



Corrigendum: [A Comparative Study of Adaptive Interlimb Coordination Mechanisms for Self-Organized Robot Locomotion]

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A corrigendum on

A Comparative Study of Adaptive Interlimb Coordination Mechanisms for Self-Organized Robot Locomotion

by Sun T, Xiong X, Dai Z, Owaki D and Manoonpong P (2021) A Comparative Study of Adaptive Interlimb Coordination Mechanisms for Self-Organized Robot Locomotion. *Front. Robot. AI* 8:638684. doi:10.3389/frobt.2021.638684

In the original article, there were errors.

In the published article, there was an error in affiliation 1. Instead of “College of Mechanical and Electrical Engineering, Institute of Bio-inspired Structure and Surface Engineering, Nanjing University of Aeronautics and Astronautics, Nanjing, China”, it should be “Institute of Bio-inspired Structure and Surface Engineering, College of Mechanical and Electrical Engineering, Nanjing University of Aeronautics and Astronautics, Nanjing, China”.

In the published article, there was an error in affiliation 2. Instead of “Embodied Artificial Intelligence and Neurobotics Lab, University of Southern Denmark Biorobotics, Mærsk Mc-Kinney Møller Institute, University of Southern Denmark, Odense, Denmark”, it should be “Embodied Artificial Intelligence and Neurobotics Laboratory, SDU Biorobotics, The Mærsk Mc-Kinney Møller Institute, University of Southern Denmark, Odense, Denmark”.

The authors apologize for this error and state that this does not change the scientific conclusions of the article in any way. The original article has been updated.

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