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A comparative study of cable fire dynamics: bench-scale experiments and numerical simulations with and without fire-retardant coating

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Cable fires are one of the primary causes of fire hazards in nuclear power plants (NPPs) and warehouse buildings. This paper presents a study on the experimental and numerical analysis of cable failure with and without fire-resistant coating. The experiments were conducted in two sets under two different average heat fluxes, ranging from 15 (13-15) kW/ m^2 to 20 (17-20) kW/ m^2 . A total of 10 experiments were analyzed, with five varying fire-resistant coating thicknesses from 0 to 0.8 mm for each heat flux value. For the power cable without coating, under an average heat flux value of 15 kW/ m^2 , the failure time was recorded as 1,897 s. Furthermore, the core and outer sheath temperatures at the time of failure, under the same heat flux, were recorded as 282.60°C and 353.90°C, respectively. For the power cable without coating under a heat flux value of 20 kW/ m^2 , the failure time was recorded as 991 s; the core and outer sheath temperatures at failure were recorded as 223.16°C and 310.16°C, respectively. Correlations for both heat fluxes were established, showing close agreement with experimental results—within a 2% variation. COMSOL Multiphysics software is used to perform the numerical simulations. The simulation results for the uncoated cable showed that under a heat flux value of 15 kW/ m^2 , the failure time, core temperature, and outer sheath temperature were 1898 s, 333.37°C, and 361.83°C, respectively. Under a heat flux value of 20 kW/ m^2 for a power cable without coating, the simulation results obtained for cable failure time, core temperature, and outer sheath temperature were found to be 990 s, 212.73°C, and 256.45°C, respectively. The absolute mean deviation for the outer sheath in numerical validation was 9.94%, while for the core, it was 14.19%. The simulation results show good agreement with the experimental results. These findings contribute to a better understanding of cable burning characteristics and failure times.

KEYWORDS

power cable, fire-retardant coating, heat flux, critical thermal stress, temperature gradient

1 Introduction

The power cable's burning characteristics are a critical parameter for fire hazard assessment. In the recent past, there have been some incidents in industrial and residential areas where cables have become a major concern because of their combustible nature. Fire is one of the major sources of energy in the form of heat, but it is also a significant safety concern (Keski-Rahkonen and Mangs, 2002). With the development of new technologies, the demand for electricity is continuously increasing, necessitating the use of power cables for its transmission. As the application increases, the chances of their failure also increase; sometimes, the failure may be in the form of a breakdown of the system, that is, when the cable stops functioning as required or works less efficiently. However, sometimes, due to fire, the temperature of the cable wire becomes so high such that it becomes a source of fire itself.

As cable insulation and sheathing are typically constructed of plastic, rubber, or other combustible materials, they are easily damaged under high-temperature circumstances (Lai, 2013). For example, the initial stage of the fire at Dalian's oil depot on 16 July 2010 caused damage to electricity supply cables and distribution rooms. Therefore, owing to the interruption of the low-voltage power supply, it was not possible to electrically shut off any of the oil tank emergency shut-off valves. The manual operation of the electric valve was slow and dangerous, which caused great difficulties in firefighting (Zhang et al., 2010; Han, 2012). Therefore, in the case of fire, some key cables connected to the firefighting and safety equipment became the weak point of the emergency system. Therefore, it is of great significance to improve the fire resistance of such key cables (James, 1998; Zhu, 2008).

Only a few studies have investigated the fundamental combustion in real cable fires. For example, Fernandez-Pello et al. (1991) studied the piloted ignition time and the flame spread rate of several commercial cables under various external radiation conditions and showed the similarity between the pyrolysis temperature of cable insulation and the ignition temperature. Tewarson and Khan (1989) tested the upward flame spread over 35 commercial electrical cables with a copper or aluminum core and found that the metal core acted as a heat sink, slowing down the flame spread.

The external heat flux is one of the most important parameters for ignition (piloted or spontaneous). To better understand the ignition criteria, most works in the literature used a constant external heat flux, as reviewed by Torero (2016). However, in most real fire scenarios, materials are ignited under a transient external heat flux rather than a constant heat flux. In pre-flashover fires, as the fire size and intensity increase, materials are more likely to be heated and eventually ignite due to the increasing heat flux. Because of its complex nature, very few studies have investigated the ignition behavior under transient heat flux (Vermesi et al., 2016; Vermesi et al., 2017; Lizhong et al., 2007; Belcher et al., 2015). Vermesi et al. (2016) and Vermesi et al. (2017) studied the piloted and spontaneous ignition processes of plastic and wood under the transient external heat flux (parabolic time-dependent curves) and revealed that the traditional ignition criteria for constant heat flux might become inappropriate. To the best of our knowledge, there is no fundamental study on the spontaneous ignition of real cables yet. Previous researchers have studied fire behavior and smoke characteristics in tunnels using both experimental and numerical methods. Siemon et al. (2019) analyzed the influence of cable tray arrangements on mass loss rate, heat release rate, and fire spread behaviors. Using FDS, Zhou et al. (2008) conducted a full-scale fire simulation in a T-shaped cable tunnel and summarized the change rules of smoke concentration, oxygen concentration, and longitudinal temperature. Kim et al. (2008) used FDS to simulate tunnel fire with forced, transient, and longitudinal ventilation flows. Oka et al. (2013) built a model to predict the peak temperature of the ceiling jet in the inclined tunnel. The effects of external heat flux and cable spacing on cable fire characteristics were also investigated. Martinka et al. (2019) investigated the fire risk of electrical cables by considering the influence of mutual spacing between the cables and the thermal conductivity of the material beneath them.

To reduce the flammability and suppression of fire on cable wire, various fire-retardant coatings have been studied by different researchers; for example, Courty and Garo (2017) performed experiments on the external heating of electric cables and investigated their auto-ignition in a furnace composed of a stainless steel cylinder that is heated using an electric coil. Ji et al. (2013) studied the failure time of PVC-insulated cable under an infrared radiation heating furnace based on a decrease in insulation resistance in both bare and coated power cables and concluded that as the thickness increases, failure time also increases. Saxena and Sharma (2002) performed experiments on three-and-a-half-core aluminum PVC-insulated cables, both bare and coated with fire-retardant paint (FRP), and concluded that as the thickness increases, the circuit failure time also increases. Various works have already been carried out in a similar manner.

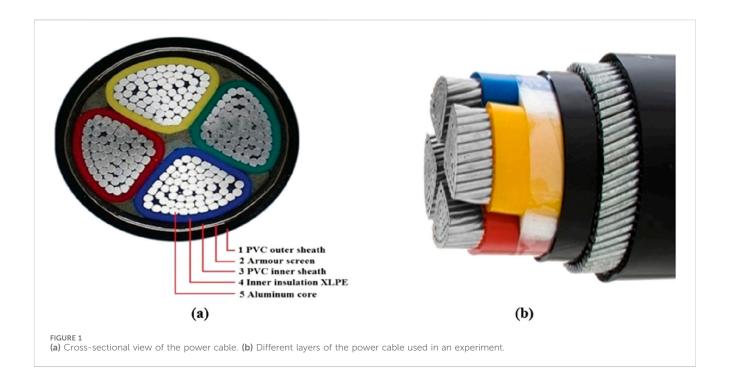
The present work focuses on the ignition of power cables subjected to radiative heat flux under continuous electric load conditions. As the outer sheath is the main combustible component of the cable, studying its pyrolysis characteristics is an important aspect. Experiments are carried out at two heat flux levels and with five different fire-resistant coating thicknesses for each heat flux value. The burning time of PVC-insulated power cables was recorded under different coating thicknesses, and the variations in failure time of power cables were analyzed. The results of this paper can be further used to enhance fire safety during the installation of power cables in power plants. Due to the burning of the cable, nearby cables stop functioning and catch fire, creating an extremely hazardous fire environment.

2 Experimental methodolgy

2.1 Power cable

In the present work, a 1.1-kV, 4-core, XLPE-insulated, armored, PVC-sheathed cable with an aluminum conductor is used, as shown in Figure 1. The outer diameter of the cable is 26.2 mm, and its current rating is 70 A.

A PVC-insulated XLPE (cross-linked polyethylene, which has a softening temperature of approximately 135°C–150°C, higher than that of PVC and PE) cable measuring 1.2 m in length, with bare ends (100 mm stripped from each end), is used, resulting in an actual experimental length of the specimen of 1,000 mm. Two holes are



drilled into the cable—one reaching the insulation and the other extending to the core of the cable. K-type thermocouples (highly accurate and precise) are inserted into these holes to measure the temperatures of the insulation and core of the cable. Additionally, two more thermocouples are used: one for measuring the surface temperature and the other for the flame temperature.

2.2 Fire-retardant paint preparation

FRP works as a shield for the outer sheath under extreme fire conditions. A single coat of paint can achieve a thickness of 90–100 microns and dries within 20–24 h after application on the cable. It also reduces flame spread, resulting in a lower temperature increase along the length of the cable. For preparing the FRP solution, the flame-retardant agent (10 g) and fire-retardant paint (10 mL) were mixed very well, and some epoxy thinner was added to reduce the setting time of FRP and increase the ease of coating on the cable.

After the FRP solution dried, the sample was tested on a physical property measurement system (PPMS). The average thermal conductivity and specific heat capacity of the FRP solution were 1.633 W/m-K and 1,690.581 J/Kg-K, respectively. The density of the FRP solution sample, with a mass of 0.00149 g and a volume of $1.195 \times 1 \times 0.98$ mm³, was 1,272.308 kg/m³. The coating thickness on the cable was measured using a CALTECH coating thickness gauge, which has a measurement range of 0–12000 μm and an accuracy of 1.5% or 2%.

2.3 Test set-up

The layout of the experimental set-up is shown in Figure 2. A step-up transformer and a variac, connected with copper wires, are

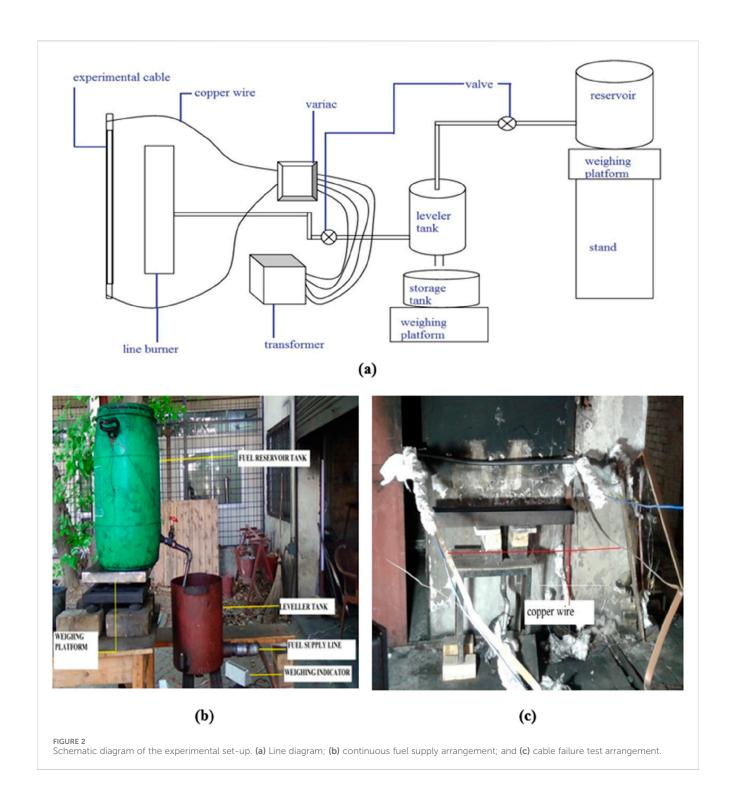
used to supply the rated current to the cable. In the case of cable fire, the term failure is defined based on two primary criteria: first, electrical failure, i.e., when the short circuit occurs; second, mechanical failure, i.e., cable failure, when the cable surface starts smoldering/igniting and flaming. The present work considered both failure modes, electrical and mechanical failure.

Different heat fluxes (15 kW/m² and 20 kW/m²) can be achieved by varying the distance between the burner and the cable. For a heat flux of 15 kW/ m^2 , a horizontal distance of 200 mm and a vertical distance of 100 mm are maintained, whereas for 20 kW/ m^2 , the burner and the test cable are maintained at a vertical distance of 100 mm and a horizontal distance of 10 mm.

The experiment is divided into three phases: the current phase, the pre-burning phase, and the burning phase. In the current phase, the current is supplied to the cable at its rated value and maintained for a duration of 20–25 min so that the temperature of the cable becomes steady. The cable temperature increases slowly, and after a certain time, it becomes steady.

The second phase comprises fuel ignition for the fire's cable failure test. The fuel is supplied from the fuel reservoir tank. The fuel level in the pan (dimensions: $1000 \times 150 \times 70 \text{ mm}^3$) was maintained at a constant height of 50 mm. Due to the burning of the fuel, there is a sudden increase in the cable surface temperature and the insulation temperature. However, the core temperature of the cable increases at a slightly slower rate than the surface temperature. A stopwatch was used to record the ignition time.

The last phase is the burning phase; in this phase, the cable starts to burn because of the temperature during the second phase. The cable itself becomes a source of ignition, which is considered one of the criteria for cable failure. Table 1 summaries the experiments with respect to coating thickness, average heat flux, and other fixed parameters.



3 Numerical methodology

3.1 Material and meshing geometry

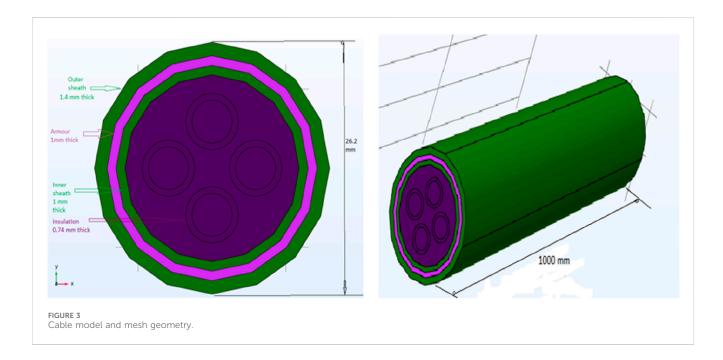
The geometry of the cable cross-section is very complex due to the number of individual components. Electric cables have a 3D symmetrical cylindrical geometry. In this work, the cable has four cores, an outer jacket diameter of 26.2 mm, an outer sheath thickness of 1.4 mm, and a total length of 1,000 mm. It also features a concentric cylindrical armor with a thickness of 1 mm and a

concentric cylindrical inner sheath, also 1-mm thick. The cylindrical conductors have a cross-sectional area of 16 mm², i.e., corresponding to a radius of 2.225 mm, and concentric cylindrical insulation has a thickness of 0.74 mm. Cable 3D model and mesh geometry representation is shown in Figure 3.

The outer and inner sheath material considered is PVC with 40% plasticizer, and the material used for the core is aluminum. Moreover, galvanized steel (BS 460B) and high-density polyethylene (HDPE) were utilized for the armor and internal insulation, respectively. For COMSOL simulation, certain cable properties

TABLE 1 Summary of the experiments.

Experiment	Coating thickness (mm)	Average heat flux (kW/ m²)	Other fixed parameter
1	0	15	Nominal diameter = 26.20 mm Nominal area = 25 mm ²
2	0.2 ± 0.1		PVC outer thickness = 1.4 mm
3	0.4 ± 0.1		PVC inner thickness = 0.3 mm Current = 204 A
4	0.6 ± 0.1		Voltage = 0.18 V
5	0.8 ± 0.1		
6	0	20	
7	0.2 ± 0.1		
8	0.4 ± 0.1		
9	0.6 ± 0.1		
10	0.8 ± 0.1		



were referenced directly from the COMSOL software library to ensure accurate modeling. To maintain consistency between the simulation and experimental conditions, the materials used in the cable fire simulation were selected to match the specifications of those used in the physical experiments. This alignment was essential to ensure that the simulated behavior closely mirrored the real-world performance observed during testing. The physical properties of the FRP solution—thermal conductivity, density, and specific heat capacity—were determined through experimental testing and subsequently used in the COMSOL simulation. The average thermal conductivity and specific heat capacity were found to be $1.6332~\rm W/m\cdot K$ and $1.690.5815~\rm J/kg\cdot K$, respectively. The density, calculated based on a sample mass of $0.00149~\rm g$ and a volume of $1.195~\rm x~1~x~0.98~mm^3$, was determined to be $1.272.3080~\rm kg/m^3$.

Meshing involves dividing a given geometric structure into numerous smaller components known as cells. In COMSOL, the meshing strategy involved an unstructured mesh that allowed for greater flexibility in capturing the complexities of the geometry, with local refinement in regions of high-gradient variables to enhance accuracy. For this simulation, extremely fine free triangular cells were used to mesh the power cable geometry. The total number of mesh elements used in the cable model, consisting of various sizes and tetrahedral geometries, was approximately 1,063,432. This number varied depending on the thickness of the fire-retardant paint solution coating.

Using a large number of cells (i.e., a refined mesh) generally results in simulation outcomes that closely approximate real-world behavior. However, a significant increase in the number of cells also leads to longer computation times. Typically, extremely fine meshing is applied to small or critical geometry sections, while coarser meshing is used for larger or less critical areas to optimize performance. A mesh independence study was not conducted in this

work as a refined mesh was consistently used throughout the simulation.

3.2 Governing equations and boundary conditions

In COMSOL Multiphysics, governing equations depend on the specific physics module being utilized as they are formulated to model a wide array of physical phenomena. Some of the common governing equations are as follows: (A) heat transfer: the governing equation is the heat conduction equation, described by Fourier's law; (B) fluid dynamics: the Navier-Stokes equations govern fluid motion, describing how the velocity field of a fluid changes due to forces acting on it; (C) electrical currents: the governing equation for electrical currents in a conductive medium is described by Ohm's law and the continuity equation; (D) structural mechanics: for solid mechanics, the governing equations are based on the equilibrium of forces, often expressed using the linear elasticity equations; and (E) chemical reaction engineering: the mass transport equations and reaction kinetics are used to model species transport and reactions, typically involving the diffusion equation. These equations are coupled in multiphysics scenarios, allowing COMSOL to simulate complex interactions between different physical phenomena.

Boundary conditions are assumed to accurately reflect the physical environment of the system; Dirichlet conditions were implemented to specify fixed temperatures at the inlets, and Neumann conditions were implemented for heat flux at the boundaries to simulate heat transfer effectively. A time-dependent solver was assumed with appropriate tolerance settings to ensure convergence, enabling us to model transient heat transfer phenomena accurately and extract meaningful results for further analysis.

In this numerical simulation, the "Heat Transfer in Solids" and "Electric Currents" physics interfaces were applied to the cable model. Based on the experimental set-up, a rated current of 210 A was supplied to the cable for 20-25 min to allow the wire temperature to reach a steady state. Although the current was continuously supplied, additional heat was applied to simulate fire conditions, and the thermal behavior of the cable was studied accordingly. During the experiments, heat fluxes of 15 kW/m² and 20 kW/m² were applied to the cables—with and without fireretardant paint coatings, respectively. In the simulation, one end of the cable was set to ground (0 V) and the other to a terminal, allowing the voltage potential distribution along the cable to be observed. To replicate the experimental conditions, a steady-state current supply was applied throughout the simulation, simulating continuous operation until the cable's complete thermal degradation.

4 Result and Discussion

4.1 Experimental results

The experimental set-up is arranged as described in Section 2.3, and the cable is attached to the copper bus bar. A series of 10 experiments were performed under heat fluxes of 15 kW/ m^2

and 20 kW/ m^2 to investigate the self-ignition time of PVC-insulated cables, with and without the coating of fire-retardant paint. A total of five ranges of coating thickness are tested. To register the temperature profile of the cable, one thermocouple is mounted on the cable surface, and two other holes are made such that one touches the insulation. The other touches the core of the cable. These three thermocouples measure the cable's surface, insulation, and core temperature. The ignition time of the cable wire is noted down; the data acquisition system records the temperature of the different layers, and its variation with time is also plotted. The failure time, core temperature, and insulation temperature of the cable corresponding to the failure time is given below in Table 2.

It can be observed from the table that for a given value of heat flux, with an increase in the thickness of the coating, the ignition time is continuously increasing, which has also been demonstrated by Ji et al. (2013). It can also be observed from the temperature profile, as given below, that there is a sudden increase in the temperature profile. An increase in the ignition time of the cable is because of the flame-retardant property of the paint. It suppresses the intense heat flux directly subjected to the cable and has a flame-retardant property that restricts the fire from spreading over the surface of the cable.

According to Equations 1, 2, the cable failure time is delayed as a function of coating thickness, providing an empirical relationship between failure time and dry coating thickness. It was found that the time to failure is well correlated with the cable's thermal mass per unit length.

The given correlation is developed using the least square method, a mathematical approach used to find the best-fitting curve through a set of obtained data points. Regression analysis widely uses this method to develop correlations between two or more variables. Using measured experimental values for the cable failure time, regression analysis is used to find the best curve for the obtained experimental data. In the present correlation, F_t represents the failure time as a dependent variable, whereas h_f and C_t are independent variables, i.e., F_t is the function of heat flux and coating thickness. In this equation, the failure time of cable, F_t , is in seconds, and coating thicknesses C_t is in mm. When comparing the correlation with the experimental results shown in Figure 4 cable response to real fire, the correlation was found to be within a 2% variation of the experimental data and provided a conservative estimate of the time to failure.

$$F_{t,at15kW} = 1.000064 * h_f^{2.889108} C_t^{-0.13952},$$
 (1)

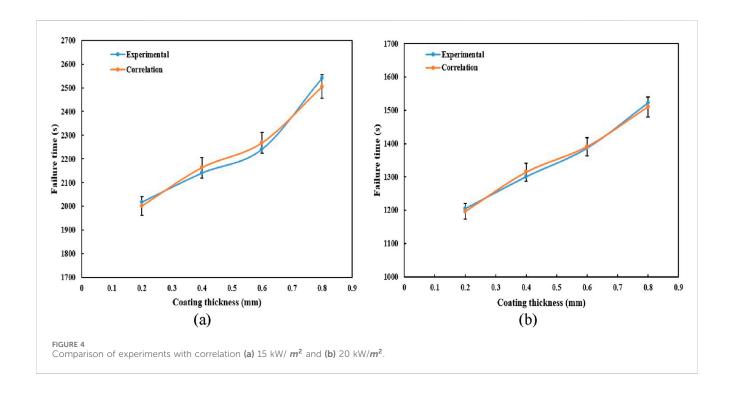
$$F_{t,at20kW} = 1.000024 * h_f^{2.44806} C_t^{-0.01986}$$
 (2)

It can be observed from Figure 5 that the ignition time of the cable increases almost linearly with the coating thickness, and it is higher for the heat flux of 15 kW/ m^2 than for 20 kW/ m^2 , which is because of the thermal impact of the heat flux.

Thus, it can be observed that ignition time is highly dependent on the core and insulation temperatures of the cable. It almost remains constant within the range of $\pm 20^{\circ}$ C of a mean temperature for a given value of heat flux, irrespective of the coating thickness. As the value of heat flux increases, the ignition temperature of the heating cable decreases because of the thermal impact of the heat flux, as mentioned earlier.

TABLE 2 Various experimental results.

Coating thickness (mm)	Failure time after the ignition of fuel (s)	Heat flux kW/ m ²	Core temperature corresponding to the failure time (°C)	Insulation temperature corresponding to the failure time (°C)
0.0	1,897	12.50	282.60	353.90
0.20 ± 1	2,017	12.85	270.89	321.54
0.40 ± 1	2,140	13.65	254.56	299.02
0.60 ± 1	2,241	14.15	268.54	330.65
0.80 ± 1	2,542	14.85	333.84	289.39
0.0	991	18.50	223.16	310.16
0.20 ± 1	1,204	17.85	192.62	253.90
0.40 ± 1	1,300	18.65	230.43	259.94
0.60 ± 1	1,386	19.15	193.99	262.91
0.80 ± 1	1,522	19.85	208.30	272.11



4.2 Numerical investigation for heat flux without coating

In this case, the cable has no fire-retardant coating attached to it. In the experimental set-up, a gap is maintained between the cable and heat flux sensor, so the measured heat flux value is less than $15 \text{ kW}/\text{m}^2$. This investigation considers the average heat flux value for different stages.

Four different stages of timing are considered in this numerical investigation, corresponding to those in the experimental study. The first stage is the time required to reach a steady-state condition. The second stage is the ignition

time of the wire, i.e., the failure time after the ignition of the fuel. Cable failure occurs due to a short circuit caused by insulation damage, which results from exposure to external fire from the fuel-line burner in the experiment. The third stage begins after the short circuit, when internal fire develops within the cable; this leads to rapid temperature increase across the different cable layers until the cable is completely burned—referred to as the complete burning stage. The final stage is the cooling phase, during which the cable temperature gradually decreases after combustion.

The average heat flux has been taken as 8 kW/ m^2 for ignition time (study-2) and 10.5 kW/ m^2 for complete burning

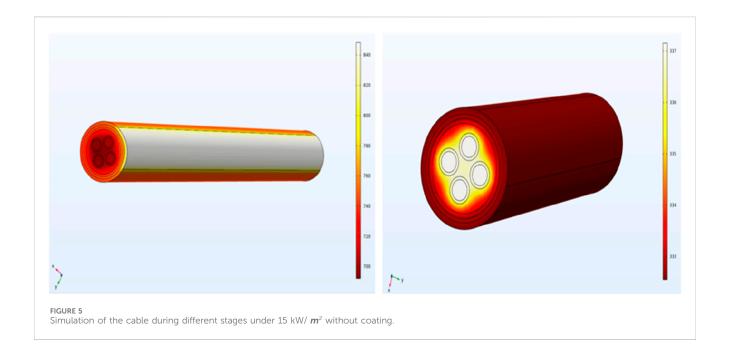


TABLE 3 Timing of different stages of simulation-1 in seconds.

Initial current time (s)	Cable failure time (s)		Cable burning time (s)		Cable cooling time (s)	
	Total time (s)	Failure time (s)	Total time (s)	Burning time (s)	Total time (s)	Cooling time (s)
1,470	3,366	(1896)	3,798	(432)	7,296	(3,498)

time (study-3). Table 3 represents the various stages of simulation, i.e., initial current time, cable failure time, cable burning time, and cable cooling time. Time in the first bracket represents the failure time of the cable after the initial current time. The second bracket represents the time taken by the cable to catch fire after failure. The third bracket represents the cooling time of the cable.

Heat flux is applied to only one-fourth part of the cable's outer sheath according to the experiment set-up because, during the experiment, the fire burner is placed below the cable at some distance; thus, the cable is affected by one-fourth part of the cable, and due to this distance, the heat flux value will be less than 15 kW/ m^2 and 20 kW/ m^2 for different stages of the numerical investigation.

In the first stage, a constant rated current of 210 A is supplied to the cable for 1,470 s, i.e., until a steady-state condition is reached. Then, in the second stage, a constant rated current of 210 A is supplied, and simultaneously, an average heat flux is also applied to the cable model for 1896 s; due to the high current supply and continuous heat flux, there is a short circuit in the cable, i.e., ignition of the cable. Due to this short circuit, there is a sudden increase in the temperature of the cable model. This stage is referred to as study-3 of the cable model, which runs for a short time (432 s), i.e., complete cable burning. After these three stages, the final stage of the cable, i.e., the cooling stage, begins; during this stage, initially, there is a fast rate of cooling of the cable, but over time, the rate of cooling decreases, and the time taken to

achieve the initial stage temperature of the cable is almost 3,498 s. In the cooling process of the cable, only the convection cooling effect is considered; the radiation effect is neglected.

The simulated temperature profiles of different layers of cable from the initial to the final stage are provided in Section 4.3.

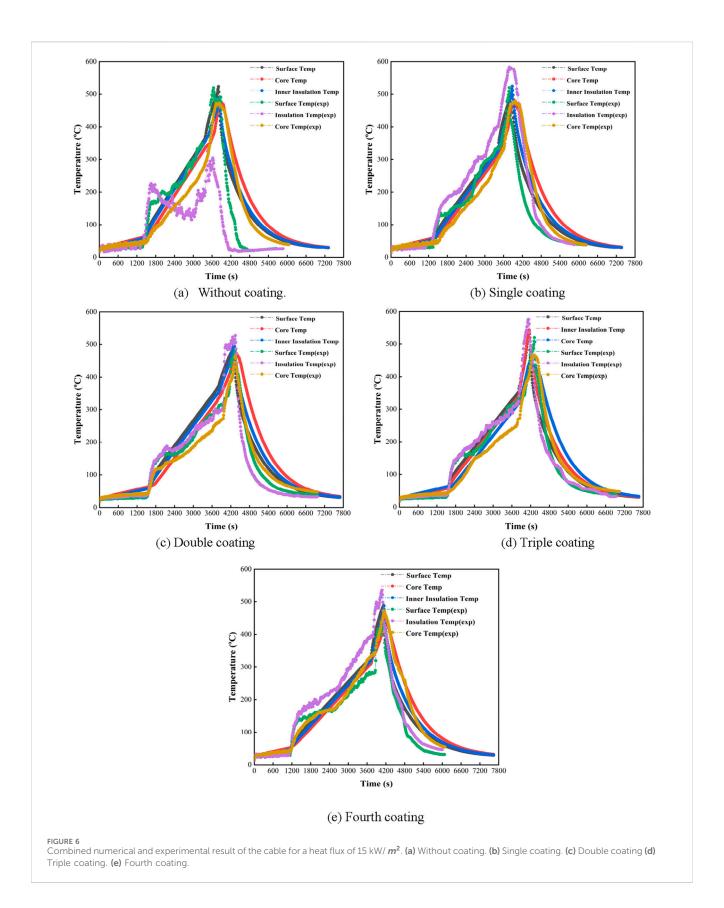
4.3 Comparison of experimental and numerical results

4.3.1 Results validation for a heat flux of 15 kW/m²

Figures 6a-e show the time-temperature curve of the cable surfaces at different depths. It can be observed from the figure that the peak temperatures are similar during heating at certain time. However, inner insulation temperature is slightly higher than core and outer surface temperatures.

4.3.2 Validation of results for a heat flux of 20 kW/m²

Figure 7a-e show the combined numerical and experimental result of cable for heat flux. As mentioned earlier, the applied heat flux was transient, which increased with time close to a parabolic function. Once heated, the outer PVC sheath swelled and shrank in multiple stages. Before the ignition, the swelling behavior was found to follow the same trends as the mass loss rate. Table 4 summaries the numerical results concerning the coating thickness, failure time



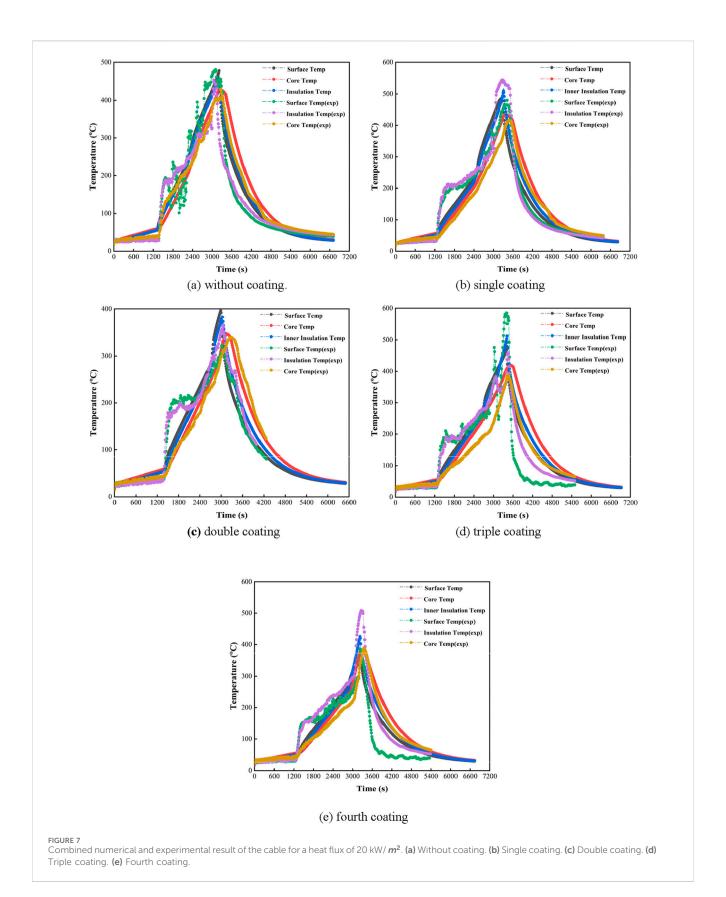


TABLE 4 Various numerical results.

Coating thickness (mm)	Failure time after the ignition of the fuel (s)	Heat flux kW/ m ²	Core temperature corresponding to the failure time (°C)	Insulation temperature corresponding to the failure time (°C)	
0.0	1898	15	333.37	361.83	
0.20 ± 1	2016	15	310.08	336.94	
0.40 ± 1	2,142	15	311.80	358.66	
0.60 ± 1	2,244	15	306.79	352.35	
0.80 ± 1	2,544	15	310.87	329.97	
0.0	990	20	212.73	256.45	
0.20 ± 1	1,206	20	214.92	244.19	
0.40 ± 1	1,302	20	248.25	282.34	
0.60 ± 1	1,386	20	246.24	281.50	
0.80 ± 1	1,524	20	240.23	232.33	

TABLE 5 TRR value for experimental and numerical data.

Average HF (kW/ m²	Coating thickness (mm)	Experimental			Numerical		
		T _{bare} (°C)	T _{paint} (°C)	TRR	T _{bare} (°C)	T _{paint} (°C)	TRR
15	0.20 ± 1	353.90	321.54	0.0914	361.83	336.94	0.0687
15	0.40 ± 1	353.90	299.02	0.1550	361.83	358.66	0.0087
15	0.60 ± 1	353.90	330.65	0.0656	361.83	352.35	0.0262
15	0.80 ± 1	353.90	289.39	0.1822	361.83	329.97	0.0880
20	0.20 ± 1	310.16	253.90	0.1813	256.45	244.19	0.0478
20	0.40 ± 1	310.16	259.94	0.1619	256.45	282.34	0.1009
20	0.60 ± 1	310.16	262.91	0.1523	256.45	281.50	0.0976
20	0.80 ± 1	310.16	272.11	0.1226	256.45	232.33	0.0940

after fuel ignition, heat flux, and core and insulation temperatures corresponding to the failure time.

Absolute percentage deviation is calculated for the core of the cable for both cases of the heat flux, i.e. $15 \text{ kW}/m^2$ and $20 \text{ kW}/m^2$, based on the failure time after the application of heat flux in each case. The absolute mean deviation for the core numerical validation is 14.19%. Absolute percentage deviation is calculated for the outer sheath of the cable for both cases of heat flux (i.e., $15 \text{ kW}/m^2$ and $20 \text{ kW}/m^2$), based on the failure time after the application of heat flux in each case. The absolute mean deviation for outer sheath numerical validation is 9.94%.

4.4 Temperature reduction ratio

The temperature reduction ratio (TRR) is a ratio of the difference between the steady-state temperature of the cable surface without coating and the paint-coated outer cable surface

temperature divided by the steady-state temperature of the cable surface without coating, i.e., the bare temperature of the cable at the failure time of the cable.

$$TRR = \frac{T_{bare} - T_{paint}}{T_{bare}}.$$

From Table 5, one can notice that the critical thickness corresponding to the heat flux of 15 kW/ m^2 (experimental and numerical) is 0.8–1.0 mm because the maximum TRRs are 0.1822 and 0.0880, respectively.

Similarly, for a heat flux of $20 \text{ kW}/m^2$, the critical thickness is different for the experimental and numerical cases; for the experimental case, the maximum value of TRR is 0.1813 for 0.2–0.4 mm of coating thickness, and for the numerical case, the maximum value of TRR is 0.1009 for 0.4–0.6 mm of coating thickness. The thickness of the FRP solution corresponding to the maximum TRR is considered the critical thickness because, for the maximum TRR, temperature reduction is maximum between

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without-paint and with-paint cable surfaces, i.e., maximum heat transfer between the cable surface and the environment.

5 Conclusion

In this paper, a comprehensive analysis was conducted on a series of 10 experiments, each designed to explore the impact of fire-resistant coating thickness on the performance of power cables under varying heat flux conditions. This is a critical consideration in industries where fire safety is paramount, such as in power cable manufacturing, electrical infrastructure, and fire safety research. The power cable's core temperature and outer sheath temperature were measured at the time of cable failure. Therefore, the following key points were noted after the successful completion of this study:

- The ignition time of the cable is greater for coated cables than for bare wires and increases almost linearly with respect to coating thickness.
- The ignition time of the cable is highly dependent on the core and insulation temperatures of the wire for a given heat flux. It remains relatively constant within a range of ±20°C. The ignition time has a higher value at lower heat flux levels and continuously decreases as the heat flux increases due to the thermal impact of heat.
- Fire-retardant paint also changes the chemical properties of the cable. Previously, after the ignition of the cable, the insulation would melt and drip off; however, after the application of fire-retardant paint, its properties change, becoming hard instead of melting. As a result, it either adheres to the cable in the form of solid particles or falls off in layers, making it less hazardous than bare wire.
- Correlation is fitted to a narrow range for the two experimental heat flux values, i.e., 15 kW/ m² and 20 kW/ m², and developed for the cable failure time corresponding to the above-mentioned heat flux values. The narrow range is due to the unavailability of experimental data for a wide range of heat flux values. Therefore, this can be observed as the future scope of the present work to validate the present correlation for a wide range of heat flux data when experiments are carried out for similar conditions.

The results can be useful for professionals working with power cables in real-world applications; understanding the relationship between coating thickness and fire resistance can help inform material specification decisions for cable installations in high-risk areas. Moreover, the study provides benchmark data that can support future research on fire-resistant materials, guiding the development of more effective protective coatings.

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Data availability statement

The raw data supporting the conclusions of this article will be made available by the authors, without undue reservation.

Author contributions

RM: Conceptualization, Methodology, Project administration, Writing – original draft. MT: Writing – original draft, Writing – review and editing. AD: Data curation, Software, Validation, Writing – review and editing. AS: Conceptualization, Data curation, Formal Analysis, Investigation, Writing – review and editing. AG: Methodology, Project administration, Supervision, Visualization, Writing – original draft. MM: Data curation, Formal Analysis, Software, Validation, Writing – review and editing. RK: Funding acquisition, Project administration, Resources, Supervision, Writing – review and editing. PS: Conceptualization, Methodology, Supervision, Validation, Writing – review and editing.

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Conflict of interest

Author AD was employed by Alstom Transport India Limited. The remaining authors declare that the research was conducted in the absence of any commercial or financial relationships that could be construed as a potential conflict of interest.

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