and AOT550, the two parameters with the highest β compared to other geophysical parameters. Moreover, it is worth noting that the GAM model is more sensitive to noise. As a result, it is concluded that multivariate linear model is a more suitable choice in this study in terms of model accuracy and sensitivity.

Instead of just utilizing the four multi-spectral bands at 412, 489, 555, and 705 nm, it is also possible to use other sets of wavelengths. For example, if we incorporate three additional wavelengths at UV, i.e., 325, 340, and 380 nm, the optional wavelengths that can be customized to the commercial Sea-Bird, Inc. OCR multi-spectral (7-band) radiometer, the RMSE of E'_s at UV exhibits significant reduction, with the maximum dropped from 0.6% to 0.02% and mostly remaining below 0.01% (Figure 16). The errors at other wavelengths also decrease to a certain extent, but not as much as in the UV. One may also be tempted to add more bands in the near infrared so that the RMSE

can be further reduced in this range. However, one needs to have in mind that the major uncertainty comes from the estimation of T_g .

In the evaluation of the model sensitivity to noise, it is found that the instrument calibration noise is the major contributor to the uncertainties in E'_s . For example, at 320.25 nm, with no noise the percent bias and RMSE in E'_s are -0.01% and 0.50% , respectively; the percent RMSE increases to 1.82% if added noise and the percent bias remains the same. The noise in the input PS, U_o3, and U_h2o affect the estimation of T_g , and this is another important source of uncertainties in the final restitution of E_s , especially at wavelengths affected by gaseous absorption. When T_g noise is included, the percent RMS of E_s increases from 1.86% to 1.94% at 320.25 nm, but changes from 2.78% to 3.60% in the oxygen band near 760 nm. To ensure accurate E_s reconstruction, it should be verified that the input multispectral E_s is not biased, for example by checking against radiative transfer simulations during very clear sky conditions (i.e., with small aerosol content), as indicated in Section 2. If the input E_s is biased, one may expect that the reconstructed E_s will be biased and the uncertainties could be large.

Since the presented method is capable of accurately reconstructing E_s at 0.5 nm resolution, it can be easily adapted to different sensors with varying spectral characteristics. One

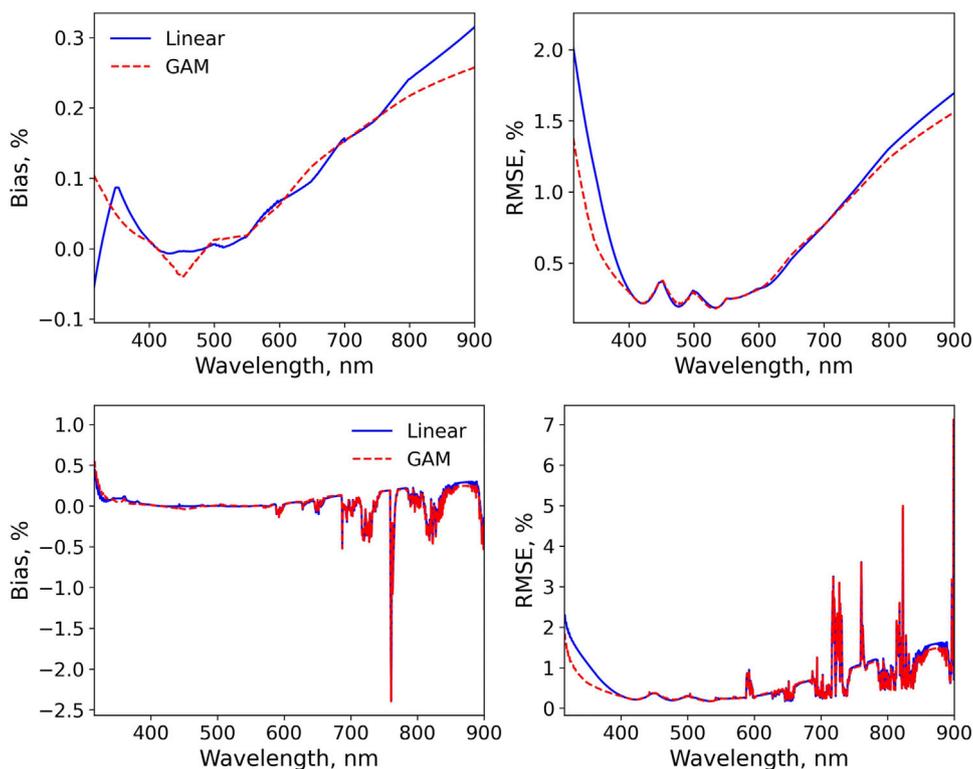


FIGURE 11 Same as Figure 9, but with noise added to E_s in the validation dataset and typical noise added to U_{h2o} , U_{o3} , and PS in T_g estimation. See text for more details.

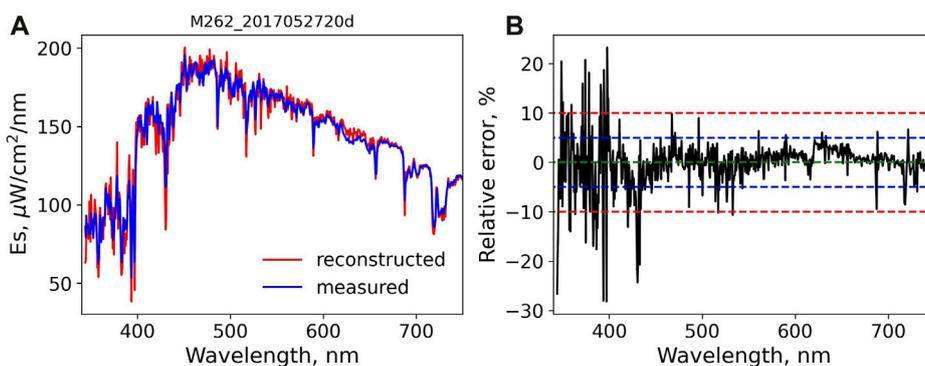


FIGURE 12 (A) Measured and reconstructed MOBY E_s on 27 May 2017, and (B) percent relative error between the measured and reconstructed E_s . Green, blue, and red dashed lines correspond to 0, 5, and 10% errors, respectively.

potential and important use in the context of the upcoming PACE mission (scheduled to be launched in February 2024) is reconstructing the OCI hyper-spectral E_s signal using measurements in the four multi-spectral measurements of the current HyperNav system. Figure 17 illustrates an example of reconstructed E_s at OCI wavelengths using simulated HyperNav E_s measurements for a clear day. Results show that the OCI E_s can be reconstructed accurately, with the relative differences within

1% from 360 nm to 900 nm. In the UV, the errors increase with wavelength, with the highest values of ~4% and ~7%, depending on the Sun zenith angle (high Sun zenith angle means low E_s and relatively large uncertainties). With such reconstructed E_s data, the HyperNav system is able to provide hyper-spectral R_{rs} by normalizing the measured hyper-spectral L_w against E_s , which has great significance for the calibration and validation of the PACE mission.

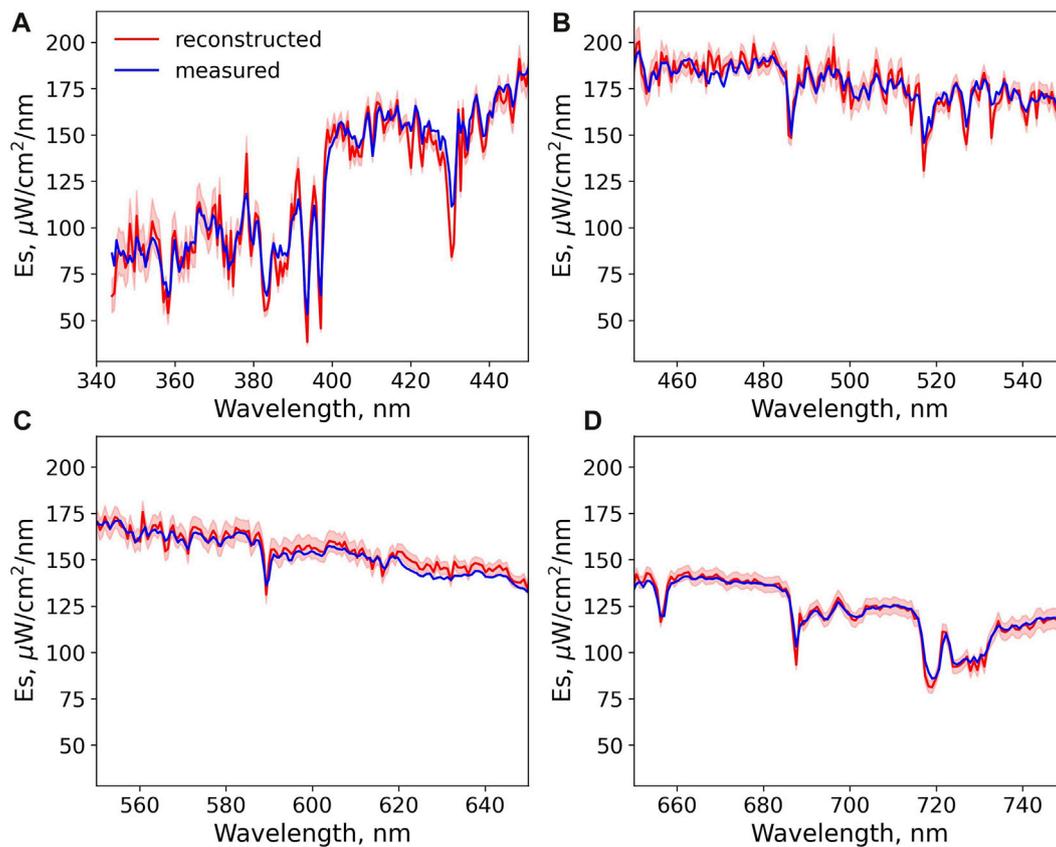


FIGURE 13
Comparisons between measured and reconstructed MOBY E_s on 27 May 2017 at (A) 340–450 nm, (B) 450–550 nm, (C) 550–650 nm, and (D) 650–750 nm. Shaded areas indicate the uncertainties of the reconstructed E_s .

7 Summary and conclusion

Spectral E_s at 0.5 nm resolution can be reconstructed accurately from E_s measurements in 4 spectral bands 10 nm-wide centered on 412, 489, 555, and 705 nm, such as those by an OCR SeaBird, Inc. planar irradiance sensor mounted on the HyperNav spectroradiometer/float system, using a multivariate linear model with constant coefficients or a GAM with coefficients dependent on SZA and AOT550. The models require as input, in addition to the 4 E_s measurements, the content of gaseous absorbers (vertically integrated content for ozone and water vapor and surface pressure for oxygen and other gases). In the absence of noise, both models yield biases less than 0.4% in magnitude and RMSEs less than 2.5%. The largest errors are obtained in regions of strong absorption bands. Errors are smaller in the UV with the GAM model, i.e., 0.2% instead of 0.6%. In the presence of typical noise on the input variables, biases and RMSEs are generally less than 1.5% in magnitude and 3.5%, respectively, except in the center of the oxygen A-band (−2.7% and 5.3%). The GAM model is more sensitive to noise, i.e., the gain in accuracy in the UV in the absence of noise is practically lost in the presence of noise. The complexity of the GAM model, therefore, may not be justified, unless the typical noise in the input variables can be reduced.

Using additional bands in the UV, i.e., at 325, 340, and 380 improves theoretical performance in the UV without noise, but marginally in practice because the E_s error is dominated by T_g uncertainties.

Evaluation of the multivariate linear model with constant coefficients against *in-situ* hyper-spectral E_s measurements at the MOBY site revealed E_s spectra reconstructed with biases less than 2% in magnitude and RMSE ranging from 1% to 2% in the visible to 5% in the UV, in agreement with theoretical uncertainties estimated using the Monte Carlo method. It is important, however, before doing any reconstruction, to check whether the multi-band E_s measurements are not biased (e.g., due to exposure, calibration, or processing errors), which can be accomplished by comparing the measurements to accurate radiative transfer calculations under favorable conditions. This revealed a significant bias in the HyperOCR E_s data acquired near the MOBY site.

The methodology, by providing a way to accurately reconstruct E_s at 0.5 nm resolution from E_s measurements at a few 10 nm-wide spectral bands, as demonstrated theoretically and experimentally, allows normalization of hyper-spectral L_w data acquired by HyperNav systems for validation activities of the PACE mission. The modeling does not replace hyper-spectral E_s measurements, such as those made by the MOBY system, but is adequate in many

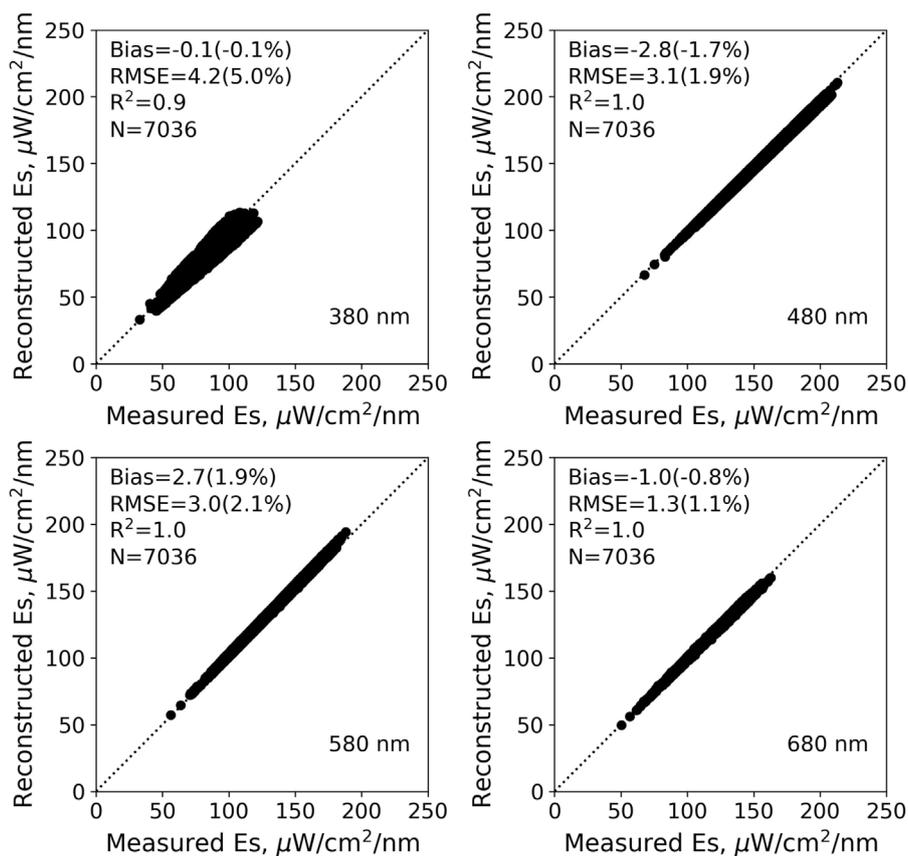


FIGURE 14 Comparisons between measured and reconstructed MOBY E_s at 380, 480, 580, and 680 nm.

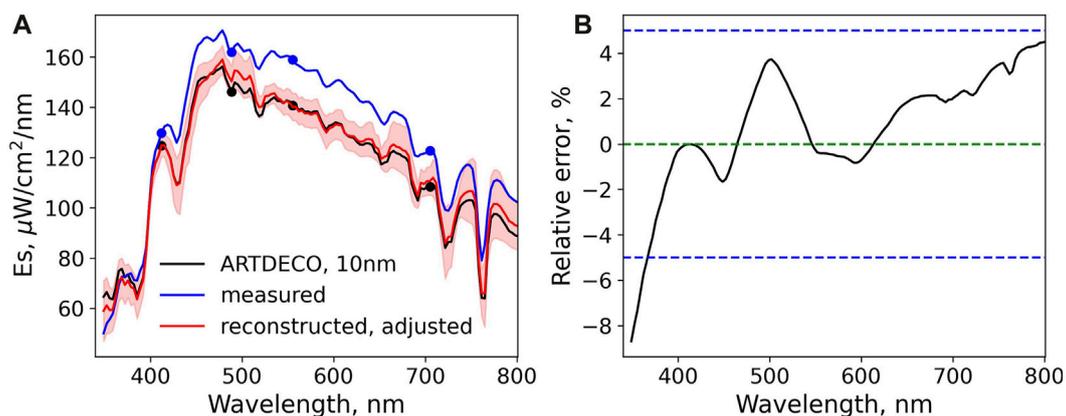


FIGURE 15 (A) Measured (blue solid) HyperOCR E_s on 16 June 2021. ATDECO simulations (black solid) show that the HyperOCR E_s is off and needs to be adjusted. The reconstructed E_s after adjustment (red solid) shows good agreement with the ARTDECO simulated values. Shaded areas indicate the uncertainties of the reconstructed E_s . (B) Percent relative error between the ARTDECO simulated and the reconstructed E_s after adjustment. Green and blue dashed lines correspond to 0% and 5% errors, respectively. Blue and black dots represent the E_s measured before and after adjustment.

aquatic optics applications, for which the acquisition of a relatively expensive hyper-spectral E_s sensor, costly to maintain and calibrate, may therefore not be necessary. The methodology is applicable to other sets of spectral bands, i.e., those of other

multi-band radiometers than the Seabird Inc. OCR used here, but accuracy of the reconstruction will depend on the bands position in the solar spectral range. Now, because the optical properties of clouds, like those of aerosols, and their effects on E_s vary

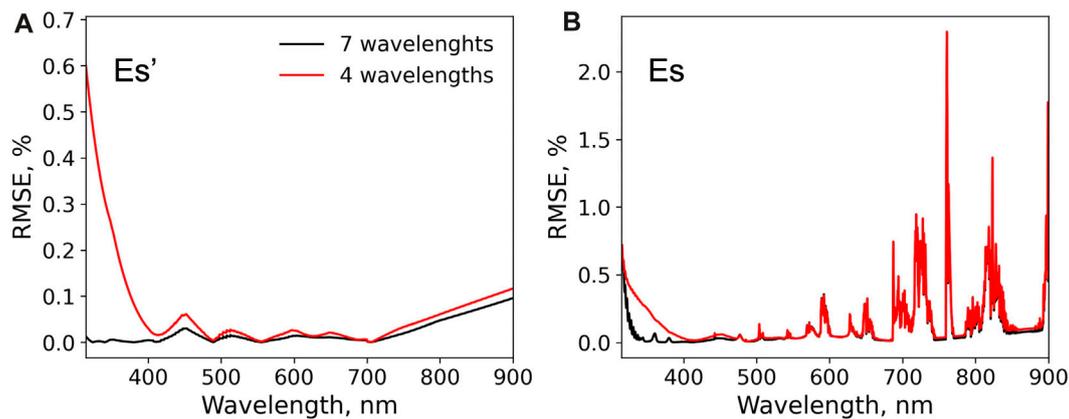


FIGURE 16
Percent RMSE of E_s' (A) and E_s (B) estimation using multivariate linear regression with three extra wavelengths in the UV, i.e., 325, 340, and 380 nm (black), in comparison to original four input wavelengths (red) as shown in Figure 6. The regression was performed using the calibration dataset without noise.

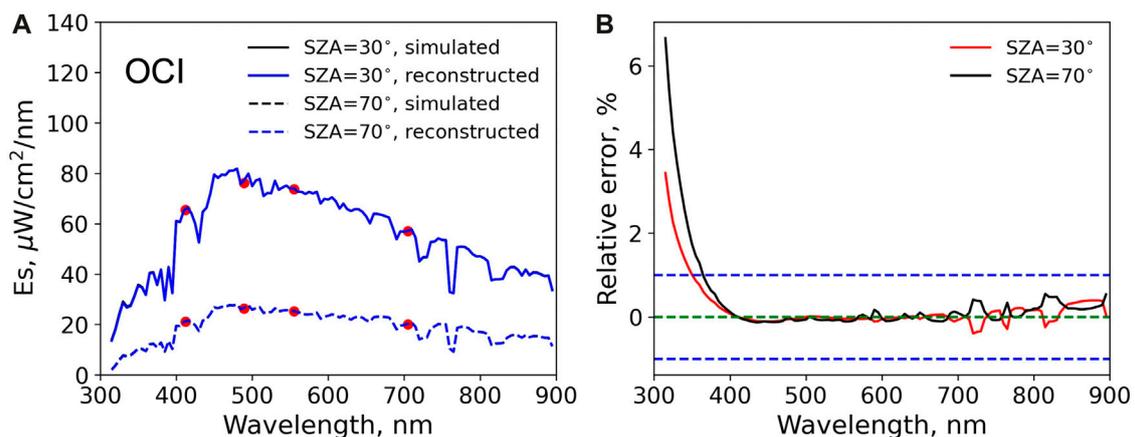


FIGURE 17
(A) The simulated (black) and reconstructed (blue) E_s at PACE OCI wavelengths. The simulations are for a clear day with $U_{o3} = 300$ Dobson, $U_{h2o} = 2$ g/cm², PS = 1,015 mb, Chl = 0.1 mg m⁻³, AOT550 = 0.1, maritime aerosol, relative humidity of 70%, SH = 2 km, and wind speed of 5 m s⁻¹. Two different SZA were used, i.e., 30° and 70°. The reconstruction was done using the simulated HyperNav values at the four wavelengths (red dots), i.e., 412, 489, 555, and 705 nm. (B) Percent relative error between the simulated and the reconstructed E_s . Green and blue dashed lines correspond to 0% and 1% errors, respectively. No noise has been added to the model input parameters.

relatively smoothly with wavelength in the UV to near infrared, the modeling can be extended to estimating spectral E_s in all sky conditions, although the coupling between absorption by gases and scattering by cloud droplets may complicate the treatment of T_g in some spectral regions. Such extension is envisioned in future work.

Data availability statement

The original contributions presented in the study are included in the article, further inquiries can be directed to the corresponding author. The code for reconstructing from E_s measurements at 412, 489, 555, and 705 nm is publicly available at https://github.com/jit079/Es_reconstruction.

Author contributions

JT: Conceptualization, Investigation, Methodology, Writing—original draft, Writing—review and editing. RF: Conceptualization, Investigation, Methodology, Supervision, Writing—review and editing. NH: Writing—review and editing. AB: Writing—review and editing. EB: Writing—review and editing. PC: Writing—review and editing. MM: Writing—review and editing. CO: Writing—review and editing.

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Conflict of interest

Author CO was employed by Sea-Bird Scientific.

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