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*CORRESPONDENCE

Frontiers Production Office,

☐ production.office@frontiersin.org

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Erratum: Transient bio-inspired gliders with embodied humidity responsive actuators for environmental sensing

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Transient bio-inspired gliders with embodied humidity responsive actuators for environmental sensing

by Wiesemüller F, Meng Z, Hu Y, Farinha A, Govdeli Y, Nguyen PH, Nyström G and Kovač M (2022). Front. Robot. Al 9:1011793. doi: 10.3389/frobt.2022.1011793

An omission to the **Funding** section of the original article was made in error. The following sentence has been added: "Open access funding was provided by Empa - Swiss Federal Laboratories For Materials Science And Technology."

The original version of this article has been updated.